

Neoclassical Growth Model

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Neoclassical Growth Model

- Original contribution of [Ramsey \(1928\)](#). That is why some times it is known as the Ramsey model.
- Completed by [David Cass \(1965\)](#) and [Tjalling Koopmans \(1965\)](#). That is why some times it is known as the Cass-Koopmans model.
- [William Brock and Leonard Mirman \(1972\)](#) introduced uncertainty.
- [Finn Kydland and Edward Prescott \(1982\)](#) used to create the real business cycle research agenda.

Utility Function

- Representative household with a utility function:

$$u(c(t))$$

Observation

$u(c)$ is strictly increasing, concave, twice continuously differentiable with derivatives u' and u'' , and satisfies Inada conditions:

$$\lim_{c \rightarrow 0} u'(c) = \infty$$

$$\lim_{c \rightarrow \infty} u'(c) = 0$$

Dynastic Structure

- Population evolves:

$$L(t) = \exp(nt)$$

with $L_0 = 1$.

- Intergenerational altruism.
- Intertemporal utility function:

$$U(0) = \int_0^{\infty} e^{-(\rho-n)t} u(c(t)) dt$$

- ρ : subjective discount rate, such that $\rho > n$.
- $\rho - n$: “effective” discount rate.

Budget Constraint

- Asset evolution:

$$\dot{a} = (r - \delta - n) a + w - c$$

- Who owns the capital in the economy? Role of complete markets.
- Modigliani-Miller theorems.
- Arrow securities.

No-Ponzi-Game Condition

- No-Ponzi games.
- Historical examples.
- Condition:

$$\lim_{t \rightarrow \infty} a(t) \exp \left(- \int_0^t (r - \delta - n) ds \right) = 0$$

Production Side

- Cobb-Douglas aggregate production function:

$$Y = K^\alpha L^{1-\alpha}$$

- Per capita terms:

$$y = k^\alpha$$

- From the first order condition of firm with respect to capital k :

$$r = \alpha k^{\alpha-1}$$

$$w = k^\alpha - k\alpha k^{\alpha-1} = (1 - \alpha) k^\alpha$$

- Interest rate:

$$r - \delta$$

Aggregate Consistency Conditions

- Asset market clearing:

$$a = k$$

- Implicitly, labor market clearing.

- Resource constraint:

$$\dot{k} = k^\alpha - c - (n + \delta) k$$

Competitive Equilibrium I

A competitive equilibrium is a sequence of per capita allocations $\{c(t), k(t)\}_{t=0}^{\infty}$ and input prices $\{r(t), w(t)\}_{t=0}^{\infty}$ such that:

- Given input prices, $\{r(t), w(t)\}_{t=0}^{\infty}$, the representative household maximizes its utility:

$$\begin{aligned} & \max_{\{c(t), a(t)\}_{t=0}^{\infty}} \int_0^{\infty} e^{-(\rho-n)t} u(c(t)) dt \\ & \text{s.t. } \dot{a} = (r - \delta - n) a + w - c \\ & \lim_{t \rightarrow \infty} a(t) \exp\left(-\int_0^t (r - \delta - n) ds\right) = 0 \\ & a_0 = k_0 \end{aligned}$$

Competitive Equilibrium II

- Input prices, $\{r(t), w(t)\}_{t=0}^{\infty}$, are equal to the marginal productivities:

$$r(t) = \alpha k(t)^{\alpha-1}$$
$$w(t) = (1 - \alpha) k(t)^{\alpha}$$

- Markets clear:

$$a(t) = k(t)$$
$$\dot{k} = k(t)^{\alpha} - c(t) - (n + \delta) k(t)$$

Household Maximization

- We can come back now to the problem of the household.
- We build the Hamiltonian:

$$\mathcal{H}(a, c, \mu) = u(c(t)) + \mu(t) ((r(t) - n - \delta) a(t) - w(t) - c(t))$$

where:

- ① $a(t)$ is the state variable.
- ② $c(t)$ is the control variable.
- ③ $\mu(t)$ is the current-value co-state variable.

