Econ 704 Macroeconomic Theory Spring 2019*

José-Víctor Ríos-Rull
University of Pennsylvania
Federal Reserve Bank of Minneapolis
CAERP

May 15, 2019

# 5 Adding Heterogeneity

## 5.1 Heterogeneity in Wealth

## 5.2 Heterogeneity in Skills

## 5.3 An International Economy Model

# 6 Stochastic Economies

## 6.1 A Review

### 6.1.1 Markov Processes

### 6.1.2 Problem of the Social Planner

### 6.1.3 Recursive Competitive Equilibrium

## 6.2 An International Economy Model with Shocks

## 6.3 Heterogeneity in Wealth and Skills with Complete Markets

# 7 Asset Pricing: Lucas Tree Model

## 7.1 The Lucas Tree with Random Endowments

## 7.2 Asset Pricing

## 7.3 Taste Shocks

# 8 Endogenous Productivity in a Product Search Model

## 8.1 Competitive Search
8.1.1 Firms\' Problem .................................................. 49

9 Measure Theory .................................................... 49

10 Industry Equilibrium ............................................... 55

  10.1 Preliminaries .................................................. 55
  10.2 A Simple Dynamic Environment ......................... 56
  10.3 Introducing Exit Decisions ................................ 59
  10.4 Stationary Equilibrium ...................................... 63
  10.5 Adjustment Costs ........................................... 65
  10.6 Non-stationary Equilibrium ................................. 67
  10.7 Linear Approximation ...................................... 69

11 Incomplete Market Models ..................................... 71

  11.1 A Farmer\'s Problem ....................................... 71
  11.2 Huggett Economy .......................................... 74
  11.3 Aiyagari Economy .......................................... 76
     11.3.1 Policy Changes and Welfare ....................... 79
  11.4 Business Cycles in an Aiyagari Economy ............... 80
     11.4.1 Aggregate Shocks ................................... 80
11.4.2 Linear Approximation Revisited ................................................. 82

11.5 Aiyagari Economy with Job Search ............................................... 83

11.6 Aiyagari Economy with Entrepreneurs ........................................... 84

11.7 Other Extensions ........................................................................... 86

12 Monopolistic Competition ................................................................. 87

12.1 Benchmark Monopolistic Competition ............................................. 87

12.2 Price Rigidity .................................................................................. 90

A A Farmer's Problem: Revisited .......................................................... 92
1 Introduction

A model is an artificial economy. The description of a model’s environment may include specifying the agents’ preferences and endowment, technology available, information structure as well as property rights. The Neoclassical Growth Model is one of the workhorses of modern macroeconomics because it delivers some fundamental properties of industrialized economies, summarized by, among others, Kaldor (1957):

1. Output per capita has grown at a roughly constant rate (2%).
2. The capital-output ratio (where capital is measured using the perpetual inventory method based on past consumption foregone) has remained roughly constant (despite output per capita growth).
3. The capital-labor ratio has grown at a roughly constant rate equal to the growth rate of output.
4. The wage rate has grown at a roughly constant rate equal to the growth rate of output.
5. The real interest rate has been stationary and, during long periods, roughly constant.
6. Labor income as a share of output has remained roughly constant (0.66).
7. Hours worked per capita have been roughly constant.

Equilibrium can be defined as a prediction of what will happen and therefore it is a mapping from environments to outcomes (allocations, prices, etc.). One equilibrium concept that we will deal with is Competitive Equilibrium\textsuperscript{1}. Characterizing the equilibrium, however, usually involves finding solutions to a system of an infinite number of equations. There are generally two ways of getting around this. First, invoke the welfare theorem to solve for the allocation and then find the equilibrium prices associated with it. This may sometimes not work due to, say, the presence of externalities. The second way is to resort to dynamic programming and study a Recursive Competitive equilibrium, in which equilibrium objects are functions instead of variables.

\textsuperscript{1} Arrow-Debreu or Valuation Equilibrium.
2 Review: Neoclassical Growth Model

We review briefly the basic neoclassical growth model.

2.1 The Neoclassical Growth Model (Without Uncertainty)

The commodity space is

\[ \mathcal{L} = \{(l_1, l_2, l_3) : l_i = (l_{it})_{t=0}^{\infty}, l_{it} \in \mathbb{R}, \sup_{t} |l_{it}| < \infty, i = 1, 2, 3\}. \]

The consumption possibility set is

\[ X(k_0) = \{x \in \mathcal{L} : \exists (c_t, k_{t+1})_{t=0}^{\infty} \text{ s.th. } \forall t = 0, 1, \ldots c_t, k_{t+1} \geq 0, x_{1t} + (1 - \delta)k_t = c_t + k_{t+1}, -k_t \leq x_{2t} \leq 0, -1 \leq x_{3t} \leq 0, k_0 = k_0\}. \]

The production possibility set is \( Y = \prod_t Y_t \), where

\[ Y_t = \{(y_{1t}, y_{2t}, y_{3t}) \in \mathbb{R}^3 : 0 \leq y_{1t} \leq F(-y_{2t}, -y_{3t})\}. \]

**Definition 1** An Arrow-Debreu equilibrium is \((x^*, y^*) \in X \times Y\), and a continuous linear functional \(\nu^*\) such that

1. \(x^* \in \arg \max_{x \in X, \nu^*(x) \leq 0} \sum_{t=0}^{\infty} \beta^t u(c_t(x), -x_{3t})\),
2. \(y^* \in \arg \max_{y \in Y} \nu^*(y)\),
3. and \(x^* = y^*\).

Note that in this definition we have added leisure. Now, let’s look at the one-sector growth model’s
Social Planner’s Problem:

\[
\max \sum_{t=0}^{\infty} \beta^t u(c_t, -x_{3t}) \quad (SPP)
\]

s.t.
\[
c_t + k_{t+1} - (1 - \delta)k_t = x_{1t}
\]

\[-k_t \leq x_{2t} \leq 0\]

\[-1 \leq x_{3t} \leq 0\]

\[0 \leq y_{1t} \leq F(-y_{2t}, -y_{3t})\]

\[x = y\]

\[k_0 \text{ given.}\]

Suppose we know that a solution in sequence form exists for (SPP) and is unique.

**Exercise 1** Clearly stating sufficient assumptions on utility and production function, show that (SPP) has a unique solution.

Two important theorems show the relationship between CE allocations and Pareto optimal allocations:

**Theorem 1 (FWT)** Suppose that for all \(x \in X\) there exists a sequence \((x_k)_{k=0}^{\infty}\), such that for all \(k \geq 0\), \(x_k \in X\) and \(U(x_k) > U(x)\). If \((x^*, y^*, \nu^*)\) is an Arrow-Debreu equilibrium, then \((x^*, y^*)\) is Pareto efficient allocation.

**Theorem 2 (SWT)** If \(X\) is convex, preferences are convex, \(U\) is continuous, \(Y\) is convex and has an interior point, then for any Pareto efficient allocation \((x^*, y^*)\) there exists a continuous linear functional \(\nu\) such that \((x^*, y^*, \nu)\) is a quasiequilibrium, that is:

(i) for all \(x \in X\) such that \(U(x) \geq U(x^*)\) it implies \(\nu(x) \geq \nu(x^*)\);

(ii) for all \(y \in Y\), \(\nu(y) \leq \nu(y^*)\).

Note that at the very basis of the CE definition and welfare theorems there is an implicit assumption of perfect commitment and perfect enforcement. Note also that the FWT implicitly assumes there is no
externality or public goods (achieves this implicit assumption by defining a consumer’s utility function only on his own consumption set but no other points in the commodity space). The Greenwald-Stiglitz theorem establishes the Pareto inefficiency of market economies with imperfect information and incomplete markets.

From the First Welfare Theorem, we know that if a Competitive Equilibrium exists, it is Pareto Optimal. Moreover, if the assumptions of the Second Welfare Theorem are satisfied and if the SPP has a unique solution, then the competitive equilibrium allocation is unique and is the same as the PO allocation. Prices can be constructed using this allocation and first-order conditions.

**Exercise 2** Show that

\[
\frac{v_{2t}}{v_{1t}} = F_k(k_t, l_t) \quad \text{and} \quad \frac{v_{3t}}{v_{1t}} = F_l(k_t, l_t).
\]

One shortcoming of the AD equilibrium is that all trade occurs at the beginning of time. This assumption is unrealistic. Modern economics is based on sequential markets. Therefore, we define another equilibrium concept, Sequential Markets Equilibrium (SME). We can easily show that SME is equivalent to ADE by introducing AD securities. All of our results still hold and SME is the right problem to solve.

**Exercise 3** Define a Sequential Markets Equilibrium (SME) for this economy. Prove that the objects we get from the AD equilibrium satisfy SME conditions and that the converse is also true. We should first show that a CE exists and therefore coincides with the unique solution of (SPP).

Note that the (SPP) problem is hard to solve, since we are dealing with an infinite number of choice variables. We have already established the fact that this SPP problem is equivalent to the following dynamic problem (removing leisure from now on), which is easier to solve:

\[
v(k) = \max_{c,k'} u(c) + \beta v(k') \quad (RSPP)
\]

s.t. \( c + k' = f(k) \).
2.2 A Comment on the Welfare Theorems

Situations in which the welfare theorems would not hold include externalities, public goods, situations in which agents are not price-takers (e.g. monopolies), some legal systems or lacking of markets, which rule out certain contracts that appear to be complete or search frictions. What happens in such situations? The solutions to the Social Planner problem and the CE do not coincide, and so we cannot use the theorems we have developed for dynamic programming. As we will see in this course, we can work with Recursive Competitive Equilibria. In general, we can prove that the solution to the RCE coincides with the one derived from the SME, but not the other way around (for example when we have multiple equilibria). However, in all the models we see in this course, this equivalence will hold.

3 Recursive Competitive Equilibrium

3.1 A Simple Example

We have so far established the equivalence between the allocation of the SP problem, which gives the unique Pareto optimal allocation, and the allocations of the AD equilibrium and the SME. We can now solve for the very complicated equilibrium allocation by solving the relatively easier Dynamic Programming problem of the social planner. One handicap of this approach is that in many environments the equilibrium is not Pareto Optimal and hence not a solution of a social planner’s problem (e.g. when taxes are distortionary or when externalities are present). Therefore, the recursive formulation of the problem would not be the right problem to solve. In some of these situations we can still write the problem in sequence form. However, we would lose the powerful computational techniques of dynamic programming. In order to resolve this issue we will define the Recursive Competitive Equilibrium equivalent to SME that we can always solve for.

