

Information Requirements for Mechanism Design*

Richard P. McLean
Rutgers University

Andrew Postlewaite
University of Pennsylvania

June, 2023

Abstract

Standard mechanism design begins with a statement of the problem, including knowledge on the designer's part about the distribution of the characteristics (preferences and information) of the participants who are to engage with the mechanism. There is a large literature on *robust* mechanism design, much of which aims to reduce the assumed information the designer has about the participants. In this paper we provide an auction mechanism that reduces the assumed information assumed of the seller, and, in addition, relaxes substantially the assumed information of the participants. In particular, the mechanism performs well when there are many buyers, even though there is no prior distribution over the accuracy of buyers' information on the part of the designer or the participants.

Keywords: Robustness, Optimal auctions, Incentive Compatibility, Mechanism Design, Interdependent Values, Informational Size, Common Knowledge

JEL Classifications: C70, D44, D60, D82

*Previous versions of this paper circulated under the title "A very robust auction mechanism." We thank the National Science Foundation for financial support. We thank Dirk Bergemann, Benjamin Brooks, George Mailath, Steve Matthews, Stephen Morris, Antonio Penta, Jusso Toikka, Rakesh Vohra, and the audience at several presentations for helpful conversations and suggestions, and Daniel Hauser for research assistance.

1 Introduction

There is a large literature on robust implementation that addresses a concern raised in Wilson (1987) concerning mechanisms designed to implement desired social outcomes in the presence of asymmetric information. Typically, the construction of a proposed optimal mechanism relies on the mechanism designer having precise knowledge of the probability distribution over the agents' types. For many problems, this seems implausible, and has prompted researchers to search for mechanisms that are "robust" to the precise knowledge of the probability distribution.¹ The robust implementation literature has made substantial strides toward understanding the degree to which the assumptions regarding the mechanism designer's information can be significantly relaxed and the characteristics of robust mechanisms.

Most of the work on robust implementation focuses on the mechanism designer's information and says little or nothing about the information of the agents who will participate in the mechanism. This is not a problem for auctions in which buyers' know their own values: second price auctions are natural candidates for selling an object. Buyers have a dominant strategy to bid their value if the auction is one with private values. While there are many auction problems for which this is the case, there are important problems for which it fails. Consider an auction for drilling rights on a particular tract. One bidder for the rights may have a very precise estimate of the amount of oil in the tract or the depth of the reservoir while another bidder may have a substantially less precise estimate. In essence, agents may have some relevant information about the tract to be auctioned that other bidders do not have. Hence, we have left the realm of private values problems: my value depends on other agents' information as well as my own. It is known that in the interdependent value case (that is, when an agent may have both information of interest to other bidders and information of interest to her alone), second price auctions may not perform well.²

Of particular interest to us is the fact that bidding one's value is *not* a dominant strategy in a second-price auction with interdependent values. (Indeed,

¹See Bergemann and Morris (2012) and Borgeers (2015), Chapter 10 for discussions of robust mechanism design.

²Jackson (2009) presents a simple example illustrating the problem with second price auctions when there is a mix of private and non-private information. In the example, the second price auction does not have either a symmetric equilibrium or an equilibrium in undominated strategies. The example shows that equilibrium exists only in the extremes of pure private and pure common values; existence in the private value model is not robust to a slight perturbation.

it is often the case that a bidder doesn't *know* her value, as it can depend on other bidders' information.) Much of the robust implementation literature assumes that the mechanism designer sets out the rules of the mechanism, following which the participating agents typically play a Bayes Nash equilibrium of the game induced by the mechanism. When an agent does not have a dominant strategy, her bidding strategy is a best response to the probability distribution over other bidders' strategies.

Wilson's critique of the mechanism designer's informational requirements leads one to also question the plausibility of participants' informational requirements. This is particularly a problem when there are many participants who may not even know how many other participants are present. Our aim in this paper is to demonstrate a two-stage auction mechanism with the property that a participant does not necessarily have a probability distribution over other participants' types and may only have a rough idea of the number of participants.

The mechanism we construct assumes there are multiple payoff relevant states, and participants get noisy signals correlated with the state. There are bounds on the accuracies of the signals, but agents do not have beliefs about other agents' signal accuracies beyond these bounds. The bounds on signal accuracies assure that as the number of agents increases, they will become informationally small in the sense of McLean and Postlewaite (2002, 2004).³ When agents are informationally small, their expected gain from misreporting their information is small, but often positive. It is easy to construct simple interdependent auction problems in which agents are informationally small, yet it is a dominant strategy for agents to misreport their types.⁴ In our various papers in which informational smallness plays a role⁵, small rewards are constructed to induce truthful announcement. The constructed reward for an agent is "personalized," that is, tailored to the information structures of both that agent and other agents. The main contribution of this paper is a mechanism that does not rely on such personalized rewards, yet gives the seller almost all the surplus when there are many agents.

A second contribution of this paper is the solution concept, or rather, the *absence* of a solution concept. Much of the literature in mechanism design, including the literature on robust implementation, employs a familiar solution concept (e.g., Bayes Nash equilibrium or ex post equilibrium) to describe the

³Roughly, an agent is informationally small if her information has a small expected effect on the posterior distribution on the states.

⁴See McLean and Postlewaite (2004) for such an auction example.

⁵In addition to the two papers mentioned above, this is the case for McLean and Postlewaite (2003, 2005, 2009, 2015).

outcome of the participants' game induced by the mechanism. We deviate from this and focus not on what the particular outcome of the game will be, but rather on what will *not* be the outcome. There is the difficulty mentioned above with, for example, Bayes Nash equilibrium: it requires that an agent have probabilistic beliefs about other agents' behavior. An agent may have far less information than a probability distribution over other agents' behavior, yet enough to know that some bids are dominated. We ask only that agents do not make dominated bids.

1.1 Literature review

McLean and Postlewaite (2004) (hereafter MP2004) analyzed an interdependent value model similar to the model in this paper. That paper focused on the role of "informational size" introduced in McLean and Postlewaite (2002). A given player's informational size in an asymmetric information problem is, roughly, the degree to which that player's information can affect, in expectation, the probability distribution over states of nature when other players truthfully reveal their private information. MP2004 shows that when each buyer's informational size is small, a seller can use a modified second price auction that generates nearly the same revenue as would be the case if the common value part of players' information were public. McLean and Postlewaite (2017) (hereafter MP2017) shows how one can construct two-stage mechanisms for this kind of interdependent problem that extract the common value part of private information in the first stage, transforming the problem in the second stage into a private value problem. The models in these papers follow the standard mechanism design approach in which there is a prior that is common knowledge among the mechanism designer and the participants in the problem. Bayes equilibrium is the solution concept in these papers.

A shortcoming of these papers is, as discussed in the introduction above, that they are not "detail free" in the sense of Wilson (1987). At the center of most of the models based on informational size are rewards to a given agent that depend on the distribution of other agents' types, conditional on the given agent's type. A mechanism designer thus needs to know the distribution of agents' types to construct the mechanism. The mechanism in the current paper does *not* need to know that distribution, and indeed, does not need to know even the exact number of participating agents.

The mechanism in this paper is a two stage mechanism somewhat similar to that in MP2017, with the second stage being a second price auction. The

current paper differs in a fundamental way from that paper. There is no assumed probability distribution over agents’ types, and consequently, Bayes equilibrium cannot be the solution concept. Rather, we assume that potential buyers do not make dominated bids in the second stage auction. A buyer in the second stage will not have a well-defined probability distribution over states, hence she will not be able to compute her expected value for the object to be sold. However, she *will* be able to put upper and lower bounds on what the expected value would be if she knew other buyers’ noisy signals about the state and the accuracies of those signals. We restrict buyers to bid no lower than the minimum possible expected value over all possible realizations of the signals. While a buyer in the second stage will be able to put tight bounds on the expected value when there are many buyers, we want to emphasize that the second stage auction remains one of interdependent values. We discuss this further in the last section.

Du (2018) presents a mechanism to sell a common value object that maximizes the revenue guarantee when there is one buyer and shows that the revenue guarantee of that mechanism converges to full surplus as the number of buyers tends to infinity. Du assumes that the prior distribution of the common value is known. His mechanism, however, guarantees good revenue for every equilibrium, while as we discuss in the last section, our result focuses on “truthful revelation” outcomes.⁶ Brooks and Du, *Econometrica* (2021) construct an auction mechanism for a common value problem that focusses on maxmin performance across all information structures. When the number of bidders is large, the profit guarantee is approximately the entire surplus. This takes care of the multiplicity problem.