Necessary Conditions

- ① Partial derivative of the Hamiltonian with respect to controls is equal to zero:

$$\mathcal{H}_c(a, c, \mu) = u'(c(t)) - \mu(t) = 0$$

- ② Partial derivative of the Hamiltonian with respect to states is:

$$\mathcal{H}_a(a, c, \mu) = \mu(t)(r(t) - n - \delta) = (\rho - n)\mu(t) - \dot{\mu}(t)$$

- ③ Partial derivative of the Hamiltonian with respect to co-states is:

$$\mathcal{H}_\mu(a, c, \mu) = (r(t) - n - \delta)a(t) - c(t) = \dot{a}(t)$$

- ④ Transversality condition:

$$\lim_{t \rightarrow \infty} e^{-\rho t} \mu(t) \hat{a}(t) = 0$$

Working with the Necessary Conditions I

- From the second condition:

$$\mu (r - n - \delta) = (\rho - n) \mu - \dot{\mu} \Rightarrow$$

$$(r - n - \delta) = (\rho - n) - \frac{\dot{\mu}}{\mu} \Rightarrow$$

$$\frac{\dot{\mu}}{\mu} = - (r - \delta - \rho)$$

- From the first condition:

$$u'(c) = \mu$$

and taking derivatives with respect to time:

$$u''(c) \dot{c} = \dot{\mu} \Rightarrow$$

$$\frac{u''(c)}{u'(c)} \dot{c} = \frac{\dot{\mu}}{\mu} = - (r - \delta - \rho)$$

Working with the Necessary Conditions II

- Now, we can combine both expressions:

$$-\sigma \frac{\dot{c}}{c} = -(r - \delta - \rho)$$

where

$$\sigma = - \frac{u''(c)}{u'(c)} c = \frac{d \log(c(s) / c(t))}{d \log(u'(c(s)) / u'(c(t)))}$$

is the (inverse of) elasticity of intertemporal substitution (EIS).

- Thus:

$$\frac{\dot{c}}{c} = \frac{1}{\sigma} (r - \delta - \rho)$$

This expression is known as the **consumer Euler equation**.

CRRA

- In the previous equation we have implicitly assumed that σ is a constant.
- This will be only true of a class of utility functions.
- **Constant Relative Risk Aversion (CRRA):**

$$\frac{c^{1-\sigma} - 1}{1 - \sigma} \text{ for } \sigma \neq 1$$

$$\log c \text{ for } \sigma = 1$$

(you need to take limits and apply L'Hôpital's rule).

- Why is it called CRRA?

Applying Equilibrium Conditions

- First, note that $r = \alpha k^{\alpha-1}$. Then:

$$\frac{\dot{c}}{c} = \frac{1}{\sigma} (\alpha k^{\alpha-1} - \delta - \rho)$$

- Second, $k = a$. Then:

$$\begin{aligned} \dot{a} &= (r - \delta - n) a + w - c \Rightarrow \\ \dot{k} &= (\alpha k^{\alpha-1} - \delta - n) k + w - c \Rightarrow \\ \dot{k} &= k^{\alpha} - c - (n + \delta) k \end{aligned}$$

where in the last step we use the fact that $k^{\alpha} = \alpha k^{\alpha-1} k + w$.

System of Differential Equations

- We have two differential equations:

$$\begin{aligned}\frac{\dot{c}}{c} &= \frac{1}{\sigma} (\alpha k^{\alpha-1} - \delta - \rho) \\ \dot{k} &= k^{\alpha} - c - (n + \delta) k\end{aligned}$$

on two variables, k and c , plus the transversality condition:

$$\lim_{t \rightarrow \infty} e^{-\rho t} \mu \hat{a} = \lim_{t \rightarrow \infty} e^{-\rho t} \mu \hat{k} = 0$$

- How do we solve it?