In order to write the household problem recursively, we need to use equilibrium conditions so that the household knows what prices are, in particular, as a function of some economy-wide aggregate state.
variables. Let aggregate capital be $K$ and aggregate labor $L = 1$. Then from solving the firm’s problem, factor prices are given by $w(K) = F_n(K, 1)$ and $R(K) = F_k(K, 1)$. Therefore, since households take prices as given, they need to know aggregate capital. A household who is deciding about how much to consume and how much to work has to know the whole sequence of future prices in order to make her decision and that means that she needs to know the path of aggregate capital. Therefore, if she believes that aggregate capital changes according to the mapping $G$ such that $K' = G(K)$, then knowing aggregate capital today she would be able to project the path of aggregate capital into the future and thus the path for prices. So, we can write the household problem given function $G(\cdot)$ as follows:

$$
\Omega(K, a; G) = \max_{c, a'} u(c) + \beta \Omega(K', a'; G) \quad \text{(RCE)}
$$

s.t. $c + a' = w(K) + R(K)a$

$K' = G(K)$,

$c \geq 0$

The above problem is the problem of a household that sees $K$ in the economy, has a belief $G$ about its evolution, and carries $a$ units of assets from past. The solution of this problem yields policy functions $c(K, a; G)$ for consumption and $g(K, a; G)$ for next period asset holdings, as well as a value function $\Omega(K, a; G)$. The price functions $w(K), R(K)$ are obtained from the firm’s FOCs (below).

$$
\begin{align*}
\quad u_c(c(K, a; G)) &= \beta \Omega_w(G(K), g(K, a; G); G) \\
\quad \Omega_a(K, a; G) &= R(K) u_c(c(K, a; G))
\end{align*}
$$

Now we can define the Recursive Competitive Equilibrium.

**Definition 2** A Recursive Competitive Equilibrium with arbitrary expectations $G$ is a set of functions $\Omega, g : K \times A \to \mathbb{R},$ and $R, w, H : K \to \mathbb{R}_+$ such that\footnote{Note that we could add the policy function for consumption $c(K, a; G)$.}
1. Given $G, w, R, \Omega, g$ solves the household problem in (RCE),

2. $K' = H(K; G) = g(K, K; G')$ (representative agent condition),

3. $w(K) = F_a(K, 1)$, and

4. $R(K) = F_k(K, 1)$.

Note that $G$ are some arbitrary expectations and do not have to necessarily be rational. Next, we define another notion of equilibrium where the expectations of the households are consistent with what happens in the economy:

**Definition 3** A Rational Expectations Recursive Competitive Equilibrium (REE) is a set of functions $\Omega, g, R, w, G^*$, such that:

1. Given $w, R, \Omega(K, a; G^*), g(K, a; G^*)$ solves HH problem in (RCE),

2. $K' = G^*(K) = g(K, K; G^*)$,

3. $w(K) = F_a(K, 1)$, and

4. $R(K) = F_k(K, 1)$.

What this means is that in a REE, households optimize given what they believe is going to happen in the future and what happens in the aggregate is consistent with the household’s decision. The proof that every REE can be used to construct a SME is left as an exercise. The reverse turns out not to be true. Notice that in a REE, function $G^*$ projects next period’s aggregate capital. In fact, if we construct an equilibrium path based on a REE, once a level of aggregate capital is reached in some period, then next period aggregate capital is uniquely pinned down by the transition function $G^*$. If we have multiplicity of SME, this would imply that we cannot construct the function $G^*$ since one value of capital today could imply more than one value of capital tomorrow. From now on, we will focus on REE unless otherwise stated.
Remark 1 Note that unless otherwise stated, we will assume that the capital depreciation rate $\delta$ is 1, with the firm’s profits given by $F(K, 1) - \delta K - r(K)K - w(K)$. $R(K)$ is the gross rate of return on capital, which is given by $F_k(K, 1) + 1 - \delta$. The net rate of return on capital is $r(K) = F_k(K, 1) - \delta$.

3.2 The Envelope Theorem and the Functional Euler equation

To solve for the RCE and, in particular, to derive the household’s optimality conditions we use envelope theorem. This method is valid because of time consistency of consumption choice.

Take the household’s problem given by

$$V(K, a) = \max_{c, a'} u(c) + \beta V(K', a')$$

s.t. $c + a' = w(K) + R(K)a$

$$K' = G(K)$$

$$c \geq 0$$

with decision rules for consumption and next period asset holdings given by $c = c(K, a)$ and $a' = g(K, a)$.

By taking the first-order conditions (assuming an interior solution since $u$ is well behaved), we get:

$$-u_c(c) + \beta V_{a'}(K', a') = 0,$$

which evaluated at the optimum is

$$-u_c(w(K) + R(K)a - g(K, a)) + \beta V_{a'}(G(K), g(K, a)) = 0$$

(1)

The problem with solving the functional Euler equation is that $V_{a'}$ is not known. However, we can
write the value function as a function of current states and differentiate both sides with respect to $a$.\footnote{Under some assumptions, $V$ is differentiable. See p. 121 of Prof. Krueger’s notes for details.}

Since the Euler equation holds for all $(a, K)$, we have

$$V(K, a) = u(w(K) + R(K)a − g(K, a)) + \beta V(G(K), g(K, a))$$

and using the implicit function theorem we can get its derivative with respect to $a$:

$$V_a(K, a) = u_c(w(K) + R(K)a − g(K, a))R(K) +$$
$$\frac{\partial g(K, a)}{\partial a} \left[-u_c(w(K) + R(K)a − g(K, a)) + \beta V_a(G(K), g(K, a))\right] \quad (3)$$

The term in square brackets in the right hand side is the first-order condition (1) and hence it is zero. So equation (3) simplifies to

$$V_a(K, a) = u_c(w(K) + R(K)a − g(K, a))R(K).$$

Finally, we can replace that in equation (1) and get the functional Euler equation

$$u_c(w(K) + R(K)a − g(K, a)) − \beta u_c(w(G(K)) + R(G(K))g(K, a) − g(G(k, g(K, a)))) R(G(K)) = 0 \quad (4)$$

To illustrate this point, consider an individual who wants to loose weight and decides whether to start diet or not. However, he would rather postpone diet for tomorrow and prefer to eat well today. Let 1 denote that he obeys the diet restrictions and 0 otherwise. Let his preference ordering be given by:

1. $(0, 1, 1, 1...)$
2. $(1, 1, 1, 1...)$
Even though he promises himself that he will start diet tomorrow and chooses to eat well today, tomorrow he will face the same problem. So he will choose the same option again tomorrow. He will thus never start diet and will end up with his least preferred option: (0, 0, 0, 0, …).

However, in our model that is not what happens. Agents’ preferences are time consistent, so what an individual promises today has to be optimal for her tomorrow as well. And that is why we can use the envelope theorem.

### 3.3 Economies with Government Expenditures

#### 3.3.1 Lump-Sum Tax

The government levies each period $T$ units of goods in a lump sum fashion and spends it in a public good, say, medals. Assume however that consumers do not care about medals. The household’s problem is

$$V(K, a) = \max_{c, a'} u(c) + \beta V(K', a')$$

s.t. $c + a' = w(K) + R(K)a - T$

$$K' = G(K)$$

$$c \geq 0$$

Let the solution of this problem be given by policy function $g_a(K, a; M, T)$ and value function $V(K, a; M, T)$. The equilibrium can be characterized by $G^*(K; M, T) = g_a(K, K; G^*, M, T)$ and $M^* = T$ (the government budget constraint is balanced period by period). We will write a complete definition of equilibrium for a version with government debt (below).

**Exercise 4** Define the aggregate resource constraint as $C + K' + M = f(K, 1)$ for the planner. Show
that the equilibrium is optimal when consumers do not care about medals.

Note that if households cared about medals, then the equilibrium would not necessarily be optimal. The social planner would equate the marginal utility of consumption and of medals, while the agent would not.

3.3.2 Labor Income Tax

We have an economy in which the government levies a tax on labor income in order to purchase medals. Medals are goods that provide utility to the consumers.

\[
V(K, a) = \max_{c, a'} u(c, M) + \beta V(K', a')
\]

t.s. \[c + a' = (1 - \tau(K')) w(K) + R(K) a \]
\[
K' = G(K)
\]
\[
c \geq 0
\]

with \(M = \tau(K) w(K)\).

Since leisure is not valued, the labor decision is trivial. Hence, there is no distortion due to taxes and the CE is Pareto optimal.

**Exercise 5** Is there any change in the above implications of optimality if the tax rate is a function of aggregate capital?

**Exercise 6** Suppose medals do not provide utility to agents but leisure does. Is the CE optimal now? Is it distorted? What if medals also provide utility?
3.3.3 Capital Income Tax

Now let us look at an economy in which the government levies tax on capital in order to purchase medals. Medals provide utility to the consumers.

\[
V(K, a) = \max_{c, a'} u(c, M) + \beta V(K', a')
\]

s.t. \[ c + a' = w(K) + a \left[ 1 + r(K) (1 - \tau(K)) \right] \]
\[ K' = G(K) \]
\[ c \geq 0 \]

with \( M = \tau(K)r(K)K \) and \( R(K) = 1 + r(K) \). Now, the First Welfare Theorem is no longer applicable and the CE will therefore not be Pareto optimal anymore (if \( \tau(K) > 0 \) there will be a wedge, and the efficiency conditions will not be satisfied).

**Exercise 7** Derive the first order conditions in the above problem to see the wedge introduced by taxes.

3.3.4 Taxes and Debt

Assume that the government can now issue debt and use taxes to finance its expenditures. Also assume that agents derive utility from these government expenditures.

A government policy consists of capital taxes, spending (medals) as well as bond issuance. When the aggregate states are \( K \) and \( B \), as you will see why, then a government policy (in a recursive world) is

\[
\tau(K, B), M(K, B) \text{ and } B'(K, B).
\]

For now, we shall assume these values are chosen so that the equilibrium exists. In this environment, debt issued is relevant for the household because it permits him to correctly infer the amount of taxes. Therefore the household needs to form expectations about the future level of debt from the government.
The government budget constraint now satisfies (with taxes on labor income):

\[ B + M(K, B) = \tau(K, B)R(K)K + q(K, B)B'(K, B) \]

Notice that the household does not care about the composition of his portfolio as long as assets have the same rate of return, which is true because of the no arbitrage condition.

The problem of a household with assets \( a \) is given by:

\[
V(K, B, a) = \max_{c, a'} u(c, M(K, B)) + \beta V(K', B', a')
\]

s.t. \( c + a' = w(K) + aR(K)(1 - \tau(K, B)) \)

\[
K' = G(K, B)
\]

\[
B' = H(K, B)
\]

\[
c \geq 0
\]

Let \( g(K, B, a) \) be the policy function associated with this problem. Then, we can define a RCE as follows.