These papers provide mechanisms for important auction problems that address the Wilson critique: the mechanism designer needs to know very little about the agents who will participate in the mechanism. While the designer’s informational requirements are minimal, the participants’ informational requirements often remain substantial. It is assumed that the participants will play a Bayes Nash equilibrium, which typically requires the participants to have substantial information about other agents. Our mechanism requires participants to know bounds on the accuracies of other agents’ signals, but little more. In particular, agents are not assumed to have well-defined probabilistic beliefs about others. A negative aspect about our mechanism relative to these papers is that their results hold for all equilibria, while our result only guarantees the existence of at least one outcome with the desirable properties.

Wolitzky (2016) studies mechanism design and the possibility of weakening

⁶See also a related paper by Bergemann, Brooks and Morris (2017).

assumptions of agents' beliefs. Toward this end, he assumes that agents are maximin expected utility maximizers a la Gilboa and Schmeidler (1989).⁷ Our assumption about what agents know is substantially weaker, but Wolitzky's results hold for a fixed (possibly small) number of agents while our result holds for large numbers of agents.

2 The model

Consider an auction model with n players and a single indivisible object. Player i 's valuation for the object is the sum of a common value component and an idiosyncratic private value component. The private value component of player i is denoted c_i and we assume that c_1, \dots, c_n are realizations of i.i.d. random variables taking values in $[0, 1]$. The distribution function F is assumed satisfy $F(0) = 0$ and $F(1) = 1$ and is differentiable and strictly increasing on $[0, 1]$. The common value component depends on the realization of one of two equally likely states of nature a and b . In particular, player i 's valuation for the object is given by $c_i + v(a)$ in state a and $c_i + v(b)$ in state b where we assume that $v(a) < v(b)$. Players observe the state only after the object has been allocated. However, each player receives a signal $t_i \in \{\alpha, \beta\}$ correlated with the state. The players' signals are independent conditional on the state and i receives signal $t_i = \alpha$ (signal $t_i = \beta$) conditional on state a (state b) with probability $\lambda_i > \frac{1}{2}$. For each $t = (t_1, \dots, t_n) \in \{\alpha, \beta\}^n$ and each i , let

$$f_\alpha^n(t_{-i}) := |\{j : t_j = \alpha \text{ and } j \neq i\}|$$

with a similar definition for $f_\beta^n(t_{-i})$.

The critical feature of this model is the assumption that buyer i does not know the accuracy parameters of the other buyers nor does he know his own accuracy parameter λ_i . Players do however know the lower and upper bounds for these accuracies, i.e., buyers know the values of the numbers x and y satisfying

$$\frac{1}{2} < x \leq \lambda_i \leq y < 1$$

for each i . We denote the set of vectors of accuracies $\Lambda^n = \{(\lambda_1, \dots, \lambda_n) : \lambda_i \in [x, y]\}$, and by λ a generic element of Λ^n .

We propose a two stage auction mechanism whose extensive form is described as follows.

⁷Wolitzky also summarizes other recent papers examining the effect of weakening the common prior assumption.

Stage 1: Each buyer i observes his signal t_i and private value c_i and makes a (not necessarily honest) report of his signal to the auctioneer. If buyer i reports signal β and at least $\frac{n}{2}$ other buyers report β , then all buyers who have reported β (including i) advance to the second stage. If buyer i reports signal α and at least $\frac{n}{2}$ other buyers report α , then all buyers who have reported α (including i) advance to the second stage. If buyer i 's report is not a majority report, then i exits the game with a payoff of 0.

Stage 2: Suppose that $k + 1$ bidders advance to the second stage where $k \geq \frac{n}{2}$. With probability ε , the auctioneer will randomly choose (with probability $\frac{1}{k+1}$) one of the second stage buyers to be awarded the object outright. With probability $1 - \varepsilon$, the auctioneer will conduct a $k + 1$ bidder second price auction.

In our framework, we will only assume that the bounds x and y are common knowledge among the buyers. In addition, we do not specify beliefs regarding the accuracy profile $\lambda \in \Lambda^n$ so that, as a result, we cannot specify an equilibrium in the two stage game. We will instead only assume that, in the second stage, buyers submit undominated bids.⁸ More precisely, suppose that buyer i has advanced to the second stage and will participate in the second stage auction along with k other buyers. Denote the set of other buyers as S and note that $|S| = k$.

Definition: A bid τ_i by buyer i in the second stage auction is *dominated* if there exists a bid τ'_i such that

- a. for every $(\sigma_j)_{j \in S}$ and for every $\lambda \in \Lambda^n$, the expected payoff to buyer i when bidding τ'_i is at least as high as that attained when bidding τ_i , and
- b. for some $(\sigma_j)_{j \in S}$ and $\lambda \in \Lambda^n$, i 's expected payoff is higher when bidding τ'_i than that attained when bidding τ_i .

Before moving to the formal analysis, we will present an example that illustrates the basic purpose of the two stages of our mechanism.

The basic idea is to elicit and make public the information that gives rise to interdependent values in the first stage, turning the second stage into a private value problem. The interdependency results from buyers' noisy state signals, and buyers are asked to report those signals in the first stage. In general buyers may have an incentive to misreport those signals: if the common value is higher

⁸Chiesa, Micali and Zhu (2015) analyze a private value model in which agents have incomplete preferences and are restricted to choosing undominated strategies.

in state b than in state a , a buyer who gets a noisy signal β that the state is b has an incentive to report signal α that the state is a . Doing so lowers other buyers' beliefs that the state is b , which lowers other buyers' expected value of the object, leading them to bid lower in the second stage.

Our mechanism gives buyers an incentive to truthfully reveal their state signal by including a buyer in the second stage auction if and only if his announcement is in the majority. If all other buyers are reporting truthfully, a buyer has a better chance of being included in the second round by reporting truthfully than by misreporting.

While a buyer is more likely to get into the second stage auction by reporting truthfully, this is not enough to assure honest reporting. Consider the following example.

Suppose there are two equally likely states, a and b , three buyers, and buyers receive conditionally independent signals about the state where $P(\alpha|a) = P(\beta|b) = .6$.⁹ Player i 's utility function is $v(s) + c_i$, $s \in \{a, b\}$; the c_i 's are independent draws from the uniform distribution on $[0, 1]$.

Suppose buyer 1 receives signal β . His belief is now that $P(b|\beta) = .6$. If he announces β he will be in the majority unless the two other buyers both receive signal α . The probability of this is .16 if the state is b and .36 if the state is a . Thus, conditional on having received signal β , buyer 1's report of β will be a majority report with probability .76. If buyer 1 reports α , he will be in the majority unless the two other buyers both receive signal β . The probability of this is .36 if the state is b and .16 if the state is a . Thus, conditional on having received signal β , buyer 1's report of α will be a majority report with probability .72. Hence, as is expected, he has a greater chance of being in the majority by announcing truthfully when his signal is β than by misreporting.

However, there is a possible gain from misreporting. The probability that the buyer is in the majority when he reports α after seeing β is .72. When all buyers report truthfully and are informed of the numbers of reports of α and β , all buyers who participate in the second stage auction have the same beliefs about the probabilities of the states; that is, the asymmetry of information regarding the common value components of buyers' information has been eliminated. But when buyer 1 reports α when he has seen signal β , the buyer distorts the beliefs of the other buyers. For example, if buyers 2 and 3 both report α , they observe that all three second stage buyers reported α . Consequently, $P(b|\alpha, \alpha, \alpha) = .064$ and the expected value of the common value component to them is $.064 \cdot v(b) + .936 \cdot v(a)$. Player 1, however, knows that his signal was β , and $P(b|2 \alpha$'s and

⁹For this example we assume that the set of vectors of accuracies is a singleton.

1 β) = .288. The expected value of the common value component to buyer 1 is $.288 \cdot v(b) + .712 \cdot v(a)$. Similarly, when one of the other buyers received signal α and one received β , and buyer 1 reports α when he received β , buyer 1's posterior probability of state b is higher than other buyers' posterior probability. For buyer 1 then, there is a potential benefit from reporting α when he sees β : conditional on a majority of buyers announcing α , buyer 1 will have distorted other buyers' expected values so that their expectation of the common value component is lower than it would be if those buyers knew his true signal. This translates into lower bids by those buyers in the second stage auction, and hence, a lower price that buyer 1 will pay should he win the object.

This potential benefit to buyer 1 of announcing α when he sees β must be weighed against the probability of getting to the second stage. The expected gain from misreporting depends on $v(b) - v(a)$: when this difference is large enough, buyer 1 will do better by misreporting when he sees β . Thus, the greater chance of getting into the second stage auction may not alone be enough to incentivize truthful reporting.