Steady State

- We search for a steady state where $\dot{c} = \dot{k} = 0$.
- Then:

$$\begin{aligned}\frac{1}{\sigma} \left(\alpha (k^*)^{\alpha-1} - \delta - \rho \right) &= 0 \\ (k^*)^\alpha - c^* - (n + \delta) k^* &= 0\end{aligned}$$

- System of two equations on two unknowns k^* and c^* with solution:

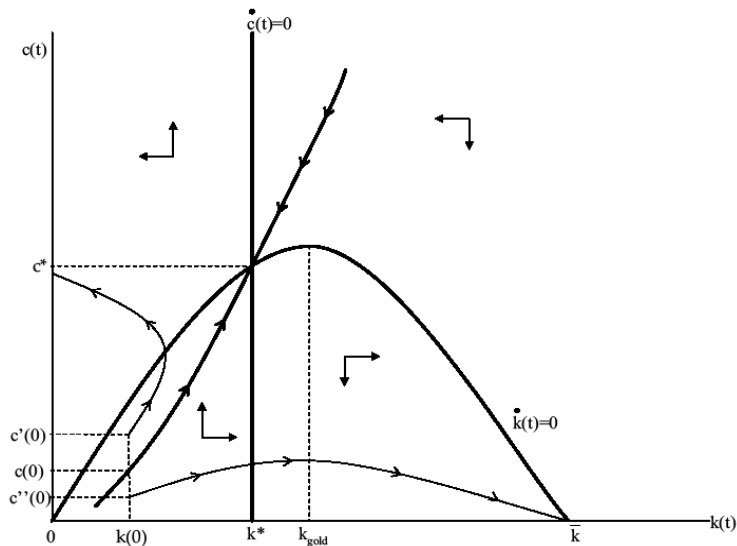
$$\begin{aligned}k^* &= \left(\frac{\alpha}{\rho + \delta} \right)^{\frac{1}{1-\alpha}} \\ c^* &= (k^*)^\alpha - (n + \delta) k^*\end{aligned}$$

- Note that EIS does not enter into the steady state. In fact, the form of the utility function is irrelevant!

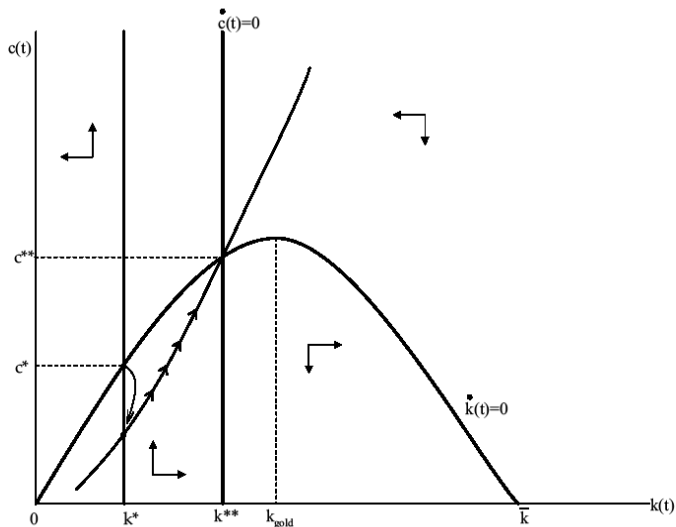
Transitional Dynamics

- The neoclassical growth model does not have a closed-form solution.
- We can do three things:
 - ① Use a phase diagram.
 - ② Solve an approximated version of the model where we linearize the equations.
 - ③ Use the computer to approximate numerically the solution.

Phase Diagram



Comparative Statics



Linearization I

- We can linearize the system

$$\begin{aligned}\frac{\dot{c}}{c} &= \frac{1}{\sigma} (\alpha k^{\alpha-1} - \delta - \rho) \\ \dot{k} &= k^{\alpha} - c - (n + \delta) k\end{aligned}$$

- We get:

$$\begin{aligned}\dot{c} &\simeq \frac{c^* \alpha (\alpha - 1) (k^*)^{\alpha-2}}{\sigma} (k - k^*) + \frac{\alpha (k^*)^{\alpha-1} - \delta - \rho}{\sigma} (c - c^*) \\ &= \frac{c^*}{\sigma} \left(\alpha (\alpha - 1) (k^*)^{\alpha-2} \right) (k - k^*)\end{aligned}$$

and

$$\begin{aligned}\dot{k} &\simeq \left(\alpha (k^*)^{\alpha-1} - n - \delta \right) (k - k^*) - (c - c^*) \\ &= (\rho - n) (k - k^*) - (c - c^*)\end{aligned}$$