**Definition 4** A Rational Expectations Recursive Competitive Equilibrium, given policies \( M(K, B) \) and \( \tau(K, B) \), is a set of functions \( V, g, G, H, w, \) and \( R \), such that

1. Given \( w \) and \( R \), \( V \) and \( g \) solve the household’s problem,

2. Factor prices are paid their marginal productivities

\[
w(K) = F_2(K, 1) \text{ and } R(K) = F_1(K, 1),
\]

3. Household wealth = Aggregate wealth

\[
g(K, B, K + q(K^-, B^-)B) = G(K, B) + q(K, B)H(K, B),
\]
4. No arbitrage condition

\[
\frac{1}{q(K,B)} = [1 - \tau(G(K,B), H(K,B))] R(G(K)),
\]

5. Government’s budget constraint holds

\[
B + M(K,B) = \tau(K,B) R(K) K + q(K,B) H(K,B),
\]

6. Government debt is bounded; i.e. \( \exists \) some \( \bar{B} \), such that for all \( K \in [0,\bar{k}) \) and \( B \leq \bar{B} \),

\[
H(K,B) \leq \bar{B}.
\]

4 Some Other Examples

4.1 A Few Popular Utility Functions

Consider the following three utility forms:

1. \( u(c, c^-) \): this function is called habit formation utility function. The utility is increasing in consumption today, but decreasing in the deviations from past consumption (e.g. \( u(c, c^-) = v(c) - (c - c^-)^2 \)). Under habit persistence, an increase in current consumption lowers the marginal utility of consumption in the current period \( (u''_{1,1} < 0) \) and increases it in the next period \( (u''_{1,2} > 0) \). Intuitively, the more the agent eats today, the hungrier she will be tomorrow. The aggregate state in this setup is \( K \), while the individual states are \( a \) and \( c^- \).

Definition 5 A Recursive Competitive Equilibrium is a set of functions \( V, g, G, w, \) and \( R, \) such that

(a) Given \( w \) and \( R, V \) and \( g \) solve the household’s problem,
(b) Factor prices are paid their marginal productivities

\[ w(K) = F_2(K, 1) \text{ and } R(K) = F_1(K, 1), \]

(c) Household wealth = Aggregate wealth

\[ g(K, K, F^{-1}(G^{-1}(K), 1) - K) = G(K). \]

**Exercise 8** Is the equilibrium optimum in this case?

2. \( u(c, C^-) \): this form is called catching up with Jones. There is an externality from aggregate consumption to the agent’s payoff. Intuitively, agents care about what their neighbors consume. The aggregate states in this case are \( K \) and \( C^- \), while \( c^- \) is no longer an individual state.

**Exercise 9** How does the agent know \( C^- \)?

**Exercise 10** Is the equilibrium optimum in this case?

3. \( u(c, C) \): this form is called keeping up with Jones. The aggregate state is \( K \) and \( C \) is no longer a predetermined variable.

**Exercise 11** How does the agent know \( C \)?

**Exercise 12** Is the equilibrium optimum in this case?

### 4.2 An Economy with Capital and Land

Consider an economy with capital and land but without labor. A firm in this economy buys and installs capital, and owns one unit of land that is used in production, according to the technology \( F(K, L) \). In other words, a firm is a “chunk of land of area one” (e.g. farmland), in which it installs its own capital (e.g. tractors). The firm’s shares are traded in a stock market, which are bought by households.
A household’s problem in this economy is given by:

\[
V(K, a) = \max_{c, a'} \ u(c) + \beta V(K', a') \\
\text{s.t. } c + P(K)d' = a [D(K) + P(K)] \\
K' = G(K)
\]

where \( a \) are shares held by the household, \( P(K) \) is their price, and \( D(K) \) are dividends per share.

The firm’s problem is given by

\[
\Omega(K, k) = \max_{d, k'} d + q(K')\Omega(K', k') \\
\text{s.t. } f(k', 1) = d + k' \\
K' = G(K)
\]

\( \Omega \) here is the \textit{value of the firm}, measured in units of output today. The value of the firm tomorrow must be discounted into units of output today, which is done by the discount factor \( q(K') \). Note that the firm needs to know \( K' \), using the aggregate law of motion \( G \) to do so.

\textbf{Definition 6} A \textit{Recursive Competitive Equilibrium} consists of functions, \( V, \Omega, h, g, d, q, D, P, \) and \( G \) so that:

1. Given prices, \( V \) and \( h \) solve the household’s problem,

2. \( \Omega, g, \) and \( d \) solve the firm’s problem,

3. Representative household holds all shares of the firm

   \[ g(K, 1) = 1, \]

4. The capital of the firm when it is representative must equal the aggregate stock of capital

   \[ h(K, K) = G(K), \]
5. Value of a representative firm must equal its price and dividends

\[ \Omega(K, K) = D(K) + P(K), \]

6. The dividends of the representative firm must equal aggregate dividends

\[ d(K, K) = D(K) \]

Exercise 13 One condition is missing in the definition of the RCE above. Find it! [Hint: it relates the discount factor of the firm \( q(G(K)) \) with the price and dividends households receive \((P(K), P(G(K)), \) and \( D(G(K)))).\]

Exercise 14 Define the RCE if \( a \) were savings paying \( R(K) \) as opposed to shares of the firm.

5. Adding Heterogeneity

In the previous section we looked at situations in which recursive competitive equilibria (RCE) were useful. In particular these were situations in which the welfare theorems failed and so we could not use the standard dynamic programming techniques learned earlier. In this section we look at another way in which RCE are helpful, in particular in models with heterogeneous agents.

5.1 Heterogeneity in Wealth

First, let us consider a model in which we have two types of households that differ only in the amount of wealth they own. Say there are two types of agents, labeled type \( R \) (for rich) and \( P \) (for poor), of measure \( \mu \) and \( 1 - \mu \) respectively. Agents are identical other than their initial wealth position and
there is no uncertainty in the model. The problem of an agent with wealth \(a\) is given by

\[
V(K^R, K^P, a) = \max_{c,a'} u(c) + \beta V(K^{R'}, K^{P'}, a') \\
\text{s.t.} \quad c + a' = w(\mu K^R + (1 - \mu) K^P) + aR(\mu K^R + (1 - \mu) K^P) \\
K^{i'} = G^i(K^R, K^P) \quad \text{for } i = R, P.
\]

**Remark 2** Note that (in general) the decision rules of the two types of agents are not linear (even though they might be almost linear); therefore, we cannot add the two states, \(K^1\) and \(K^2\), to write the problem with one aggregate state, in the recursive form.

**Definition 7** A Recursive Competitive Equilibrium is a set of functions \(V, g, w, R, G^1, \text{ and } G^2\) such that that:

1. Given prices, \(V\) solves the household’s functional equation, with \(g\) as the associated policy function,

2. \(w\) and \(R\) are the marginal products of labor and capital, respectively (watch out for arguments!),

3. Consistency: representative agent conditions are satisfied, i.e.

\[
g(K^R, K^P, K^R) = G^R(K^R, K^P),
\]

and

\[
\]

**Remark 3** Note that \(G^R(K^R, K^P) = G^P(K^P, K^R)\) (look at the arguments carefully). Why? (How are rich and poor different?)

**Remark 4** This is a variation of the simple neoclassical growth model. What does the neoclassical growth model say about inequality? In the steady state, the Euler equations for the two different types
simplify to

\[ u'(c^R) = \beta Ru'(c^R), \text{ and } u'(c^{P^*}) = \beta Ru'(c^{P^*}). \]

and we thus have \( \beta R = 1 \), where

\[ R = F_K (\mu K^R + (1 - \mu)K^{P^*}, 1). \]

Finally, by the household’s budget constraint, we must have:

\[ c^i + a^i = w + a^i R \quad \text{for } i = R, P \]

where \( a^i = K^i \) by the representative agent’s condition. Therefore, we have three equations (budget constraints and Euler equation) and four unknowns \((a^i, c^i)\) for \( i = R, P \). This implies that this theory is silent about the distribution of wealth in the steady state!

This is an important implication of the aggregation property. In fact, in the neoclassical growth model with \( n \) agents that only differ in their initial endowments, with homothetic preferences, there is a continuum with dimension \( n - 1 \) of steady state wealth distributions.

As we will see throughout the course, heterogeneity will matter in various situations. In the setup we have discussed above, however, wealth heterogeneity did not matter. This aggregation property applied to our macroeconomic context (see Gorman’s aggregation theorem for further details) states that if agents’ individual savings decision is linear in their individual state (i.e. \( g(K, a) = \mu^i(K) + \lambda(K)a \), with \( \lambda(K) \) being the marginal propensity to save common to all agents) provided that they all have the same preferences, then aggregate capital can be expressed as the choice of a representative agent (with savings decision given by \( g(K, K) = \bar{\mu}(K) + \lambda(K)K \)).

**Remark 5** Does this property hold when discount factors or coefficients of relative risk aversion are heterogeneous?
5.2 Heterogeneity in Skills

Now, consider a slightly different economy in which type $i$ has labor skill $\epsilon_i$. Measures of agents' types, $\mu_1$ and $\mu_2$, satisfy $\mu_1\epsilon_1 + \mu_2\epsilon_2 = 1$ (below we will consider the case in which $\mu_1 = \mu_2 = 1/2$).

The question we have to ask ourselves is: would the value functions of the two types remain the same, as in the previous subsection? The answer turns out to be no!

The problem of the household $i \in \{1, 2\}$ can be written as follows:

$$V^i(K^1, K^2, a) = \max_{c,a'} \left\{ u(c) + \beta V^i(K^{1'}, K^{2'}, a') \right\}$$

s.t. $c + a' = w\left(\frac{K^1 + K^2}{2}\right)\epsilon_i + aR\left(\frac{K^1 + K^2}{2}\right)$

$K^i = G^i(K^1, K^2)$ for $i = 1, 2$.

Notice that we have indexed the value function by the agent’s type and thus the policy function is also indexed by $i$. The reason is that the marginal product of the labor supplied by each of these types is different (think of $w^i\left(\frac{K^1 + K^2}{2}\right) = w\left(\frac{K^1 + K^2}{2}\right)\epsilon_i$).