The above discussion points out a buyer's trade-off between maximizing the chance of getting to the second stage auction and the benefits of distorting other buyers' beliefs. But it is clear that when the accuracy of buyers' signals is uniformly bounded below by $x > 1/2$ and above by $y < 1$, the degree to which a buyer believes that he can alter other buyers' beliefs by misreporting goes to zero as the number of buyers goes to infinity.

To summarize, we have so far argued that the gain to a buyer from misreporting his state signal when other buyers report truthfully goes to zero as the number of buyers goes to infinity. To ensure that there is *no* gain to such misreporting we modify the second stage. With probability $1 - \varepsilon$ the buyers will engage in a second price auction; with probability ε the object for sale will be given at no charge to one of the majority announcers who have advanced to the second stage. We will show that, when there are many buyers, this small modification will be sufficient to assure that a buyer has a strict incentive to announce truthfully if other buyers are doing so.

It is useful to provide a sketch of the argument. Choose $\varepsilon > 0$. Fix buyer i and suppose that buyer i receives signal β and all other buyers report honestly in the first stage and choose undominated bids in the second stage.

If i reports β along with k other buyers and advances to the second stage then he is awarded the object outright with probability $\frac{\varepsilon}{k+1}$. With probability $1 - \varepsilon$, i participates in a $k+1$ buyer auction in which exactly $k+1$ buyers have

received signal β . If $A_i(f_\beta^n(t_{-i}) = k, t_i = \beta)$ denotes the payoff to i in the auction, then i 's second stage payoff is

$$z(f_\beta^n(t_{-i}) = k, t_i = \beta) = (1-\varepsilon) \times A_i(f_\beta^n(t_{-i}) = k, t_i = \beta) + \frac{\varepsilon}{k+1} \times [\text{expected lottery payoff}].$$

If i instead reports α and advances to the second stage then he is awarded the object outright with probability $\frac{\varepsilon}{k+1}$. With probability $1 - \varepsilon$, i participates in a $k+1$ buyer auction in which exactly k buyers have received signal α . If $A_i(f_\alpha^n(t_{-i}) = k, t_i = \beta)$ denotes the payoff to i in the auction, then i 's second stage payoff is

$$z(f_\alpha^n(t_{-i}) = k, t_i = \beta) = (1-\varepsilon) \times A_i(f_\alpha^n(t_{-i}) = k, t_i = \beta) + \frac{\varepsilon}{k+1} \times [\text{expected lottery payoff}].$$

Buyer i will honestly report β if

$$\sum_{k \geq \frac{n}{2}} z(f_\beta^n(t_{-i}) = k, t_i = \beta) P(f_\beta^n(t_{-i}) = k | t_i = \beta) \geq \sum_{k \geq \frac{n}{2}} z(f_\alpha^n(t_{-i}) = k, t_i = \beta) P(f_\alpha^n(t_{-i}) = k | t_i = \beta)$$

and the following steps outline why this is true if n is sufficiently large. In particular, the argument proceeds by showing that, for sufficiently large n , there exists an integer $m(n) > \frac{n}{2}$ for which the following steps are valid whenever each $c_i < 1$.¹⁰

Step 1: Suppose that $k \geq m(n)$.

Then for every admissible accuracy profile, we have

$$P(b | f_\beta^n(t_{-i}) = k, t_i = \beta) \approx 1$$

implying that i 's expected lottery payoff is

$$c_i + E[v | f_\beta^n(t_{-i}) = k, t_i = \beta] \approx c_i + v(b).$$

Similarly,

$$P(b | f_\alpha^n(t_{-i}) = k, t_i = \beta) \approx 0$$

implying that i 's expected lottery payoff is

$$c_i + E[v | f_\alpha^n(t_{-i}) = k, t_i = \beta] \approx c_i + v(a).$$

Step 2: Suppose that $k \geq m(n)$. Then¹¹

¹⁰In the proof, $m(n) = x(n-1) - (n-1)^{\frac{2}{3}}$.

¹¹When $c_i < 1$, the payoff to the winning bidder converges to zero at an exponential rate. This is shown in Step 5 of the proof.

$$\lambda_i A_i(f_\beta^n(t_{-i}) = k, t_i = \beta) - (1 - \lambda_i) A_i(f_\alpha^n(t_{-i}) = k, t_i = \beta) \approx o\left(\frac{1}{k+1}\right)$$

where $mo\left(\frac{1}{m}\right) \rightarrow 0$ as $m \rightarrow \infty$ and

$$\begin{aligned} & \lambda_i [\text{i's expected lottery payoff} \mid f_\beta^n(t_{-i}) = k, t_i = \beta] \\ & - (1 - \lambda_i) [\text{i's expected lottery payoff} \mid f_\alpha^n(t_{-i}) = k, t_i = \beta] \\ & > \frac{\varepsilon}{(k+1)} \left[\frac{v(b) - v(a)}{2} \right]. \end{aligned}$$

Step 3: Combining steps 1 and 2, we conclude that for all $k \geq m(n)$ and for any accuracy profile, we have

$$\begin{aligned} \lambda_i z(f_\beta^n(t_{-i}) = k, t_i = \beta) &= k, t_i = \beta) - (1 - \lambda_i) z(f_\alpha^n(t_{-i}) = k, t_i = \beta) \\ &> o\left(\frac{1}{k+1}\right) + \frac{\varepsilon}{(k+1)} \left[\frac{v(b) - v(a)}{2} \right] \\ &> \frac{\varepsilon}{(k+1)} \left[\frac{v(b) - v(a)}{4} \right]. \end{aligned}$$

Step 4: For each $k \geq m(n)$ and for any accuracy profile, an application of the law of large numbers yields

$$\begin{aligned} & \sum_{k \geq \frac{n}{2}} z(f_\beta^n(t_{-i}) = k, t_i = \beta) P(f_\beta^n(t_{-i}) = k \mid t_i = \beta) \\ & \quad - \sum_{k \geq \frac{n}{2}} z(f_\alpha^n(t_{-i}) = k, t_i = \beta) P(f_\alpha^n(t_{-i}) = k \mid t_i = \beta) \\ & \approx \sum_{k \geq m(n)} z(f_\beta^n(t_{-i}) = k, t_i = \beta) P(f_\beta^n(t_{-i}) = k, t_i = \beta \mid b) \\ & \quad - \sum_{k \geq m(n)} z(f_\alpha^n(t_{-i}) = k, t_i = \beta) P(f_\alpha^n(t_{-i}) = k, t_i = \beta \mid a). \end{aligned}$$

Furthermore,

$$P(f_\beta^n(t_{-i}) = k, t_i = \beta \mid b) = \lambda_i Q_k(n)$$

and

$$P(f_\alpha^n(t_{-i}) = k, t_i = \beta \mid a) = (1 - \lambda_i) Q_k(n)$$

where

$$\sum_{k \geq m(n)} Q_k(n) \approx 1.$$

Step 5: Combining the previous steps, we conclude that

$$\begin{aligned}
& \sum_{k \geq \frac{n}{2}} z(f_\beta^n(t_{-i}) = k, t_i = \beta) P(f_\beta^n(t_{-i}) = k | t_i = \beta) - \sum_{k \geq \frac{n}{2}} z(f_\alpha^n(t_{-i}) = k, t_i = \beta) P(f_\alpha^n(t_{-i}) = k | t_i = \beta) \\
& \approx \sum_{k \geq m(n)} z(f_\beta^n(t_{-i}) = k, t_i = \beta) P(f_\beta^n(t_{-i}) = k, t_i = \beta | b) \\
& \quad - \sum_{k \geq m(n)} z(f_\alpha^n(t_{-i}) = k, t_i = \beta) P(f_\alpha^n(t_{-i}) = k, t_i = \beta | a) \\
& \approx \sum_{k \geq m(n)} z(f_\beta^n(t_{-i}) = k, t_i = \beta) \lambda_i Q_k(n) - \sum_{k \geq m(n)} z(f_\alpha^n(t_{-i}) = k, t_i = \beta) (1 - \lambda_i) Q_k(n) \\
& \approx \sum_{k \geq m(n)} [\lambda_i z(f_\beta^n(t_{-i}) = k, t_i = \beta) - (1 - \lambda_i) z(f_\alpha^n(t_{-i}) = k, t_i = \beta)] Q_k(n) \\
& \approx \sum_{k \geq m(n)} \frac{\varepsilon}{(k+1)} \left[\frac{v(b) - v(a)}{4} \right] Q_k(n) \\
& \geq \varepsilon \left[\frac{v(b) - v(a)}{4(n+1)} \right] \sum_{k \geq m(n)} Q_k(n) \\
& \approx \varepsilon \left[\frac{v(b) - v(a)}{4(n+1)} \right]
\end{aligned}$$

implying that

$$\sum_{k \geq \frac{n}{2}} z(f_\beta^n(t_{-i}) = k, t_i = \beta) P(f_\beta^n(t_{-i}) = k | t_i = \beta) - \sum_{k \geq \frac{n}{2}} z(f_\alpha^n(t_{-i}) = k, t_i = \beta) P(f_\alpha^n(t_{-i}) = k | t_i = \beta) > 0.$$