Linearization II

- The behavior of the linearized system is given by the roots (eigenvalues) ξ of:

$$\det \begin{pmatrix} \rho - n - \xi & -1 \\ \frac{c^*}{\sigma} (\alpha (\alpha - 1) (k^*)^{\alpha-2}) & -\xi \end{pmatrix}$$

- Solving

$$-\xi (\rho - n - \xi) + \frac{c^*}{\sigma} (\alpha (\alpha - 1) (k^*)^{\alpha-2}) = 0 \Rightarrow$$

$$\xi^2 - \xi (\rho - n) + \frac{c^*}{\sigma} (\alpha (\alpha - 1) (k^*)^{\alpha-2}) = 0$$

Linearization III

- Thus:

$$\tilde{\zeta} = \frac{(\rho - n) \pm \sqrt{1 - 4(\alpha(\alpha - 1)(k^*)^{\alpha-2})}}{2}$$

and since $\alpha(\alpha - 1) < 1$, we have one positive and one negative eigenvalue \Rightarrow one stable manifold.

- We will call $\tilde{\zeta}_1$ the positive eigenvalue and $\tilde{\zeta}_2$ the negative one.
- With some results in differential equations, we can show:

$$\begin{aligned} k &= k^* + \eta_1 e^{\tilde{\zeta}_1 t} + \eta_2 e^{\tilde{\zeta}_2 t} \Rightarrow \\ k - k^* &= \eta_1 e^{\tilde{\zeta}_1 t} + \eta_2 e^{\tilde{\zeta}_2 t} \end{aligned}$$

where η_1 and η_2 are arbitrary constants of integration.

Linearization IV

- It must be that $\eta_1 = 0$. If $\eta_1 > 0$, we will violate the transversality condition and $\eta_1 < 0$ will take k_t to 0.
- Then, η_2 is determined by:

$$\eta_2 = k_0 - k^*$$

- Hence:

$$k = (1 - e^{\zeta_2 t}) k^* + e^{\zeta_2 t} k_0 \Rightarrow$$
$$k - k^* = \eta_2 e^{\zeta_2 t} = (k_0 - k^*) e^{\zeta_2 t}$$

Linearization V

- Also:

$$\dot{c} = \frac{c^*}{\sigma} \left(\alpha (\alpha - 1) (k^*)^{\alpha-2} \right) (k - k^*)$$

or

$$c = \frac{c^*}{\sigma} \left(\alpha (\alpha - 1) (k^*)^{\alpha-2} \right) \frac{\eta_2}{\xi_2} e^{\xi_2 t} + c^*$$

where the constant c^* ensures that we converge to the steady state.

- Since $y = k^\alpha$, we get:

$$\log y = \alpha \log \left(k^* + (k_0 - k^*) e^{\xi_2 t} \right)$$

Linearization VI

- Taking time derivatives and making $y = y_0$:

$$\begin{aligned}\frac{\dot{y}}{y_0} &= \frac{\alpha}{k^* + (k_0 - k^*) e^{\zeta_2 t}} \left((k_0 - k^*) \zeta_2 e^{\zeta_2 t} \right) \\ &= \alpha \zeta_2 - \alpha \zeta_2 \frac{k^*}{k_0} \\ &= \alpha \zeta_2 - \alpha \zeta_2 \left(\frac{y^*}{y_0} \right)^{\frac{1}{\alpha}}\end{aligned}$$

- This suggest to go to the data and run convergence regressions of the form:

$$g_{i,t,t-1} = b^0 + b^1 \log y_{i,t-1} + \varepsilon_{i,t}$$

- We need to be careful about interpreting the coefficient \hat{b}^1 .
- Where does the error come from?

Selecting Parameter Values

- In general computers cannot approximate the solution for arbitrary parameter values.
- How do we determine the parameter values?
- Two main approaches:
 - ① Calibration.
 - ② Statistical methods: Methods of Moments, ML, Bayesian.
- Advantages and disadvantages.

Calibration as an Empirical Methodology

- Emphasized by Lucas (1980) and Kydland and Prescott (1982).
- Two sources of information:
 - ① Well accepted microeconomic estimates.
 - ② Matching long-run properties of the economy.
- Problems of 1 and 2.
- References:
 - ① Browning, Hansen, and Heckman (1999) chapter in *Handbook of Macroeconomics*.
 - ② Debate in *Journal of Economic Perspectives*, Winter 1996: Kydland and Prescott, Hansen and Heckman, Sims.