**Exercise 15** Define the RCE.

**Remark 6** We can also rewrite this problem as

$$V^i(K, \lambda, a) = \max_{c,a'} \left\{ u(c) + \beta V^i(K', \lambda', a') \right\}$$

s.t. $c + a' = R(K)a + W(K)\epsilon_i$

$K = G(K, \lambda)$

$\lambda' = H(K, \lambda)$,

where $K$ is the total capital in this economy, and $\lambda$ is the share of one type in total wealth (e.g. type 1).
Then, if $g^i$ is the policy function of type $i$, then the consistency conditions of the RCE must be:

$$G(K, \lambda) = \frac{1}{2} \left[ g^1(K, \lambda, 2\lambda K) + g^2(K, \lambda, 2(1 - \lambda)K) \right],$$

and

$$H(K, \lambda) = \frac{g^1(K, \lambda, 2\lambda K)}{2G(K, \lambda)}.$$

5.3 An International Economy Model

In an international economy model the definition of country is an important one. We can introduce
the idea of different locations or geography, countries can be victims of different policies, trade across
countries maybe more difficult due to different restrictions.

Here we will focus on a model with two countries, 1 and 2, where labor is not mobile between the
countries, but capital markets perfect and thus investment can flow freely across countries. However,
in order to use it in production, it must have been installed in advanced. Traded goods flow within the
period.

The aggregate resource constraint is:

$$C^1 + C^2 + K^1' + K^2' = F(K^1, 1) + F(K^2, 1)$$

Suppose that there is a mutual fund that owns the firms in each country and chooses labor in each
country and capital to be installed. Its shares are traded in the market and thus, as in the economy
with capital and land, individuals own shares of this mutual fund.

The first question to ask, as usual, is what are the appropriate states in this world? As it is apparent
from the resource constraint and production functions, we need the capital in each country. Moreover,
we need to know total wealth in each country. Therefore, we need an additional variable as the
aggregate state: the shares owned by country 1 is a sufficient statistic.

We can then write the country $i$'s household problem as:

$$V^i(K^1, K^2, A, a) = \max_{c, a'} u(c) + \beta V^i(K^{1'}, K^{2'}, A', a')$$

s.t.

$$c + Q(K^1, K^2, A)a' = w^i(K^i) + a\Phi(K^1, K^2, A)$$

$$K^{i'} = G^i(K^1, K^2, A), \text{ for } i = 1, 2$$

$$A' = H(K^1, K^2, A)$$

where $A$ is the total amount of shares in the mutual fund that individuals in country 1 own and $a$ is the amount of shares that an individual owns in country $i$.

Since labor is immobile and capital is installed in advanced, the wage is country-specific and is simply given by the marginal product of labor: $w^i(K^i) = F^i_N(K^i, 1)$.

Now let's look at the problem of the mutual fund:

$$\Phi(K^1, K^2, A, k^1, k^2) = \max_{k^{1'}, k^{2'}, n^1, n^2} \sum_i \left[ F^i(k^i, n^i) - n^i w^i(K_i) - k^{i'} \right] + \frac{1}{R(K^{1'}, K^{2'}, A)} \Phi(K^{1'}, K^{2'}, A', k^{1'}, k^{2'})$$

s.t.

$$K^{i'} = G^i(K^1, K^2, A), \text{ for } i = 1, 2$$

$$A' = H(K^1, K^2, A)$$

**Definition 8** A Recursive Competitive Equilibrium for the (world’s) economy is a list of functions, \{\{V^i, h^i, g^i, n^i, w^i, G^i\}_{i=1,2}, \Phi, H, Q, and R\}, such that the following conditions hold:

1. Given prices, $V^i$ and $h^i$ solve the household's problem in country $i$ (for $i \in \{1, 2\}$),

2. Given prices, $\Phi, \{g^i, n^i\}_{i=1,2}$ solves the mutual fund problem,
3. Labor markets clear

\[ n^i(K^1, K^2, A, K^1, K^2) = 1 \quad \text{for } i = 1, 2, \]

4. Consistency (MF)

\[ g^i(K^1, K^2, A, K^1, K^2) = G^i(K^1, K^2, A) \quad \text{for } i = 1, 2, \]

5. Consistency (Households)

\[ h^1(K^1, K^2, A, A) = H(K^1, K^2, A) \]

and

\[ h^1(K^1, K^2, A, A) + h^2(K^1, K^2, A, 1 - A) = 1, \]

6. \( Q(K^1, K^2, A) = \frac{1}{R(K^{1'}, K^{2'}, A')} \Phi(K^{1'}, K^{2'}, A'). \)

**Exercise 16** Solve for the mutual fund’s decision rules. Is next period capital in each country chosen by the mutual fund priced differently? What about labor?

## 6 Stochastic Economies

### 6.1 A Review

#### 6.1.1 Markov Processes

From now on, we will focus on stochastic economies, in which productivity shocks affects the economy. The stochastic process for productivity that we assume is a first-order Markov Process that takes on a
finite number of values in the set $Z = \{z^1 < \cdots < z^{n_z}\}$. A first order Markov process implies

$$\Pr(z_{t+1} = z^j|h_t) = \Gamma_{ij}, \quad z_t(h_t) = z^i$$

where $h_t$ is the history of previous shocks. $\Gamma$ is a Markov chain with the property that the elements of each row sum to 1.

Let $\mu$ be a probability distribution over initial states, i.e.

$$\sum_i \mu_i = 1$$

and $\mu_i \geq 0 \forall i = 1, ..., n_z$.

For next periods the probability distribution can be found by $\mu' = \Gamma^T \mu$.

If $\Gamma$ is “nice” then $\exists$ a unique $\mu^*$ s.t. $\mu^* = \Gamma^T \mu^*$ and $\mu^* = \lim_{m \to \infty} (\Gamma^T)^m \mu_0, \forall \mu_0 \in \Delta^i$.

$\Gamma$ induces the following probability distribution conditional on the initial draw $z_0$ on $h_t = \{z^0, z^1, ..., z^t\}$:

$$\Pi(\{z^0, z_1\}) = \Gamma_{i,i}, \quad \text{for } z^0 = z_i.$$

$$\Pi(\{z^0, z_1, z_2\}) = \Gamma^T \Gamma_{i,i}, \quad \text{for } z^0 = z_i.$$

Then, $\Pi(h_t)$ is the probability of history $h_t$ conditional on $z^0$. The expected value of $z'$ is $\sum_{z'} \Gamma_{zz'} z'$ and $\sum_{z'} \Gamma_{zz'} = 1$.

### 6.1.2 Problem of the Social Planner

Let productivity affect the production function in a multiplicative fashion; i.e. technology is $zF(K, N)$, where $z$ is a shock that follows a Markov chain on a finite state-space. Recall that the problem of the
social planner problem (SPP) in sequence form is

$$\max \left\{ \sum_{t=0}^{\infty} \sum_{z_t} \beta^t \pi(z_t) u(c_t(z_t)) \right\},$$

subject to

$$c_t(z_t) + k_{t+1}(z_t) = z_t F(k_t(z_t-1), 1),$$

where $z_t$ is the realization of the shock in period $t$, and $z^t$ is the history of shocks up to (and including) time $t$. $X(z^t)$ is similar to the consumption possibility set defined earlier but this is after history $z^t$ has occurred and is for consumption and next period capital.

We can then formulate the stochastic SPP in a recursive fashion as

$$V(z_i, K) = \max_{c,K'} \left\{ u(c) + \beta \sum_j \Gamma_{ij} V(z_j, K') \right\},$$

subject to

$$c + K' = z_i F(K, 1),$$

where $\Gamma$ is the Markov transition matrix. The solution to this problem gives us a policy function of the form $K' = G(z, K)$.

In a decentralized economy, the Arrow-Debreu equilibrium can be defined by:

$$\max \left\{ \sum_{t=0}^{\infty} \sum_{z_t} \beta^t \pi(z_t) u(c_t(z_t)) \right\},$$

subject to

$$\sum_{t=0}^{\infty} \sum_{z_t} p_t(z_t).x_t(z_t) \leq 0,$$

where $X(z^t)$ is again a variant of the consumption possibility set after history $z^t$ has occurred. Ignore the overloading of notation. Note that we are assuming the markets are dynamically complete; i.e. there is a complete set of securities for every possible history.
By the same procedure as before, the SME can be written in the following way:

$$\max \left\{ \sum_{t=0}^{\infty} \beta^t \pi(c_t(z^t)) \right\}$$

$s.t.$

$$c_t(z^t) + k_{t+1}(z^t) + \sum_{z_{t+1}} q_t(z^t, z_{t+1}) b_{t+1}(z^t, z_{t+1})$$

$$= k_t(z^{t-1}) R_t(z^t) + w_t(z^t) + b_t(z^{t-1}, z_t)$$

$$b_{t+1}(z^t, z_{t+1}) \geq -B.$$ 

To replicate the AD equilibrium, we have introduced Arrow securities to allow agents to trade with each other against possible future shocks.

Note that when there is no heterogeneity, there will be no trade in equilibrium, i.e \( b_{t+1}(z^t, z_{t+1}) = 0 \) for any \( z^t, z_{t+1} \). Moreover, we have two ways of delivering the goods specified in an Arrow security contract: after production and before production. In an after production setting, the goods will be delivered after production takes place and can only be consumed or saved for the next period. This is the above setting. It is also possible to allow the consumer to rent the Arrow security income as capital to firms, which will correspond to the before production setting.

An important condition that must hold true in the before production setting is the no-arbitrage condition:

$$\sum_{z_{t+1}} q_t(z^t, z_{t+1}) = 1$$

**Exercise 17** Every equilibrium achieved in AD settings can also be achieved in a SM setting, by the relation where

$$q_t(z^t, z_{t+1}) = p_{1t+1}(z^t, z_{t+1})/p_{1t}(z^t),$$

$$R_t(z^t) = p_{2t}(z^t)/p_{1t}(z^t).$$
and

\[ w_t(z') = p_{3t}(z') / p_{1t}(z'). \]

Check from the FOC’s that the we get the same allocations in the two settings.

**Exercise 18** The problem above assumes state contingent goods are delivered in terms of consumption goods. Instead of this assume they are delivered in terms of capital goods. Show that the same allocation would be achieved in both settings.

### 6.1.3 Recursive Competitive Equilibrium

Assume that households can trade state contingent assets, as in the sequential markets case above. Then, we can write a household’s problem in recursive form as:

\[
V(K, z, a) = \max_{c, k', b(z')} u(c) + \beta \sum_{z'} \Gamma_{zz'} V(K', z', a'(z'))
\]

s.t. \[ c + k' + \sum_{z'} q_{zz'}(K, z) b(z') = w(K, z) + aR(K, z) \]

\[ K' = G(K, z) \]

\[ a'(z') = k' + b(z'). \]

**Exercise 19** Write the FOC’s for this problem, given prices and the law of motion for aggregate capital.

**Definition 9** A Recursive Competitive Equilibrium is a collection of functions \( V, k', d, G, w, \) and \( R, \) so that

1. Given \( G, w, \) and \( R, \) \( V \) solves the household’s functional equation, with \( k' \) and \( b \) as the associated policy function,

2. \( b(K, z, K; z') = 0, \) for all \( z', \)
3. \( k'(K, z, K) = G(K, z) \),

4. \( w(K, z) = zF_n(K, 1) \) and \( R(K, z) = zF_k(K, 1) \),

5. and \( \sum_{z'} q_{z'}(K, z) = 1 \).