3 The result

Proposition: Suppose that $v(b) > v(a) \geq 0$ and $xv(a) > (1-x)v(b)$. Then for each $\varepsilon > 0$, there exists an N such that for each $n \geq N$ the following holds: for every accuracy profile $(\lambda_1, \dots, \lambda_n)$ satisfying $\frac{1}{2} < x \leq \lambda_j \leq y < 1$ for each j , for every characteristic profile (c_1, \dots, c_n) with $c_i \in [0, 1[$ and for every profile $(\sigma_1, \dots, \sigma_n)$ of undominated bids, the auction game is strictly interim individually rational and strictly incentive compatible at the first stage. That is

$$\sum_{k \geq \frac{n}{2}} z(f_\beta(t_{-i}) = k, t_i = \beta) P(f_\beta(t_{-i}) = k | t_i = \beta) - \sum_{k \geq \frac{n}{2}} z(f_\alpha(t_{-i}) = k, t_i = \beta) P(f_\alpha(t_{-i}) = k | t_i = \beta) > 0$$

and

$$\sum_{k \geq \frac{n}{2}} z(f_\alpha(t_{-i}) = k, t_i = \alpha) P(f_\alpha(t_{-i}) = k | t_i = \alpha) - \sum_{k \geq \frac{n}{2}} z(f_\beta(t_{-i}) = k, t_i = \alpha) P(f_\beta(t_{-i}) = k | t_i = \alpha) > 0.$$

Remark: For large n , the seller's **expected** revenue is close to

$$1 + \frac{v(a) + v(b)}{2}.$$

To see this, suppose that n is large. If the second stage auction has $k \geq \frac{n}{2}$ bidders who have reported α and are choosing undominated bids, then the bidders estimate the value of the common component to be approximately $v(a)$ so the winning bidder pays approximately $v(a)$ plus the second highest value of the private valuations of the other $k-1$ bidders. For large n this is approximately $1 + v(a)$. If the second stage auction has $k \geq \frac{n}{2}$ bidders who have reported β and are choosing undominated bids, then the bidders estimate the value of the common component to be approximately $v(b)$ so the winning bidder pays approximately $v(b)$ plus the second highest value of the private valuations of the other $k-1$ bidders. For large n this is approximately $1 + v(b)$. Therefore the seller's expected revenue from the mechanism is approximately equal to

$$[1 + v(a)]P(f_\alpha(t) \geq \frac{n}{2}) + [1 + v(b)]P(f_\beta(t) \geq \frac{n}{2}) = 1 + \frac{v(a) + v(b)}{2}.$$

4 Proof

Assume that i sees β and c_i where $0 \leq c_i < 1$.¹²

For a profile t of signals, note that

$$f_\alpha(t_{-i}) + f_\beta(t_{-i}) = n - 1$$

Let

$$\begin{aligned} \pi_k^\beta(n) &= E[v | f_\beta(t_{-i}) = k, t_i = \beta] \\ \pi_k^*(n) &= E[v | f_\alpha(t_{-i}) = k, t_i = \beta] \end{aligned}$$

and note that

$$\pi_k^\beta(n) > \pi_k^*(n).$$

The dependence of $f_\alpha(t_{-i})$ and $f_\beta(t_{-i})$ on n and the dependence of $\pi_k^\beta(n)$ and $\pi_k^*(n)$ on $\lambda_1, \dots, \lambda_n$ are suppressed for notational ease.

Step 1: To begin, note that there exists an integer N_0 such that for each i and for all $n \geq N_0$, we have

$$\frac{n}{2} < x(n-1) - (n-1)^{\frac{2}{3}} \leq \lambda_i(n-1) - (n-1)^{\frac{2}{3}} < \lambda_i(n-1) + (n-1)^{\frac{2}{3}} \leq y(n-1) + (n-1)^{\frac{2}{3}} < n.$$

¹²In this proof, the assumption that $v(b) > v(a)$ plays an important role. The case in which player i sees signal α employs essentially symmetric computations but now the assumption that $xv(a) > (1-x)v(b)$ comes into play.

Applying Hoeffding's inequality, it follows that

$$P\left(\left|\frac{f_\beta(t_{-i})}{n-1} - \frac{\sum_{j \neq i} \lambda_j}{n-1}\right| > \frac{1}{(n-1)^{\frac{1}{3}}}|b\right) \leq 2 \exp\left(-2(n-1)\frac{1}{(n-1)^{\frac{2}{3}}}\right).$$

Therefore,

$$P\left(f_\beta(t_{-i}) > y(n-1) + (n-1)^{\frac{2}{3}}|b\right) \leq P\left(f_\beta(t_{-i}) > \sum_{j \neq i} \lambda_j + (n-1)^{\frac{2}{3}}|b\right) \leq 2 \exp[-2(n-1)^{\frac{1}{3}}]$$

and

$$P\left(f_\beta(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}|b\right) \leq P\left(f_\beta(t_{-i}) < \sum_{j \neq i} \lambda_j - (n-1)^{\frac{2}{3}}|b\right) \leq 2 \exp(-2(n-1)^{\frac{1}{3}}).$$

Similarly,

$$P\left(\left|\frac{f_\alpha(t_{-i})}{n} - \frac{\sum_{j \neq i} \lambda_j}{n}\right| > \frac{1}{(n-1)^{\frac{1}{3}}}|a\right) \leq 2 \exp(-2(n-1)\frac{1}{(n-1)^{\frac{2}{3}}})$$

implying that

$$P\left(f_\alpha(t_{-i}) > y(n-1) + (n-1)^{\frac{2}{3}}|a\right) \leq P\left(f_\alpha(t_{-i}) > \sum_{j \neq i} \lambda_j + (n-1)^{\frac{2}{3}}|a\right) \leq 2 \exp(-2(n-1)^{\frac{1}{3}})$$

and

$$P\left(f_\alpha(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}|a\right) \leq P\left(f_\alpha(t_{-i}) < \sum_{j \neq i} \lambda_j - (n-1)^{\frac{2}{3}}|a\right) \leq 2 \exp(-2(n-1)^{\frac{1}{3}}).$$

We also will need the following probability bounds that follow from the bounds computed above:

(i)

$$\begin{aligned} P\left(f_\alpha(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}, t_i = \beta|a\right) &= (1 - \lambda_i)P\left(f_\alpha(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}|a\right) \\ &\leq 2(1 - \lambda_i) \exp(-2(n-1)^{\frac{1}{3}}). \end{aligned}$$

(ii)

$$\begin{aligned} P\left(f_\alpha(t_{-i}) \geq \frac{n}{2}, t_i = \beta|b\right) &= \lambda_i P\left(f_\alpha(t_{-i}) \geq \frac{n}{2}|b\right) \\ &= \lambda_i P\left(f_\beta(t_{-i}) < \frac{n}{2}|b\right) \\ &\leq \lambda_i P\left(f_\beta(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}|b\right) \\ &\leq 2\lambda_i \exp(-2(n-1)^{\frac{1}{3}}). \end{aligned}$$

(iii)

$$\begin{aligned} P\left(f_\beta(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}, t_i = \beta|b\right) &= \lambda_i P\left(f_\beta(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}|b\right) \\ &\leq 2\lambda_i \exp(-2(n-1)^{\frac{1}{3}}) \end{aligned}$$

(iv)

$$\begin{aligned} P\left(f_\beta(t_{-i}) \geq \frac{n}{2}, t_i = \beta|a\right) &= (1 - \lambda_i) P\left(f_\beta(t_{-i}) \geq \frac{n}{2}|a\right) \\ &= (1 - \lambda_i) P\left(f_\alpha(t_{-i}) < \frac{n}{2}|a\right) \\ &\leq (1 - \lambda_i) P\left(f_\alpha(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}|a\right) \\ &\leq 2(1 - \lambda_i) \exp(-2(n-1)^{\frac{1}{3}}). \end{aligned}$$

Step 2: We first compute bounds for $\pi_k^\beta(n) = E[v|f_\beta(t_{-i}) = k, t_i = \beta]$ that hold for all sufficiently large n . To begin, note that

$$\begin{aligned} \pi_k^\beta(n) &= v(a)P(a|f_\beta(t_{-i}) = k, t_i = \beta) + v(b)P(b|f_\beta(t_{-i}) = k, t_i = \beta) \\ &= v(b) - [v(b) - v(a)]P(a|f_\beta(t_{-i}) = k, t_i = \beta). \end{aligned}$$