Calibration of the Standard Model

- Parameters: n , α , δ , ρ , and σ .
- n : population growth in the data.
- α : capital income. Proprietor's income?
- δ : in steady state

$$\delta k^* = x^* \Rightarrow \delta = \frac{x^*}{k^*}$$

- ρ : in steady state

$$r^* = \alpha \left(\frac{\alpha}{\rho + \delta} \right)^{\frac{\alpha}{1-\alpha} - 1} - \delta$$

Then, we take r^* from the data and given α and δ , we find ρ

- σ : from microeconomic evidence.

Running Model in the Computer

- We have the system:

$$\begin{aligned}\frac{\dot{c}}{c} &= \frac{1}{\sigma} (\alpha k^{\alpha-1} - \delta - \rho) \\ \dot{k} &= k^\alpha - c - (n + \delta) k\end{aligned}$$

- Many methods to solve it.
- A simple one is a **shooting algorithm**.
- A popular alternative: **Runge-Kutta methods**.

A Shooting Algorithm

- Approximate the system by:

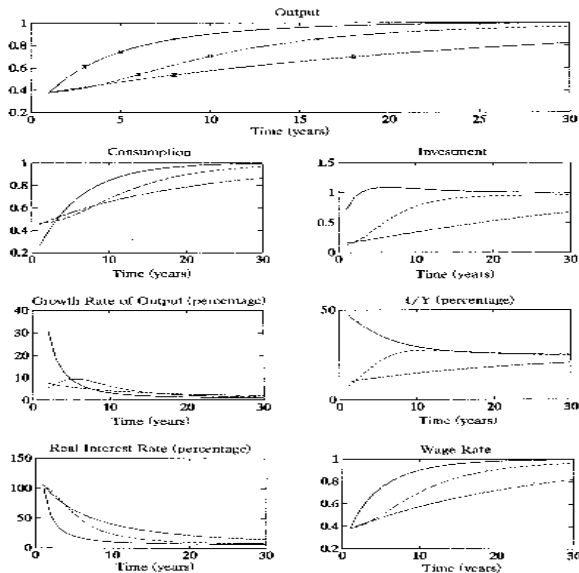
$$\frac{\frac{c(t+\Delta t) - c(t)}{\Delta t}}{c(t)} = \frac{1}{\sigma} \left(\alpha k(t)^{\alpha-1} - \delta - \rho \right)$$

$$\frac{k(t + \Delta t) - k(t)}{\Delta t} = k(t)^\alpha - c(t) - (n + \delta) k(t)$$

for a small Δt .

- Steps:
 - Given $k(0)$, guess $c(0)$.
 - Trace dynamic system for a long t .
 - Is $k(t) \rightarrow k^*$? If yes, we got the right $c(0)$. If $k(t) \rightarrow \infty$, raise $c(0)$, if $k(t) \rightarrow 0$, lower $c(0)$.
- Intuition: phase diagram.

A Computational Example



Savings Rate I

- We can actually work on our system of differential equations a bit more to show a more intimate relation between the Solow and the Neoclassical growth model.
- The savings rate is defined as:

$$s(t) = 1 - \frac{c(t)}{y(t)}$$

- Now

$$\frac{d(c(t)/y(t))}{dt} \frac{1}{c(t)/y(t)} = \frac{\dot{c}}{c} - \frac{\dot{y}}{y} = \frac{\dot{c}}{c} - \alpha \frac{\dot{k}}{k}$$

Savings Rate II

- If we substitute in the differential equations for $\frac{\dot{c}}{c}$ and \dot{k} :

$$\begin{aligned}
 & \frac{d(c(t)/y(t))}{dt} \frac{1}{c(t)/y(t)} \\
 &= \frac{1}{\sigma} (\alpha k^{\alpha-1} - \delta - \rho) - \alpha \left(k^{\alpha-1} - \frac{c}{k} - n - \delta \right) \\
 &= \frac{1}{\sigma} (\alpha k^{\alpha-1} - \delta - \rho) - \alpha \left(k^{\alpha-1} - \frac{c}{y} k^{\alpha-1} - n - \delta \right) \\
 &= -\frac{1}{\sigma} (\delta + \rho) + \alpha (n + \delta) + \left(\frac{1}{\sigma} - 1 + \frac{c}{y} \right) \alpha k^{\alpha-1}
 \end{aligned}$$