The last condition is known as the no-arbitrage condition (recall that we had this equation in the case of sequential markets as well). To see why this is a necessary equation in the equilibrium, note that an agent can either save in the form of capital or through Arrow securities. However, these two choices must cost the same, which implies Condition 5 above.

**Remark 7** Note that in the SME version of the household problem, in order for households not to achieve infinite consumption, we need a no-Ponzi condition. Such condition is

\[
\lim_{t \to \infty} \frac{a_t}{\prod_{s=0}^{t} R_s} < \infty.
\]

This is the weakest condition that imposes no restrictions on the first order conditions of the household’s problem. It is harder to come up with its analogue for the recursive case. One possibility is to assume that \( a' \) lies in a compact set \( A \), or a set that is bounded from below.

### 6.2 An International Economy Model with Shocks

We revisit the international economy model studied before and we now add country-specific shocks. Let \( z_1 \) and \( z_2 \) represent productivity shocks in country 1 and 2, respectively. The aggregate state variables are now the productivity shocks, the aggregate stocks of capital in each country, and the amount of shares owned by country 1 in the mutual fund.

---

4 We must specify \( \mathcal{A} \) such that the borrowing constraint implicit in \( \mathcal{A} \) is never binding.
The problem of an household in country $i$ is:

$$V^i(z_1, z_2, K_1, K_2, A, a) = \max_{c, a'} u(c) + \beta \sum_{\tilde{z}} \Gamma_{\tilde{z}} V^i(\tilde{z}', \tilde{K}', A'(\tilde{z}'), a'(\tilde{z}'))$$

s.t. $c + \sum_{\tilde{z}} q(\tilde{z}, \tilde{K}, A, z') a'(\tilde{z}') = w^i(z_i, K_i) + a \Phi(\tilde{z}, \tilde{K}, A)$

$$K'_i = G_i(\tilde{z}, \tilde{K}, A), \quad \text{for } i = 1, 2$$

$$A(\tilde{z}') = H(\tilde{z}, \tilde{K}, A, \tilde{z}') \quad \forall \tilde{z}'$$

Let decision rule for next period asset holdings be $a'(\tilde{z}') = h(\tilde{z}, \tilde{K}, A, a, \tilde{z}') \quad \forall \tilde{z}'$. Note the financial market structure assumed here. As before, labor is immobile and thus wages are country-specific and given by $w^i(z_i, K_i) = z_i F_N(K_i, 1)$.

**Exercise 20** Write this economy with state-contingent claims in own country only.

**Exercise 21** Write this economy where individuals can move freely in advance, but with incomplete markets.

Now let’s look at the net present value of the mutual fund in equilibrium:

$$\Phi(\tilde{z}, \tilde{K}, A) = \sum_{z_i} [z_i F(K_i, 1) - w^i(z_i, K_i)] - \sum_i G_i(\tilde{z}, \tilde{K}, A) +$$

$$+ \sum_{\tilde{z}} \Gamma_{\tilde{z}} Q(\tilde{z}', G(\tilde{z}, \tilde{K}, A), H(\tilde{z}, \tilde{K}, A, \tilde{z}')) \Phi(\tilde{z}', G(\tilde{z}, \tilde{K}, A), H(\tilde{z}, \tilde{K}, A, \tilde{z}'))$$

(5)

where $Q$ represents intertemporal prices, which in equilibrium should satisfy $\forall \tilde{z}_'$:

$$q(\tilde{z}, \tilde{K}, A, \tilde{z}') = Q(\tilde{z}', G(\tilde{z}, \tilde{K}, A), H(\tilde{z}, \tilde{K}, A, \tilde{z}')) \Phi(\tilde{z}', G(\tilde{z}, \tilde{K}, A), H(\tilde{z}, \tilde{K}, A, \tilde{z}'))$$

**Exercise 22** There is one more condition for $G_i$ that equates expected return in each country. What is it?
Definition 10 A Recursive Competitive Equilibrium for the (world’s) economy is a set of functions $V^i$, $h^i$, $w^i$, $G_i$ for $i \in \{1, 2\}$, and $q$, $H$, $Q$, and $\Phi$ such that the following conditions hold:

1. Given prices and laws of motion, $V^i$ and $h^i$ solve the household’s problem in country $i$ for $i \in \{1, 2\}$,

2. The representative agent condition must hold:
   \[ h^1(\vec{z}, \vec{K}, A, \vec{A}, \vec{z}') = H(\vec{z}, \vec{K}, A, \vec{A}, \vec{z}') \quad \forall \vec{z}', \]

3. The sum of shares in the mutual fund must be 1:
   \[ h^1(\vec{z}, \vec{K}, A, \vec{A}, \vec{z}') + h^2(\vec{z}, \vec{K}, A, 1-A, \vec{z}') = 1 \quad \forall \vec{z}', \]

4. The mutual fund’s value $\Phi$ satisfies equation 5

5. $w^i(z_i, K_i)$ is equated to the marginal products of labor in each country $i$ for $i \in \{1, 2\}$,

6. Expected rate of return on capital is the same across countries,

7. $q(\vec{z}, \vec{K}, A, \vec{z}') = Q(\vec{z}', G(\vec{z}, \vec{K}, A), H(\vec{z}, \vec{K}, A, \vec{z}'))\Phi(\vec{z}', G(\vec{z}, \vec{K}, A), H(\vec{z}, \vec{K}, A, \vec{z}')) \quad \forall \vec{z}',$

8. The aggregate resource constraint must hold:
   \[
   \sum_i \left[ z_i F(K_i, 1) - G_i(\vec{z}, \vec{K}, A) - \left( w^i(z_i, K_i) + A_i \Phi(\vec{z}, \vec{K}, A) - \sum_{\vec{z}'} q(\vec{z}, \vec{K}, A, \vec{z}') h^i(\vec{z}, \vec{K}, A, A_i, \vec{z}') \right) \right] = 0
   \]

   where $A_1 = A$ and $A_2 = 1 - A$.

6.3 Heterogeneity in Wealth and Skills with Complete Markets

Now, let us consider a model in which we have two types of households, with equal measure $\mu_i = 1/2$, that care about leisure, but differ in the amount of wealth they own as well as their labor skill. There
is also uncertainty and Arrow securities like we have seen before.

Let \( A^1 \) and \( A^2 \) be the aggregate asset holdings of the two types of agents. These will now be state variables for the same reason \( K^1 \) and \( K^2 \) were state variables earlier. The problem of an agent \( i \in \{1, 2\} \) with wealth \( a \) is given by

\[
V^i (z, A^1, A^2, a) = \max_{c, n, a'} u(c, n) + \beta \sum_{z'} \Gamma_{zz'} V^i \left( z', A^1(z'), A^2(z'), a'(z') \right)
\]

s.t. \( c + \sum_{z'} q(z, A^1, A^2, z') a'(z') = R(z, K, N) a + W(z, K, N) \epsilon_i n \)

\( A^i(z') = G^i(z, A^1, A^2) \), for \( i = 1, 2, \forall z' \)

\( N = H(z, A^1, A^2) \)

\( K = \frac{A^1 + A^2}{2} \).

Let \( g^i(z, A^1, A^2, a^i) \) and \( h^i(z, A^1, A^2, a^i) \) be the asset and labor policy functions be the solution of each type \( i \) to this problem. Then, we can define the RCE as below.

**Definition 11 A Recursive Competitive Equilibrium with Complete Markets** is a set of functions \( V^i \), \( g^i \), \( h^i \), \( G^i \) for \( i \in \{1, 2\} \), \( R \), \( w \), \( H \), and \( q \), such that:

1. Given prices and laws of motion, \( V^i \), \( g^i \) and \( h^i \) solve the problem of household \( i \) for \( i \in \{1, 2\} \),

2. Labor markets clear:
\[
H(z, A^1, A^2) = \epsilon_1 h^1(z, A^1, A^2, A^1) + \epsilon_2 h^2(z, A^1, A^2, A^2),
\]

3. The representative agent condition:
\[
G^i(z, A^1, A^2, z') = g^i(z, A^1, A^2, A^i, z') \quad \text{for} \quad i = 1, 2, \forall z'
\]

4. The average price of the Arrow security must satisfy:
\[
\sum_{z'} q(z, A^1, A^2, z') = 1
\]

5. \( G^1(z, A^1, A^2, z') + G^2(z, A^1, A^2, z') \) is independent of \( z' \) (due to market clearing).
6. $R$ and $W$ are the marginal products of capital and labor.

**Exercise 23** Write down the household problem and the definition of RCE with non-contingent claims instead of complete markets.

## 7 Asset Pricing: Lucas Tree Model

We now turn to the simplest of all models in term of allocations as they are completely exogenous, called the *Lucas tree model*. We want to characterize the properties of prices that are capable of inducing households to consume the stochastic endowment.

### 7.1 The Lucas Tree with Random Endowments

Consider an economy in which the only asset is a tree that gives fruit. The agent’s problem is to choose consumption $c$ and the amount of shares of the tree to hold $s'$ according to

$$V(z, s) = \max_{c, s'} u(c) + \beta \sum_{z'} \Gamma_{zz'} V(z', s')$$

subject to

$$c + p(z) s' = s [p(z) + d(z)],$$

where $p(z)$ is the price of the shares (to the tree), in state $z$, and $d(z)$ is the dividend associated with state $z$.