Since

$$P(f_\beta(t_{-i}) = k, t_i = \beta|a) = (1 - \lambda_i) \sum_{\substack{S \subseteq N \setminus i \\ :|S|=k}} \left[\prod_{j \in S} (1 - \lambda_j) \right] \left[\prod_{j \notin S \cup i} \lambda_j \right]$$

and

$$P(f_\beta(t_{-i}) = k, t_i = \beta|b) = \lambda_i \sum_{\substack{S \subseteq N \setminus i \\ :|S|=k}} \left[\prod_{j \in S} \lambda_j \right] \left[\prod_{j \notin S \cup i} (1 - \lambda_j) \right]$$

we conclude that for all $n \geq N_0$,

$$\begin{aligned} P(a|f_\beta(t_{-i}) = k, t_i = \beta) &= \frac{P(f_\beta(t_{-i}) = k, t_i = \beta|a)}{P(f_\beta(t_{-i}) = k, t_i = \beta|a) + P(f_\beta(t_{-i}) = k, t_i = \beta|b)} \\ &= \frac{1}{1 + \frac{\lambda_i \sum_{\substack{S \subseteq N \setminus i \\ :|S|=k}} \left[\prod_{j \in S} \lambda_j \right] \left[\prod_{j \notin S \cup i} (1 - \lambda_j) \right]}{(1 - \lambda_i) \sum_{\substack{S \subseteq N \setminus i \\ :|S|=k}} \left[\prod_{j \in S} (1 - \lambda_j) \right] \left[\prod_{j \notin S \cup i} \lambda_j \right]} \\ &\leq \frac{1}{1 + \left(\frac{x}{1-x}\right)^{2k-n+2}} \end{aligned}$$

Let $d = 2x - 1$. Then there exists an integer $N_1 > N_0$ such that $n \geq N_1$ and $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$ imply that

$$\left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}} \leq \left(\frac{x}{1-x}\right)^{2k-(n-1)}.$$

To see this choose N_1 so that $d - 2(n-1)^{-\frac{1}{3}} > \frac{d}{2}$ for all $n \geq N_1$. Next, suppose that note that $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$. Then $\frac{x}{1-x} > 1$ implies that

$$\left(\frac{x}{1-x}\right)^{2k-(n-1)} \geq \left(\frac{x}{1-x}\right)^{2(x(n-1)-(n-1)^{\frac{2}{3}})-(n-1)}$$

and it follows that

$$\left(\frac{x}{1-x}\right)^{2k-(n-1)} \geq \left(\frac{x}{1-x}\right)^{2(x(n-1)-(n-1)^{\frac{2}{3}})-(n-1)} = \left(\frac{x}{1-x}\right)^{(n-1)[d-2(n-1)^{-\frac{1}{3}}]} \geq \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}}.$$

In particular,

$$\left(\frac{x}{1-x}\right)^{2k-n+2} \geq \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}+1}$$

Therefore, $n \geq N_1$ implies (since $v(a) < v(b)$) that for each $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$ we have

$$\begin{aligned} v(b) &\geq \pi_k^\beta(n) \\ &= v(b) - [v(b) - v(a)]P(a|f_\beta(t_{-i}) = k, t_i = \beta) \\ &\geq v(b) - \left[\frac{1}{1 + \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}+1}} \right] [v(b) - v(a)]. \end{aligned}$$

Step 3: We next compute bounds for $\pi_k^*(n) = E[v|f_\alpha(t_{-i}) = k, t_i = \beta]$ that hold for all n sufficiently large. To begin, note that

$$\begin{aligned} \pi_k^*(n) &= v(a)P(a|f_\alpha(t_{-i}) = k, t_i = \beta) + v(b)P(b|f_\alpha(t_{-i}) = k, t_i = \beta) \\ &= v(a) + [v(b) - v(a)]P(b|f_\alpha(t_{-i}) = k, t_i = \beta). \end{aligned}$$

Since

$$P(f_\alpha(t_{-i}) = k, t_i = \beta|a) = (1 - \lambda_i) \sum_{\substack{S \subseteq N \setminus i \\ :|S|=k}} \left[\prod_{j \in S} \lambda_j \right] \left[\prod_{j \notin S \cup i} (1 - \lambda_j) \right]$$

and

$$P(f_\alpha(t_{-i}) = k, t_i = \beta | b) = \lambda_i \sum_{\substack{S \subseteq N \setminus i \\ : |S|=k}} \left[\prod_{j \in S} (1 - \lambda_j) \right] \left[\prod_{j \notin S \cup i} \lambda_j \right]$$

we conclude that

$$\begin{aligned} P(b | f_\alpha(t_{-i}) = k, t_i = \beta) &= \frac{P(f_\alpha(t_{-i}) = k, t_i = \beta | b)}{P(f_\alpha(t_{-i}) = k, t_i = \beta | a) + P(f_\beta(t_{-i}) = k, t_i = \beta | b)} \\ &= \frac{1}{1 + \frac{(1 - \lambda_i) \sum_{\substack{S \subseteq N \setminus i \\ : |S|=k}} \left[\prod_{j \in S} \lambda_j \right] \left[\prod_{j \notin S \cup i} (1 - \lambda_j) \right]}{\lambda_i \sum_{\substack{S \subseteq N \setminus i \\ : |S|=k}} \left[\prod_{j \in S} (1 - \lambda_j) \right] \left[\prod_{j \notin S \cup i} \lambda_j \right]} } \\ &\leq \frac{1}{1 + \left(\frac{x}{1-x}\right)^{2k-n}}. \end{aligned}$$

If $n \geq N_1$ and $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$ then we conclude from step 2 that

$$\left(\frac{x}{1-x}\right)^{2k-(n-1)} \geq \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}}$$

implying that

$$\left(\frac{x}{1-x}\right)^{2k-n} = \left(\frac{x}{1-x}\right)^{2k-(n-1)} \left(\frac{1-x}{x}\right) \geq \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}} \left(\frac{1-x}{x}\right) = \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}-1}.$$

Therefore,

$$\begin{aligned} v(a) &\leq \pi_k^*(n) \\ &= v(a) + [v(b) - v(a)] P(b | f_\alpha(t_{-i}) = k, t_i = \beta). \\ &\leq v(a) + \left[\frac{1}{1 + \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}-1}} \right] [v(b) - v(a)]. \end{aligned}$$

Step 4: For each n , define

$$\eta_n = \left[\frac{1}{1 + \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}-1}} \right] [v(b) - v(a)]$$

and note that

$$\eta_n \geq \left[\frac{1}{1 + \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2}+1}} \right] [v(b) - v(a)].$$

Summarizing Steps 2 and 3, we conclude the following: for every $n \geq N_1$ and for each $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$, we conclude that

$$v(b) \geq \pi_k^\beta(n) \geq v(b) - \left[\frac{1}{1 + \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2} + 1}} \right] [v(b) - v(a)] \geq v(b) - \eta_n$$

$$v(a) \leq \pi_k^*(n) \leq v(a) + \left[\frac{1}{1 + \left(\frac{x}{1-x}\right)^{\frac{(n-1)d}{2} - 1}} \right] [v(b) - v(a)] = v(a) + \eta_n.$$

Step 5: We now compute estimates of player i 's expected payoff in the second stage auction if player i reports α and advances to the second stage. In this case, i will join $k \geq \frac{n}{2}$ other players that have reported α . Therefore, i 's expected payoff in the presence of k other players is equal to

$$\begin{aligned} & (1 - \varepsilon) \times [\text{expected auction payoff}] + \frac{\varepsilon}{k+1} \times [\text{expected lottery payoff}] \\ = & (1 - \varepsilon) A_i(f_\alpha(t_{-i}) = k, t_i = \beta) + \frac{\varepsilon}{k+1} [c_i + \pi_k^*(n)] \end{aligned}$$

So we must estimate player i 's expected payoff in the auction.

Suppose that $n \geq N_1$ and $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$. As summarized in Step 3, we have computed a bound for $\pi_k^*(n)$, so we must estimate player i 's expected payoff in the auction.