Savings Rate III

- Then:

$$\frac{d(c(t)/y(t))}{dt} \frac{1}{c(t)/y(t)}$$

$$= -\frac{1}{\sigma} (\delta + \rho) + \alpha (n + \delta) + \left(\frac{1}{\sigma} - 1 + \frac{c}{y} \right) \alpha k^{\alpha-1}$$

$$\dot{k} = k^{\alpha} - c - (n + \delta) k$$

is another system of differential equations.

- This system implies that the saving rate is monotone (always increasing, always decreasing, or constant).

Savings Rate IV

- We find the locus $\frac{d(c(t)/y(t))}{dt} = 0$:

$$\left(\frac{1}{\sigma} - 1 + \frac{c}{y}\right) \alpha k^{\alpha-1} = \frac{1}{\sigma} (\delta + \rho) - \alpha (n + \delta) \Rightarrow$$

$$\frac{c}{y} = 1 - \frac{1}{\sigma} + \left(\frac{1}{\sigma} (\delta + \rho) - \alpha (n + \delta)\right) \frac{1}{\alpha} k^{1-\alpha}$$

- Hence, if

$$\frac{1}{\sigma} (\delta + \rho) = \alpha (n + \delta)$$

the savings rate is constant, and we are back into the basic Solow model!

The Social Planner's Problem

- The Social planner's problem can be written as:

$$\begin{aligned} & \max_{\{c(t), k(t)\}_{t=0}^{\infty}} \int_0^{\infty} e^{-(\rho-n)t} u(c(t)) dt \\ & \text{s.t. } \dot{k} = k(t)^\alpha - c(t) - (n + \delta) k(t) \\ & \lim_{t \rightarrow \infty} k(t) \exp\left(-\int_0^t (r - \delta - n) ds\right) = 0 \\ & \quad k_0 \text{ given} \end{aligned}$$

- This problem is very similar to the household's problem.
- We can also apply the optimality principle to the Hamiltonian:

$$u(c(t)) + \mu(t) (k(t)^\alpha - c(t) - (n + \delta) k(t))$$

Necessary Conditions

- ① Partial derivative of the Hamiltonian with respect to controls is equal to zero:

$$H_c(a, c, \mu) = u'(c(t)) - \mu(t) = 0$$

- ② Partial derivative of the Hamiltonian with respect to states is:

$$H_a(a, c, \mu) = \mu(t) \left(\alpha k(t)^{\alpha-1} - n - \delta \right) = (\rho - n) \mu(t) - \dot{\mu}(t)$$

- ③ Partial derivative of the Hamiltonian with respect to co-states is:

$$H_\mu(a, c, \mu) = k(t)^\alpha - c(t) - (n + \delta) k(t) = \dot{k}(t)$$

- ④ Transversality condition:

$$\lim_{t \rightarrow \infty} e^{-\rho t} \mu(t) \hat{k}(t) = 0$$

Comparing the Necessary Conditions

- Following very similar steps than in the problem of the consumer we find:

$$\begin{aligned}\frac{\dot{c}}{c} &= \frac{1}{\sigma} (\alpha k^{\alpha-1} - \delta - \rho) \\ \dot{k} &= k^{\alpha} - c - (n + \delta) k \\ \lim_{t \rightarrow \infty} e^{-\rho t} \mu(t) \hat{k}(t) &= 0\end{aligned}$$

- From the household problem:

$$\begin{aligned}\frac{\dot{c}}{c} &= \frac{1}{\sigma} (\alpha k^{\alpha-1} - \delta - \rho) \\ \dot{k} &= k^{\alpha} - c - (n + \delta) k \\ \lim_{t \rightarrow \infty} e^{-\rho t} \mu(t) \hat{k}(t) &= 0\end{aligned}$$

- Both problems have the same necessary conditions!