**Definition 12** A Rational Expectations Recursive Competitive Equilibrium is a set of functions, $V$, $g$, $d$, and $p$, such that

1. $V$ and $g$ solves the household’s problem given prices,

2. $d(z) = z$, and,
3. \( g(z, 1) = 1, \) for all \( z. \)

To explore the problem further, note that the FOC for the household’s problem imply the equilibrium condition

\[
\begin{align*}
\frac{\partial u_c(c(z, 1))}{\partial z} &= \beta \sum_{z'} \Gamma_{zz'} \left[ \frac{p(z') + d(z')}{p(z)} \right] u_c(c(z', 1)).
\end{align*}
\]

where we have \( u_c(z) := u_c(c(z, 1)). \) Then this simplifies to

\[
\begin{align*}
p(z) u_c(z) &= \beta \sum_{z'} \Gamma_{zz'} u_c(z') \left[ p(z') + z' \right] \quad \forall z.
\end{align*}
\]

**Exercise 24** Derive the Euler equation for household’s problem to show the result above.

Note that this is just a system of \( n_z \) equations with unknowns \( \{p(z_i)\}_{i=1}^{n} \). We can use the power of matrix algebra to solve the system. To do so, let:

\[
p := \begin{bmatrix}
p(z_1) \\
\vdots \\
p(z_n)
\end{bmatrix}_{(n_z \times 1)}
\]

and

\[
u_c := \begin{bmatrix}
u_c(z_1) \\
0 \\
\vdots \\
0 \\
u_c(z_n)
\end{bmatrix}_{(n_z \times n_z)}
\]

Then

\[
u_c . p = \begin{bmatrix}
p(z_1) u_c(z_1) \\
\vdots \\
p(z_n) u_c(z_n)
\end{bmatrix}_{(n_z \times 1)}
\]
and

\[ \mathbf{u_c.z} = \begin{bmatrix} z_1 u_c(z_1) \\ \vdots \\ z_n u_c(z_n) \end{bmatrix}^{(n \times 1)} \]

Now, rewrite the system above as

\[ \mathbf{u_c.p} = \beta \Gamma \mathbf{u_c.z} + \beta \Gamma \mathbf{u_c.p}, \]

where \( \Gamma \) is the transition matrix for \( z \), as before. Hence, the price for the shares is given by

\[ (I_n - \beta \Gamma) \mathbf{u_c.p} = \beta \Gamma \mathbf{u_c.z}, \]

or

\[ \mathbf{p} = (I_n - \beta \Gamma)^{-1} \beta \Gamma \mathbf{u_c.z}, \]

where \( \mathbf{p} \) is the vector of prices that clears the market.

**Exercise 25** How are prices defined when the agent faces taste shocks?

### 7.2 Asset Pricing

Consider our simple model of Lucas tree with fluctuating output. What is the definition of an asset in this economy? It is "a claim to a chunk of fruit, sometime in the future."

If an asset, \( a \), promises an amount of fruit equal to \( a_t(z^t) \) after history \( z^t = (z_0, z_1, \ldots, z_t) \) of shocks, after a set of (possible) histories in \( H \), the price of such an entitlement in date \( t = 0 \) is given by:

\[ p(a) = \sum_t \sum_{z^t \in H} q^0_t(z^t) a_t(z^t), \]
where \( q^0_t (z^t) \) is the price of one unit of fruit after history \( z^t \) in today's "dollars"; this follows from a no-arbitrage argument. If we have the date \( t = 0 \) prices, \( \{ q_t \} \), as functions of histories, we can replicate any possible asset by a set of state-contingent claims and use this formula to price that asset.

To see how we can find prices at date \( t = 0 \), consider a world in which the agent wants to solve

\[
\max_{c_t(z^t)} \sum_{t=0}^{\infty} \beta^t \pi_t(z^t) u(c_t(z^t))
\]

\[
s.t. \sum_{t=0}^{\infty} \sum_{z^t} q^0_t(z^t) c_t(z^t) \leq \sum_{t=0}^{\infty} \sum_{h^t} q^0_t(z^t) z_t.
\]

This is the familiar Arrow-Debreu market structure, where the household owns a tree, and the tree yields \( z \in Z \) amount of fruit in each period. The FOC for this problem imply:

\[
q^0_t(z^t) = \beta^t \pi_t(z^t) \frac{u_c(z_t)}{u_c(z_0)}.
\]

This enables us to price the good in each history of the world and price any asset accordingly.

**Comment 1** What happens if we add state-contingent shares \( b \) into our recursive model? Then the agent’s problem becomes:

\[
V(z, s, b) = \max_{c,s',b'(z')} u(c) + \beta \sum_{z'} \Gamma_{zz'} V(z', s', b'(z'))
\]

\[
s.t. c + p(z)s' + \sum_{z'} q(z, z') b'(z') = s[p(z) + z] + b.
\]

A characterization of \( q \) can be obtained by the FOC, evaluated at the equilibrium, and thus written as:

\[
q(z, z') u_c(z) = \beta \Gamma_{zz'} u_c(z').
\]

We can thus price all types of securities using \( p \) and \( q \) in this economy.

To see how we can price an asset given today's shock is \( z \), consider the option to sell it tomorrow at
price $P$ as an example. The price of such an asset today is

$$\hat{q}(z, P) = \sum_{z'} q(z, z') \max \{P - p(z'), 0\},$$

where the agent has the option not to sell it. The American option to sell at price $P$ either tomorrow or the day after tomorrow is priced as:

$$\tilde{q}(z, P) = \sum_{z'} q(z, z') \max \{P - p(z'), \hat{q}(z', P)\}.$$

Similarly, an European option to buy the asset at price $P$ the day after tomorrow is priced as:

$$\bar{q}(z, P) = \sum_{z'} \sum_{z''} \max \{p(z'') - P, 0\} q(z', z'') q(z, z').$$

Note that $R(z) = [\sum_{z'} q(z, z')^{-1}$ is the gross risk free rate, given today’s shock is $z$. The unconditional gross risk free rate is then given by $R^f = \sum_{z} \mu^s_z R(z)$ where $\mu^s_z$ is the steady-state distribution of the shocks.

The average gross rate of return on the stock market is $\sum_{z} \mu^s_z \sum_{z'} \Gamma_{zz'} \left[\frac{p(z') + z'}{p(z)}\right]$ and the risk premium is the difference between this rate and the unconditional gross risk free rate (i.e. given by $\sum_{z} \mu^s_z \left(\sum_{z'} \Gamma_{zz'} \left[\frac{p(z') + z'}{p(z)}\right] - R(z)\right)$).

Exercise 26 Use the expressions for $p$ and $q$ and the properties of the utility function to show that risk premium is positive.

7.3 Taste Shocks

Consider an economy in which the only asset is a tree that gives fruits. The fruit is constant over time (normalized to 1) but the agent is subject to preference shocks for the fruit each period given by
The agent’s problem in this economy is

\[ V(\theta, s) = \max_{c, s'} \theta u(c) + \beta \sum_{\theta'} \Gamma_{\theta \theta'} V(\theta', s') \]

subject to \( c + p(\theta) s' = s[p(\theta) + d(\theta)] \).

The equilibrium is defined as before. The only difference is that, now, we must have \( d(\theta) = 1 \) since \( z \) is normalized to 1. What does it mean that the output of the economy is constant (fixed at one), but the tastes for this output change? In this setting, the function of the price is to convince agents to keep their consumption constant even in the presence of taste shocks. All the analysis follows through as before once we write the FOC’s characterizing the prices of shares, \( p(\theta) \), and state-contingent prices \( q(\theta, \theta') \).

This is a simple model, in the sense that the household does not have a real choice regarding consumption and savings. Due to market clearing, household consumes what nature provides her. In each period, according to the state of productivity \( z \) and taste \( \theta \), prices adjusts such that household would like to consume \( z \), which is the amount of fruit that the nature provides. In this setup, output is equal to \( z \). If we look at the business cycle in this economy, the only source of output fluctuations is caused by nature. Everyrhing determined by the supply side of the economy and the demand side has indeed no impact on output.

In next section, we are going to introduce search frictions to incorporate a role for the demand side into our model.

8 Endogenous Productivity in a Product Search Model

We will model the situation in which households need to find the fruit before consuming it. Assume that households have to find the tree in order to consume the fruit. Finding trees is characterized by

\footnote{Think of fields in *The Land of Apples*, full of apples, that are owned by firms; agents have to buy the apples. In addition, they have to search for them as well!}
a constant returns to scale (increasing in both arguments) matching function \( M(T,D) \), where \( T \) is the number of trees in the economy and \( D \) is the aggregate shopping effort exerted by households when searching. The probability that a tree finds a shopper is given by \( \frac{M(T,D)}{T} \), i.e. the total number of matches divided by the number of trees. The probability that a unit of shopping effort finds a tree is given by \( \frac{M(T,D)}{D} \), i.e. the total number of matches divided by the economy’s effort level.

Let’s assume that \( M(T,D) \) takes the form \( D^\varphi T^{1-\varphi} \) and denote \( \frac{1}{Q} := \frac{D}{T} \), i.e. the ratio of shoppers per trees, as capturing the market tightness (and thus \( Q = \frac{T}{D} \)). The probability of a household finding a tree is given by \( \Psi_h(Q) := \frac{M(T,D)}{D} = Q^{1-\varphi} \) and thus the higher the number of people searching, the smaller the probability of a household finding a tree. The probability of a tree finding a household is then given by \( \Psi_f(Q) := \frac{M(T,D)}{T} = Q^{-\varphi} \), and thus the higher the number of people searching, the higher the probability of a tree finding a shopper. Note that in this economy the number of trees is constant and equal to one\(^6\).

Let us assume households face a demand side shock \( \theta \) and a supply side shock \( z \). They are follow independent Markov processes with transitional probabilities \( \Gamma_{\theta \theta'} \) and \( \Gamma_{zz'} \), respectively. Households choose the consumption level \( c \), the search effort exerted to get the fruit \( d \), and the shares of the tree to hold next period \( s' \). The household’s problem can be written as

\[
V(\theta, z, s) = \max_{c, d, s'} u(c, d, \theta) + \beta \sum_{\theta', z'} \Gamma_{\theta \theta'} \Gamma_{zz'} V(\theta', z', s')
\] (6)

s.t. \( c + P(\theta, z) s' = P(\theta, z) \left[ s \left( 1 + \hat{R}(\theta, z) \right) \right] \) (7)
\( c = d \Psi_h(Q(\theta, z)) z \). (8)

\(^6\) What does the fact that \( M \) is constant returns to scale imply?

\(^7\) It is easy to find the statements for \( \Psi_h \) and \( \Psi_f \), given the Cobb-Douglas matching function:

\[
\Psi_h(Q) = \frac{D^\varphi T^{1-\varphi}}{D} = \left( \frac{T}{D} \right)^{1-\varphi} = Q^{1-\varphi},
\]

\[
\Psi_f(Q) = \frac{D^\varphi T^{1-\varphi}}{T} = \left( \frac{T}{D} \right)^{-\varphi} = Q^{-\varphi}.
\]

The question is: is Cobb-Douglas an appropriate choice for the matching function, or its choice is a matter of simplicity?
where \( P \) is the price of the tree relative to that of consumption and \( \hat{R} \) is the dividend income (in units of the tree). Note that the equation 7 is our standard budget constraint, while equation 8 corresponds to the shopping constraint.