Suppose that each bidder i submits an undominated bid $c_i + z_i$ where z_i is bidder i 's estimate of the expectation of the common value component. Then

$$v(a) + \eta_n \geq z_i \geq v(a)$$

for every i . Note that the rv $c_j + z_j$ takes values in $[z_j, 1 + z_j]$. Next, note that for each $\zeta \in [\max_{j \neq i} z_j, 1 + \max_{j \neq i} z_j]$ we have

$$\text{Prob} \left(\max_{j \neq i} \{c_j + z_j\} \leq \zeta \right) = \prod_{j \neq i} F(\zeta - z_j).$$

Next, note that for sufficiently large n , we have

$$c_i + z_i \leq 1 + \max_{j \neq i} z_j$$

so we consider two cases. If $\max_{j \neq i} z_j \geq c_i + z_i$, then i 's auction payoff is 0. If $\max_{j \neq i} z_j < c_i + z_i$, then i 's auction payoff is

$$\int_{\max_{j \neq i} z_j}^{c_i + z_i} [c_i + \pi_k^*(n) - \zeta] \frac{d}{dy} \left[\prod_{j \neq i} F(\zeta - z_j) \right] dy = (\pi_k^*(n) - z_i) \prod_{j \neq i} F(c_i + z_i - z_j) + (c_i + z_i - \max_{j \neq i} z_j) \prod_{j \neq i} F(\mu - z_j)$$

for some μ satisfying

$$c_i + z_i > \mu > \max_{j \neq i} z_j.$$

Since $|z_i - z_j| < \eta_n$ for each j and $|z_i - \max_{j \neq i} z_j| < \eta_n$, there exists an integer $N_2 > N_1$ and $\delta > 0$ such that $0 \leq |c_i + z_i - z_j| \leq c_i + |z_i - z_j| < c_i + \delta < 1$ and $0 \leq |c_i + z_i - \max_{j \neq i} z_j| < c_i + \delta < 1$ whenever $n \geq N_2$. Therefore, $n \geq N_2$ and $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$ imply that

$$\begin{aligned} A_i(f_\alpha(t_{-i}) = k, t_i = \beta) &= (\pi_k^*(n) - z_i) \prod_{j \neq i} F(c_i + z_i - z_j) + (c_i + z_i - \max_{j \neq i} z_j) \prod_{j \neq i} F(\mu - z_j) \\ &\leq \eta_n F(c_i + \delta)^k + F(c_i + \delta)^{k+1}. \end{aligned}$$

Step 6: Suppose that $n \geq N_2 = \max\{N_0, N_1, N_2\}$ and $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$.

Let

$$B = \max\{z(f_\beta(t_{-i}) = k, t_i = \beta), z(f_\alpha(t_{-i}) = k, t_i = \beta) : t \in T, \lambda \in \{x, y\}^n\}.$$

Recalling that

$$P\left(f_\alpha(t_{-i}) \geq \frac{n}{2}, t_i = \beta | b\right) \leq 2\lambda_i \exp(-2(n-1)^{\frac{1}{3}})$$

and

$$P\left(f_\alpha(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}, t_i = \beta | a\right) \leq 2(1 - \lambda_i) \exp(-2(n-1)^{\frac{1}{3}})$$

we conclude that

$$\begin{aligned} & \sum_{k \geq \frac{n}{2}} z(f_\alpha(t_{-i}) = k, t_i = \beta) P(f_\alpha(t_{-i}) = k | t_i = \beta) \\ = & \sum_{\frac{n}{2} \leq k < x(n-1) - (n-1)^{\frac{2}{3}}} z(f_\alpha(t_{-i}) = k, t_i = \beta) P(f_\alpha(t_{-i}) = k, t_i = \beta | a) \\ & + \sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} z(f_\alpha(t_{-i}) = k, t_i = \beta) P(f_\alpha(t_{-i}) = k, t_i = \beta | a) \\ & + \sum_{k \geq \frac{n}{2}} z(f_\alpha(t_{-i}) = k, t_i = \beta) P(f_\alpha(t_{-i}) = k, t_i = \beta | b) \\ \leq & \sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} z(f_\alpha(t_{-i}) = k, t_i = \beta) P(f_\alpha(t_{-i}) = k, t_i = \beta | a) + 2B \exp(-2(n-1)^{\frac{1}{3}}). \end{aligned}$$

Recalling that

$$P\left(f_\beta(t_{-i}) \geq \frac{n}{2}, t_i = \beta | a\right) \leq 2(1 - \lambda_i) \exp(-2(n-1)^{\frac{1}{3}})$$

and

$$P\left(f_\beta(t_{-i}) < x(n-1) - (n-1)^{\frac{2}{3}}, t_i = \beta | b\right) \leq 2\lambda_i \exp(-2(n-1)^{\frac{1}{3}})$$

we conclude that

$$\begin{aligned} & \sum_{k \geq \frac{n}{2}} z(f_\beta(t_{-i}) = k, t_i = \beta) P(f_\beta(t_{-i}) = k | t_i = \beta) \\ = & \sum_{\frac{n}{2} \leq k < x(n-1) - (n-1)^{\frac{2}{3}}} z(f_\beta(t_{-i}) = k, t_i = \beta) P(f_\beta(t_{-i}) = k, t_i = \beta | b) \\ & + \sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} z(f_\beta(t_{-i}) = k, t_i = \beta) P(f_\beta(t_{-i}) = k, t_i = \beta | b) \\ & + \sum_{k \geq \frac{n}{2}} z(f_\beta(t_{-i}) = k, t_i = \beta) P(f_\beta(t_{-i}) = k, t_i = \beta | a) \\ \geq & \sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} z(f_\beta(t_{-i}) = k, t_i = \beta) P(f_\beta(t_{-i}) = k, t_i = \beta | b) - 2B \exp(-2(n-1)^{\frac{1}{3}}). \end{aligned}$$

Defining

$$Q_k(n) = \sum_{\substack{S \subseteq N \setminus i \\ |S|=k}} \left[\prod_{j \in S} \lambda_j \right] \left[\prod_{j \notin S \cup i} (1 - \lambda_j) \right]$$

it follows that

$$P(f_\alpha(t_{-i}) = k, t_i = \beta | a) = (1 - \lambda_i) P(f_\alpha(t_{-i}) = k | a) = (1 - \lambda_i) Q_k(n)$$

and

$$P(f_\beta(t_{-i}) = k, t_i = \beta | b) = \lambda_i P(f_\beta(t_{-i}) = k | b) = \lambda_i Q_k(n).$$

Therefore,

$$\begin{aligned} & \sum_{k \geq \frac{n}{2}} z(f_\beta(t_{-i}) = k, t_i = \beta) P(f_\beta(t_{-i}) = k | t_i = \beta) - \sum_{k \geq \frac{n}{2}} z(f_\alpha(t_{-i}) = k, t_i = \beta) P(f_\alpha(t_{-i}) = k | t_i = \beta) \\ \geq & \sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} [\lambda_i z(f_\beta(t_{-i}) = k, t_i = \beta) - (1 - \lambda_i) z(f_\alpha(t_{-i}) = k, t_i = \beta)] Q_k(n) - 4B \exp(-2(n-1)^{\frac{1}{3}}). \end{aligned}$$

Step 7: Suppose that $n \geq N_2 = \max\{N_0, N_1, N_2\}$ and $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$.

In this step we estimate

$$\lambda_i z(f_\beta(t_{-i}) = k, t_i = \beta) - (1 - \lambda_i) z(f_\alpha(t_{-i}) = k, t_i = \beta).$$

Recall that

$$z(f_\beta(t_{-i}) = k, t_i = \beta) = (1 - \varepsilon) A_i(f_\beta(t_{-i}) = k, t_i = \beta) + \frac{\varepsilon}{k+1} [c_i + \pi_k^\beta(n)]$$

and

$$z(f_\alpha(t_{-i}) = k, t_i = \beta) = (1 - \varepsilon) A_i(f_\alpha(t_{-i}) = k, t_i = \beta) + \frac{\varepsilon}{k+1} [c_i + \pi_k^*(n)].$$

Applying Step 5, it follows that

$$-(1 - \lambda_i) A_i(f_\alpha(t_{-i}) = k, t_i = \beta) \geq -(1 - \lambda_i) (\eta_n (c_i + \delta)^k + (c_i + \delta)^{k+1}) > -(\eta_n (c_i + \delta)^k + (c_i + \delta)^{k+1}).$$

Steps 2 and 3 imply that $\pi_k^\beta(n) \rightarrow v(b)$ and $\pi_k^*(n) \rightarrow v(a)$. So choose $N_3 > N_2$ so that for all $n > N_3$,

$$\lambda_i \pi_k^\beta(n) - (1 - \lambda_i) \pi_k^*(n) > \frac{\lambda_i v(b) - (1 - \lambda_i) v(a)}{2} \geq \frac{xv(b) - (1 - x)v(a)}{2} > 0.$$