Note some notation conventions here. \( P(\theta, z) \) is in terms of consumption goods, while \( \hat{R}(\theta, z) \) is in terms of shares of the tree (that’s why we are using the hat). We could also write the household budget constraint in terms of the price of consumption relative to that of the tree. To do so, let’s define \( \hat{P}(\theta, z) = \frac{1}{P(\theta, z)} \) as the price of consumption goods in terms of the tree. Then the budget constraint can be defined as:

\[
c\hat{P}(\theta, z) + s' = s \left( 1 + \hat{R}(\theta, z) \right)
\]

Let’s maintain our notation with \( P(\theta, z) \) and \( \hat{R}(\theta, z) \) from now on. We can substitute the constraints into the objective and solve for \( d \) in order to get the Euler equation for the household. Using the market clearing condition in equilibrium, the problem reduces to one equation and two unknowns, \( P(\theta, z) \) and \( Q(\theta, z) \) (other objects, \( C, D \) and \( \hat{R} \) are known functions of \( P \) and \( Q \), and the amount shares of the tree in equilibrium is 1 as before). We thus still need another functional equation to solve for the equilibrium of this economy, i.e. we need to specify the search protocol. We now turn to one way of doing so.

**Exercise 27** Derive the Euler equation of the household from the problem defined above.

### 8.1 Competitive Search

Competitive search is a particular search protocol of what is called non-random (or directed) search. To understand this protocol, consider a world consisting of a large number of islands. Each island has a sign that displays two numbers, \( P(\theta, z) \) and \( Q(\theta, z) \). \( P(\theta, z) \) is the price on the island and \( Q(\theta, z) \) is a measure of market tightness in that island (or if the price is a wage rate \( W \), then \( Q \) is the number of workers on the island divided by the number of job opportunities in that island). Both individuals and firms have to decide to go to one island. For instance, in an island with a higher wage, the worker
might have a higher income conditional on finding a job. However, the probability of finding a job might be low on that island given the tightness of the labor market on that island. The same story holds for the job owners, who are searching to hire workers.

In our economy, both firms and workers search for specific markets indexed by price $P$ and a market tightness $Q$. An island, or a pair of $(P, Q)$, is operational if there exists some consumer and firm choosing that market. Therefore, an agent should choose $P$ and $Q$ such that it gives sufficient profit to the firm, so that it wants to be in that island as opposed to doing something else, which will be determined in the equilibrium. Competitive search is magic in the sense that it does not presuppose a particular pricing protocol that other search protocols need (e.g. bargaining).

Maintaining the demand shock $\theta$ and supply side shock $z$ we introduced before, we can then define the household problem with competitive search as follows

$$V(\theta, z, s) = \max_{c, d, s', P, Q} u(c, d, \theta) + \beta \sum_{\theta', z'} \Gamma_{\theta\theta'} \Gamma_{zz'} V(\theta', z', s')$$  \hspace{1cm} (9)

$$s.t. \quad c + Ps' = P \left[ s \left( 1 + \hat{R}(\theta, z) \right) \right],$$  \hspace{1cm} (10)

$$c = d \Psi_h(Q) z$$  \hspace{1cm} (11)

$$\frac{z \Psi_f(Q)}{P} \geq \hat{R}(\theta, z)$$  \hspace{1cm} (12)

Let $u(c, d, \theta) = u(\theta c, d)$ from here on. The first two constraints were defined above, while the last is the firm’s participation constraint, which is the condition that states that firms would prefer this market to other markets in which they would get $\hat{R}(\theta, z)$.

To solve the problem, let’s take the first order conditions. One way to do this is to first plug the first two constraints into the objective function (expressing $c$ and $s'$ as functions of $d$) and then take the
derivative with respect to \(d\) (recall that \(\Psi^h = Q^{1-\varphi}\)) to get:

\[
\theta Q^{1-\varphi}zu_c(\theta d Q^{1-\varphi}z, d) + u_d(\theta d Q^{1-\varphi}z, d) = \\
\beta \sum_{\theta', z'} \Gamma_{\theta \theta'} \Gamma_{z z'} V_3 \left( \theta', z', s(1 + \hat{R}(\theta, z)) - \frac{dQ^{1-\varphi}z}{P} \right) \frac{Q^{1-\varphi}z}{P} (13)
\]

To find \(V_3\) consider the original problem where constraints are not plugged into the objective function. Using the envelope theorem we get:

\[
V_3(\theta, z, s) = \left[ \theta u_c(\theta d Q^{1-\varphi}z, d) + \frac{u_d(\theta d Q^{1-\varphi}z, d)}{Q^{1-\varphi}z} \right] P(1 + \hat{R}(\theta, z))
\]

Combining these two gives the Euler equation:

\[
\theta u_c(\theta d Q^{1-\varphi}z, d) + \frac{u_d(\theta d Q^{1-\varphi}z, d)}{Q^{1-\varphi}z} = \\
\beta \sum_{\theta', z'} \Gamma_{\theta \theta'} \Gamma_{z z'} P'(1 + \hat{R}(\theta', z')) \left[ \theta' u_c(\theta' d' Q^{1-\varphi}z', d') + \frac{u_d(\theta' d' Q^{1-\varphi}z', d')}{Q^{1-\varphi}z'} \right] (14)
\]

Observe that this equation is the same as the Euler equation from the random search model. This gives us the optimal search and saving behavior for a given island (i.e. a market tightness \(1/Q\) and price level \(P\)). To understand which market to search in, we need to look at the FOC with respect to \(Q\) and \(P\). Let \(\lambda\) denote the Lagrange multiplier on the firm’s participation constraint, then the FOC with respect to \(Q\) and \(P\) are respectively:

\[
\theta d (1 - \varphi)Q^{-\varphi}zu_c(\theta d Q^{1-\varphi}z, d) = \\
\beta \sum_{\theta', z'} \Gamma_{\theta \theta'} \Gamma_{z z'} V_3 \left( \theta', z', s(1 + \hat{R}(\theta, z)) - \frac{dQ^{1-\varphi}z}{P} \right) \frac{d(1 - \varphi)Q^{-\varphi}z}{P} - \lambda \frac{Q^{-\varphi - 1}z}{P} (15)
\]
and

$$\beta \sum_{\theta', z'} \Gamma_{\theta' z'} V_3 \left( \theta', z', s(1 + \hat{R}(\theta, z)) - \frac{dQ^{1-\varphi}_z}{P} \right) dQ = -\lambda$$

(16)

Combining these two equations gives us:

$$\theta u_c(\theta dQ^{1-\varphi}_z, d) = \beta \sum_{\theta', z'} \Gamma_{\theta' z'} V_3 \left( \theta', z', s(1 + \hat{R}(\theta, z)) - \frac{dQ^{1-\varphi}_z}{P} \right) \left[ \frac{1}{(1 - \varphi)P} \right]$$

(17)

Recall that we had defined $V_3(\cdot, \cdot, \cdot)$ above and thus this Euler equation simplifies to

$$(1 - \varphi)\theta u_c(\theta dQ^{1-\varphi}_z, d) = \beta \sum_{\theta', z'} \Gamma_{\theta' z'} P'(1 + \hat{R}(\theta', z')) \left[ \theta' u_c(\theta' d'Q^{1-\varphi}_{z'}, d') + \frac{u_d(\theta' d'Q^{1-\varphi}_{z'}, d')}{Q^{1-\varphi}_{z'}} \right]$$

(18)

Or by equations (14) and (18), we get:

$$\theta u_c(\theta dQ^{1-\varphi}_z, d) + \frac{u_d(\theta dQ^{1-\varphi}_z, d)}{Q^{1-\varphi}_z} = (1 - \varphi)\theta u_c(\theta dQ^{1-\varphi}_z, d)$$

(19)

Now we can define the equilibrium:

**Definition 13** An equilibrium with competitive search consists of functions $V, c, d, s', P, Q, and R$ that satisfy:

1. Household’s budget constraint, (condition 10)
2. Household’s shopping constraint, (condition 11)
3. Household’s Euler equation, (condition 14)
4. Market condition, (condition 18)
5. Firm’s participation constraint, (condition 12), which gives us that the dividend payment is the profit of the firm, \( \hat{R}(\theta, z) = \frac{zQ - P}{P} \).

6. Market clearing, i.e. \( s' = 1 \) and \( Q = 1/d \).

Note that if you had solved the problem by replacing \( c \) and \( d \) as functions of \( s' \), then the Euler equations (14) and (18) would be given by:

\[
\theta u_c + \frac{u_d}{Q^{1-\varphi} z} = \beta \sum_{\theta', z'} R_{\theta' z'} \frac{P' (1 + \hat{R}(\theta', z'))}{P} \left[ \theta' u'_c + \frac{u'_d}{Q^{1-\varphi} z'} \right]
\]

and

\[
\theta u_c + \frac{u_d}{Q^{1-\varphi} z} = -\frac{(1 - \varphi)}{\varphi} \frac{u_d}{Q^{1-\varphi} z}
\]

where now \( u_c = u_c \left( \theta P \left[ s \left( 1 + \hat{R} \right) - s' \right], \frac{P [(1+\hat{R})-s']}{Q^{1-\varphi} z} \right) \) and \( u_d = u_d \left( \theta P \left[ s \left( 1 + \hat{R} \right) - s' \right], \frac{P [(1+\hat{R})-s']}{Q^{1-\varphi} z} \right) \).

Also, if the agent’s budget constraint would be defined as \( c + P(\theta, z)s' = s (P(\theta, z) + R(\theta, z)) \), then the firm’s participation constraint is given by \( z \Psi^f(Q(\theta, z)) \geq R(\theta, z) \) and the equilibrium conditions are

\[
\theta u_c + \frac{u_d}{Q^{1-\varphi} z} = \beta \sum_{\theta', z'} R_{\theta' z'} \frac{P' + R'}{P} \left[ \theta' u'_c + \frac{u'_d}{Q^{1-\varphi} z'} \right]
\]

and

\[
\left( \theta u_c + \frac{u_d}{Q^{1-\varphi} z} \right) \left[ s \left( 1 - \varphi \frac{R}{Q} \right) - s' \right] = (1 - \varphi) Q^{-\varphi} \left( \frac{s [P + R] - Ps'}{z} \right) u_d
\]

where now \( u_c = u_c \left( \theta \left[ s (P + R) - Ps' \right], \frac{s [P + R] - Ps'}{Q^{1-\varphi} z} \right) \) and \( u_d = u_d \left( \theta \left[ s (P + R) - Ps' \right], \frac{s [P + R] - Ps'}{Q^{1-\varphi} z} \right) \).