Therefore,

$$\begin{aligned} & \lambda_i z(f_\beta(t_{-i}) = k, t_i = \beta) - (1 - \lambda_i) z(f_\alpha(t_{-i}) = k, t_i = \beta) = \\ & \lambda_i (1 - \varepsilon) A_i(f_\beta(t_{-i}) = k, t_i = \beta) + \frac{\varepsilon}{k+1} \lambda_i [c_i + \pi_k^\beta(n)] \\ & - (1 - \varepsilon) (1 - \lambda_i) A_i(f_\alpha(t_{-i}) = k, t_i = \beta) - (1 - \lambda_i) \frac{\varepsilon}{k+1} [c_i + \pi_k^*(n)] \\ & \geq \frac{\varepsilon}{k+1} \left[\frac{xv(b) - (1 - x)v(a)}{2} \right] - (1 - \varepsilon) \eta_n (c_i + \delta)^k + (c_i + \delta)^{k+1} \\ = & \frac{1}{(k+1)} \left(\varepsilon \left[\frac{xv(b) - (1 - x)v(a)}{2} \right] - (1 - \varepsilon)(k+1) (\eta_n (c_i + \delta)^k + (c_i + \delta)^{k+1}) \right). \end{aligned}$$

Step 8: Since $F(c_i + \delta) < 1$, it follows that for k large enough,

$$\varepsilon \left[\frac{xv(b) - (1 - x)v(a)}{2} \right] - (1 - \varepsilon)(k+1) (\eta_n F(c_i + \delta)^k + F(c_i + \delta)^{k+1}) > \varepsilon \left[\frac{xv(b) - (1 - x)v(a)}{4} \right]$$

Furthermore, for n large enough,

$$\varepsilon \left[\frac{xv(b) - (1 - x)v(a)}{4} \right] (1 - 2 \exp(-2(n-1)^{\frac{1}{3}}) - 4B(n+1) \exp(-2(n-1)^{\frac{1}{3}})) > 0$$

Consequently, there exists an $N > N_3$ such that for all $n \geq N$ and $k \geq x(n-1) - (n-1)^{\frac{2}{3}}$, and we conclude that

$$\begin{aligned}
& \sum_{k \geq \frac{n}{2}} z(f_\beta(t_{-i}) = k, t_i = \beta) P(f_\beta(t_{-i}) = k | t_i = \beta) - \sum_{k \geq \frac{n}{2}} z(f_\alpha(t_{-i}) = k, t_i = \beta) P(f_\alpha(t_{-i}) = k | t_i = \beta) \\
\geq & \sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} [\lambda_i z(f_\beta(t_{-i}) = k, t_i = \beta) - (1 - \lambda_i) z(f_\alpha(t_{-i}) = k, t_i = \beta)] Q_k(n) - 4B \exp(-2(n-1)^{\frac{1}{3}}) \\
\geq & \sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} \frac{1}{(k+1)} \left(\varepsilon \left[\frac{xv(b) - (1-x)v(a)}{2} \right] - (1-\varepsilon)(k+1) (\eta_n(c_i + \delta)^k + (c_i + \delta)^{k+1}) \right) Q_k(n) \\
& - 4B \exp(-2(n-1)^{\frac{1}{3}}) \\
\geq & \sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} \frac{1}{(k+1)} \left(\varepsilon \left[\frac{xv(b) - (1-x)v(a)}{4} \right] \right) Q_k(n) - 4B \exp(-2(n-1)^{\frac{1}{3}}) \\
\geq & \frac{1}{(n+1)} \left[\sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} \left(\varepsilon \left[\frac{xv(b) - (1-x)v(a)}{4} \right] \right) Q_k(n) - 4B(n+1) \exp(-2(n-1)^{\frac{1}{3}}) \right] \\
\geq & \frac{1}{(n+1)} \left[\left(\varepsilon \left[\frac{xv(b) - (1-x)v(a)}{4} \right] \right) \left[\sum_{k \geq x(n-1) - (n-1)^{\frac{2}{3}}} Q_k(n) \right] - 4B(n+1) \exp(-2(n-1)^{\frac{1}{3}}) \right] \\
= & \frac{1}{(n+1)} \left[\left(\varepsilon \left[\frac{xv(b) - (1-x)v(a)}{4} \right] \right) \left[P(f_\beta(t_{-i}) \geq x(n-1) - (n-1)^{\frac{2}{3}} | b) \right] - 4B(n+1) \exp(-2(n-1)^{\frac{1}{3}}) \right] \\
\geq & \frac{1}{(n+1)} \left[\left(\varepsilon \left[\frac{xv(b) - (1-x)v(a)}{4} \right] \right) (1 - 2 \exp(-2(n-1)^{\frac{1}{3}}) - 4B(n+1) \exp(-2(n-1)^{\frac{1}{3}})) \right] \\
> & 0
\end{aligned}$$

5 Discussion

1. When the number of buyers is large, the information of a single agent will generally have a small influence on the expected value of the common component. As discussed above, this is related to the idea of informational size that we have employed in other papers but differs in important ways. Our previous work assumed common knowledge of the information structure. Thus, if we were able to induce truthful revelation of agents' private information about the common component and make that information public, there would be common knowledge of the expected value of that common component. This turns the second stage auction into a private value auction. In the current paper there is no common knowledge prior over agents' information - no assumption is made about agents' beliefs about either the accuracy of their own signal or the signals

of others. For every probability distribution over buyers' accuracies, one can compute the expected value of the common component. To prove our main result we show that there is a lower bound on these expected values that converges to the expected value given the true state.

The following example illustrates that the convergence is NOT driven by revelation of all information relevant to the common component, but holds even if the second stage auction is one of interdependent values. Consider a problem like that analyzed in the paper in which bidders get noisy signals about the state where the accuracy is between x and y , where $x > 1/2$ and $y < 1$. Suppose that in addition to the signal about the state, each bidder learns whether the accuracy of her signal was above or below $\frac{x+y}{2}$. The process is as before - bidders announce their signal (but not the signal about the accuracy) and those in the majority participate in a second price auction in the second stage. Now, even though every bidder has information relevant to all other bidders but not available to them, our result still obtains. This follows since we proved that for every vector of accuracies the conclusion of the theorem holds.

2. We demonstrate that in our mechanism, if it is assumed that buyers do not make dominated bids should they reach the second stage auction, then it is optimal for a buyer to correctly reveal his state signal when there were many buyers and other buyers reported truthfully.¹³ It would, however, also have been optimal for a buyer to misreport his signal if all other buyers did so, for more or less the same reasons that truthful revelation is often not the unique equilibrium in a standard direct mechanism. To get to the second stage in our model, a buyer wants to be in the majority; if all other buyers misreport, my doing so as well maximizes my chance to move to the second stage. It should be noted, however, that whether all buyers report truthfully or all buyers lie (that is, each buyer announces the opposite of her signal), the same set of buyers will advance to the second stage and having advanced to the second stage, the constraints on the bids that are undominated is the same. Hence, the lower bound on the seller's expected revenue is the same whether buyers unanimously announce truthfully or untruthfully in the first stage. This does not, however, mean that the lower bound is the same for *all* equilibria. For example, it is an equilibrium for all buyers to report state a regardless of the signal they receive, and the lower bound on the seller's expected revenue would typically be lower

¹³Note that we do not say that correctly reporting the state signal is an equilibrium. Since a buyer who reaches the second stage does not necessarily have a well defined probability distribution over his possible values of the object, he does not have a well defined expected utility conditional on getting to the second stage.

for this equilibrium.

3. We treat the case in which there are two equally likely states of nature. An extension to an arbitrary finite number of equally likely states would be straightforward. Let $\{\theta_1, \dots, \theta_m\}$ denote the set of states and let $\{\alpha_1, \dots, \alpha_m\}$ denote the set of signals where $\frac{1}{2} < x \leq P_i(\alpha_i|\theta_i) \leq y < 1$. That is, the probability that player i 's signal is "correct" is bounded by x and y . Suppose that $v(\theta_k)$ denotes the common value in state θ_k and that $v(\theta_i)P(\theta_i|\alpha_i) > v(\theta_j)P(\theta_j|\alpha_i)$ for $i \neq j$. Then, as in the case analyzed above, if more buyers have announced state α_k than any other state, those buyers proceed to the second stage auction. As in the case above, a small lottery will induce buyers to truthfully announce their signals when other buyers do so.

4. We assume two equally likely states. While it is not critical that the states be exactly equally likely, the analysis above will break down if the states have dramatically different probabilities. Suppose the probability of state a is p and buyers get a state signal that has accuracy $.6$. If $p = .5$ and my signal indicates that the state is a , my belief is that a is the more likely state, and consequently, other people are more likely to get the signal indicating state a than a signal indicating state b . However, if $p = .01$, my posterior beliefs are that state b is more likely than a , and I have a better chance of getting to the second stage by misreporting my state signal than by reporting truthfully. If the states are not equally likely, there will be a minimum accuracy ρ of the signal for which, when I observe a signal for state a , my belief is that a is the most likely state. It is necessary and sufficient that the signal accuracy be at least this high to elicit truthful reporting.

5. We assume that the common value components of utility ($v(a)$ and $v(b)$) are the same for all buyers. One would expect that a similar argument would hold for some variation in these values across buyers. Similarly, one would expect a similar result would hold for some variations of the problem when the private and common values of buyers are not additively separable.

6. We assume that the bounds on the accuracies of buyers' signals is common knowledge. The intuition underlying the arguments above holds for deviations from common knowledge that are not too large. Suppose that there is a subset of buyers for whom the bounds on accuracies are common knowledge among themselves. If the subset consists of a proportion of the number of buyers that is close to, but less than, one, the intuition of our result carries over: bidding in

the second stage will generate expected revenue close to the maximum possible, and it will be strictly incentive compatible for buyers in the subset to report truthfully if others in the group do so.

7. We demonstrate that, for a particular auction problem, the incentive problem stemming from interdependent values can be ameliorated when there are many buyers. The structure of the argument suggests a general message. A buyer gains by misreporting that part of his private information that affects other buyers' values. By doing so the buyer alters other buyers' values by distorting their beliefs. The information structure in our problem has the property that as the number of buyers gets large, the degree to which a buyer can distort others' beliefs gets small, hence small rewards for truthful revelation induce truthful reporting. When the number of buyers gets large, the *aggregate* reward necessary to induce truthful reporting is small because the amount by which a buyer can distort other buyers' beliefs decreases faster than rate at which the number of buyers increases.

While there are information structures for which this is not the case, many natural information structures share this property. When this property holds, an important part of agents' asymmetric information – the part leading to interdependent values – can be dealt with at small cost.

8. MP2017 constructs a two-stage mechanism that uses the first-stage announcements to convert the initial interdependent value problem into a private value problem in the second stage, assuming truthful reporting in the first stage. This makes the analysis of agents' second stage bidding behavior easier: in the standard second-price auction, bidding below one's expected value is weakly dominated. In the current paper the second period problem is *not* private value: agents do not have a probability distribution over the accuracies of the signals received, hence, they do not have a probability distribution over their value of the object being auctioned. However, the lower bound on the possible accuracies puts a lower bound on the probability of the correct state of nature over all possible accuracies. This, in turn, puts a lower bound for any agent on her expected values across all possible accuracies, and bidding below this lower bound is dominated. As the number of agents increases, this lower bound converges (with probability one) to the value of the object had the underlying state of nature been known.

We outline a simple variant of the problem we have analyzed for which the second stage is necessarily interdependent value. Suppose each agent gets a noisy signal of the state of nature, with upper and lower bounds x and y on

the accuracy. Suppose that, unlike in our problem, each agent also learns that the accuracy is above or below $\frac{x+y}{2}$, that is, above or below the midpoint of the possible accuracies.¹⁴ How does this affect the performance of our mechanism (in which agents report their signal about the state but not whether their signal accuracy was above or below $\frac{x+y}{2}$).

The incentive in our mechanism for an agent to honestly report her signal when other agents do so is unchanged: the chance to participate in the lottery open to those whose reports are in the majority outweighs any incentive to misrepresent when there are many agents. The second stage second price auction, however, will not be a private value auction since each agent now has private information – whether her signal accuracy is above or below $\frac{x+y}{2}$ – that is unknown to other agents but payoff relevant to them. The second stage auction may be close to a private value auction, since in the second stage the non-public information any single agent has is of little importance when there are many agents. But the example in Jackson (2009) discussed above makes clear that auctions that are almost, but not quite, private value can be problematic.

Despite the fact that the second stage auctions for this problem are not private value, the performance of the mechanism when the number of agents increases will be the same as in our initial problem. The fact that the second stage auction is now an interdependent value problem makes determining an optimal bid even more difficult. But if agents truthfully report their stage signal in the first period, the lower bound on an agent’s expected value will still converge to her value had the state been known when the number of agents increases.

9. The first stage of our two stage mechanism functions as a way to provide information to agents in the second stage that is useful in constructing an accurate estimate of the true state $\theta \in \{a, b\}$. This estimate is then used to compute expected payoffs that determine those second stage bids that are undominated. In this paper, all agents report their signals and those making a majority report move to the second stage. In an equilibrium in which agents are truthful in the first stage, a player who advances to the second stage can compute the relative frequency vector and, consequently, construct an accurate estimate of the state θ as an application of the law of large numbers. Our choice of the first stage construction ensures strict interim individual rationality and strict incentive compatibility, properties that we view as desirable. If these strictness requirements are relaxed, then one can find alternative constructions

¹⁴We make no assumptions on the probability distribution of these.

of the first stage such that the information learned by second stage participants allows them to compute an accurate estimate of the state θ .

10. Our mechanism provides the incentive to truthfully report agents' state signals in the first stage by giving the object for free with probability ε to a randomly chosen member of the first stage majority. One could think of this as a metaphor for some advantage that accrues to being on the "winning side". For example, one could think of firms looking at applicants' announcements and limiting attention for promotion to those who had been in the majority.

11. Our main result takes an asymptotic perspective as the number of bidders gets large. A "small numbers" result is possible if signals are sufficiently accurate. Suppose that there are at least three bidders and each bidder gets a noisy signal about theta, with accuracy x_i , and $x_i \geq x^* < 1$. Let x^* be close to 1, meaning that all agents are getting signals that are highly accurate, but not perfectly accurate. Agents as usual announce the state, a or b . The majority go to the second stage (ignoring ties). Given the assumptions on the signal structure, an agent's expected effect on possible posteriors is small when other agents are announcing truthfully. A small prize (get the object for free with probability ε) is enough to get truth as an equilibrium if x^* sufficiently close to 1.

12. We can extend the analysis to multidimensional states. Suppose for the oil field example, the state θ has two attributes that bidders (might) value, say, the amount of oil and the depth of oil. Suppose that each of the attributes is binary: the amount is *High* or *Low* and depth is *Deep* or *Shallow*. Bidders may care about these differentially, that is, some may care more about amount than depth while for others it is the reverse. Suppose now each agent is going to receive a signal correlated with one of the attributes, but not the other. This violates our assumption that for any state, an agent receives a signal that has accuracy above .5 that his signal is the true state; now agents won't know about states that differ on the attribute signal they do not receive. Now, instead of asking an agent to "predict" the state, we ask him to predict the attribute with which his signal is correlated and the majority announcers go to the second stage. While not a private values problem in the second stage, our method of restricting bids to be undominated will still deliver the same result.

References

- [1] Bergemann, D., B. Brooks, and S. Morris (2017), “First Price Auctions with General Information Structures: Implications for Bidding and Revenue,” *Econometrica*, 85, 107-143.
- [2] Bergemann, D. and S. Morris (2012), “Robust Mechanism Design,” *World Scientific Book Chapters*, pp. 49-96.
- [3] Brooks, B. and S. Du (2021), “Optimal Auction Design with Common Values: An Informationally Robust Approach,” *Econometrica* 89, 1313-1360.
- [4] Borgeers, T. (2015), *An Introduction to the Theory of Mechanism Design*, Oxford University Press, New York, NY.
- [5] Chiesa, A., Silvio Micali and Z. Zhu (2015), “Knightian analysis of the Vickrey Mechanism,” *Econometrica*, 83, 1727-1754.
- [6] Du, Songzi (2018), “Robust Mechanisms under Common Valuation,” *Econometrica* 86, 1569-1588.
- [7] Gilboa, Itzhak and David Schmeidler (1989), “Maxmin expected utility with a nonunique prior,” *Journal of Mathematical Economics*, 18, 141–153.
- [8] Jackson, M. (2009), “Non-existence of Equilibrium in Vickrey, Second-Price, and English Auctions,” *Review of Economic Design* 13(1/2), 137-145.
- [9] McLean, R. and A. Postlewaite (2002), “Informational Size and Incentive Compatibility,” *Econometrica* 70, 2421-2454.
- [10] McLean, R. and A. Postlewaite (2004), “Informational Size and Efficient Auctions,” *Review of Economic Studies* 71, 809-827.
- [11] McLean, R. and A. Postlewaite (2017), “A Dynamic Non-direct Implementation Mechanism for Interdependent Value Problems,” *Games and Economic Behavior* 101, 34-48.
- [12] Wilson, R. (1989), “Game-Theoretic Analyses of Trading Processes,” in *Advances Fifth World Congress*, ed. by T. Bewley. Cambridge, U.K.: Chap. 2, 33-70.
- [13] Wolitzky, Alexander (2016), “Mechanism Design with Maxmin Agents: Theory and an Application to Bilateral Trade,” *Theoretical Economics* (11), 971-1004.