**Exercise 28** Define the recursive equilibrium with competitive search for this last setup.
8.1.1 Firms' Problem

Note that in any given period a firm maximizes its returns to the tree by choosing the appropriate market, $Q$. Note that, by choosing a market $Q$, the firm is effectively choosing a price. Let the numeraire be the price of trees, then $\hat{P}(Q)$ is price of consumption.

Since there is nothing dynamic in the choice of a market (note that, we are assuming firms can choose a different market in each period), we can write the problem of a firm as:

$$\pi = \max_Q \hat{P}(Q) \Psi^f(Q) z. \quad (24)$$

The first order condition for the optimal choice of $Q$ is

$$\hat{P}'(Q) \Psi^f(Q) + \hat{P}(Q) \Psi''(Q) = 0, \quad (25)$$

which then determines $\hat{P}(Q)$ as

$$\frac{\hat{P}''(Q)}{\hat{P}(Q)} = -\frac{\Psi''(Q)}{\Psi^f(Q)}. \quad (26)$$

9 Measure Theory

This section will be a quick review of measure theory, so that we are able to use it in the subsequent sections. In macroeconomics we encounter the problem of aggregation often and it’s crucial that we do it in a reasonable way. Measure theory is a tool that tells us when and how we could do so. Let us start with some definitions on sets.

**Definition 14** For a set $S$, $S$ is a family of subsets of $S$, if $B \in S$ implies $B \subseteq S$ (but not the other way around).
Remark 8 Note that in this section we will assume the following convention

1. small letters (e.g. $s$) are for elements,
2. capital letters (e.g. $S$) are for sets, and
3. fancy letters (e.g. $S$) are for a set of subsets (or families of subsets).

Definition 15 A family of subsets of $S$, $S$, is called a $\sigma$-algebra in $S$ if

1. $S, \emptyset \in S$;
2. if $A \in S \Rightarrow A^c \in S$ (i.e. $S$ is closed with respect to complements and $A^c = S \setminus A$); and,
3. for $\{B_i\}_{i \in \mathbb{N}}$, if $B_i \in S$ for all $i \Rightarrow \bigcap_{i \in \mathbb{N}} B_i \in S$ (i.e. $S$ is closed with respect to countable intersections and by De Morgan’s laws, $S$ is closed under countable unions).

Example 1

1. The power set of $S$ (i.e. all the possible subsets of a set $S$), is a $\sigma$-algebra in $S$.

2. $\{\emptyset, S\}$ is a $\sigma$-algebra in $S$.

3. $\{\emptyset, S_{1/2}, S_{2/2}\}$, where $S_{1/2}$ means the lower half of $S$ (imagine $S$ as an closed interval in $\mathbb{R}$), is a $\sigma$-algebra in $S$.

4. If $S = [0, 1]$, then

\[
S = \left\{ \emptyset, \left[0, \frac{1}{2}\right), \left\{\frac{1}{2}\right\}, \left[\frac{1}{2}, 1\right], S \right\}
\]

is not a $\sigma$-algebra in $S$. But

\[
S = \left\{ \emptyset, \left\{\frac{1}{2}\right\}, \left\{\left[0, \frac{1}{2}\right) \cup \left(\frac{1}{2}, 1\right] \right\}, S \right\}
\]

is a $\sigma$-algebra in $S$. 

50
Why do we need the $\sigma$-algebra? Because it defines which sets may be considered as “events”: things that have positive probability of happening. Elements not in it may have no properly defined measure. Basically, a $\sigma$-algebra is the ”patch” that lets us avoid some pathological behaviors of mathematics, namely non-measurable sets. We are now ready to define a measure.

**Definition 16** Suppose $S$ is a $\sigma$-algebra in $S$. A measure is a real-valued function $x : S \rightarrow \mathbb{R}_+$, that satisfies

1. $x(\emptyset) = 0$;
2. if $B_1, B_2 \in S$ and $B_1 \cap B_2 = \emptyset \Rightarrow x(B_1 \cup B_2) = x(B_1) + x(B_2)$ (additivity); and,
3. if $\{B_i\}_{i \in \mathbb{N}} \in S$ and $B_i \cap B_j = \emptyset$ for all $i \neq j \Rightarrow x(\bigcup_i B_i) = \sum_i x(B_i)$ (countable additivity).\footnote{Countable additivity means that the measure of the union of countable disjoint sets is the sum of the measure of these sets.}

Put simply, a measure is just a way to assign each possible “event” a non-negative real number. A set $S$, a $\sigma$-algebra in it ($S$), and a measure on $S$ ($x$) define a measurable space, $(S, S, x)$.

**Definition 17** A Borel $\sigma$-algebra is a $\sigma$-algebra generated by the family of all open sets $\mathcal{B}$ (generated by a topology). A Borel set is any set in $\mathcal{B}$.

Since a Borel $\sigma$-algebra contains all the subsets generated by the intervals, you can recognize any subset of a set using a Borel $\sigma$-algebra. In other words, a Borel $\sigma$-algebra corresponds to complete information.

**Definition 18** A probability measure is a measure with the property that $x(S) = 1$ and thus $(S, S, x)$ is now a probability space. The probability of an event is then given by $x(A)$, where $A \in S$.

**Definition 19** Given a measurable space $(S, S, x)$, a real-valued function $f : S \rightarrow \mathbb{R}$ is measurable (with respect to the measurable space) if, for all $a \in \mathbb{R}$, we have

$$\{b \in S \mid f(b) \leq a\} \in S.$$
Given two measurable spaces \((S, S, x)\) and \((T, T, z)\), a function \(f : S \to T\) is measurable if for all \(A \in T\), we have

\[
\{ b \in S \; | \; f(b) \in A \} \in S.
\]

One way to interpret a \(\sigma\)-algebra is that it describes the information available based on observations, i.e. a structure to organize information. Suppose that \(S\) is comprised of possible outcomes of a dice throw. If you have no information regarding the outcome of the dice, the only possible sets in your \(\sigma\)-algebra can be \(\emptyset\) and \(S\). If you know that the number is even, then the smallest \(\sigma\)-algebra given that information is \(S = \{\emptyset, \{2, 4, 6\}, \{1, 3, 5\}, S\}\). Measurability has a similar interpretation. A function is measurable with respect to a \(\sigma\)-algebra \(S\), if it can be evaluated under the current measurable space \((S, S, x)\).

**Example 2** Suppose \(S = \{1, 2, 3, 4, 5, 6\}\). Consider a function \(f\) that maps the element 6 to the number 1 (i.e. \(f(6) = 1\)) and any other elements to -100. Then \(f\) is NOT measurable with respect to \(S = \{\emptyset, \{1, 2, 3\}, \{4, 5, 6\}, S\}\). Why? Consider \(a = 0\), then \(\{ b \in S \; | \; f(b) \leq a \} = \{1, 2, 3, 4, 5\}\). But this set is not in \(S\).

We can also generalize Markov transition matrices to any measurable space, which is what we do next.

**Definition 20** Given a measurable space \((S, S, x)\), a function \(Q : S \times S \to [0, 1]\) is a transition probability if

1. \(Q(s, \cdot)\) is a probability measure for all \(s \in S\); and,
2. \(Q(\cdot, B)\) is a measurable function for all \(B \in S\).

Intuitively, for \(B \in S\) and \(s \in S\), \(Q(s, B)\) gives the probability of being in set \(B\) tomorrow, given that
the state is $s$ today. Consider the following example: a Markov chain with transition matrix given by

$$\Gamma = \begin{bmatrix}
0.2 & 0.2 & 0.6 \\
0.1 & 0.1 & 0.8 \\
0.3 & 0.5 & 0.2
\end{bmatrix},$$

on the set $S = \{1, 2, 3\}$, with the $\sigma$-algebra $S = P(S)$ (where $P(S)$ is the power set of $S$). If $\Gamma_{ij}$ denotes the probability of state $j$ happening, given the current state $i$, then

$$Q(3, \{1, 2\}) = \Gamma_{31} + \Gamma_{32} = 0.3 + 0.5.$$

As another example, suppose we are given a measure $x$ on $S$ with $x_i$ being the fraction of type $i$, for any $i \in S$. Given the previous transition function, we can calculate the fraction of types that will be in $i$ tomorrow using the following formulas:

$$x'_1 = x_1 \Gamma_{11} + x_2 \Gamma_{21} + x_3 \Gamma_{31},$$
$$x'_2 = x_1 \Gamma_{12} + x_2 \Gamma_{22} + x_3 \Gamma_{32},$$
$$x'_3 = x_1 \Gamma_{13} + x_2 \Gamma_{23} + x_3 \Gamma_{33}.$$

In other words

$$x' = \Gamma^T x,$$

where $x^T = (x_1, x_2, x_3)$.

To extend this idea to a general case with a general transition function, we define an updating operator as $T(x, Q)$, which is a measure on $S$ with respect to the $\sigma$-algebra $S$, such that

$$x'(B) = T(x, Q)(B)$$
$$= \int_S Q(s, B) x(ds), \quad \forall B \in S,$$
where we integrated over all the possible current states $s$ to get the probability of landing in set $B$ tomorrow.

A stationary distribution is a fixed point of $T$, that is $x^*$ such that

$$x^*(B) = T(x^*, Q)(B), \quad \forall B \in S.$$  

We know that, if $Q$ has nice properties (monotone, Feller property, and enough mixing)\footnote{See Chapters 11/12 in Stockey, Lucas, and Prescott (1989) for more details.} then a unique stationary distribution exists (for instance, we discard alternating from one state to another) and we have that

$$x^* = \lim_{n \to \infty} T^n(x_0, Q),$$

for any $x_0$ in the space of probability measures on $(S, S)$.

**Exercise 29** Consider unemployment in a very simple economy (in which the transition matrix is exogenous). There are two states of the world: being employed and being unemployed. The transition matrix is given by

$$\Gamma = \begin{pmatrix} 0.95 & 0.05 \\ 0.50 & 0.50 \end{pmatrix}.$$  

Compute the stationary distribution corresponding to this Markov transition matrix.
10 Industry Equilibrium

10.1 Preliminaries

Now we are going to study a type of models initiated by Hopenhayn. We will abandon the general equilibrium framework from the previous sections to study the dynamics of the distribution of firms in a partial equilibrium environment.

To motivate things, let’s start with the problem of a single firm that produces a good using labor as input according to a technology described by the production function \( f(n) \). Let us assume that this function is increasing, strictly concave, with \( f(0) = 0 \). A firm that hires \( n \) units of labor is able to produce \( sf(n) \), where \( s \) is productivity. Markets are competitive, so a firm takes prices \((p, w)\) as given. A firm then chooses \( n \) in order to solve

\[
\pi(s, p) = \max_{n \geq 0} \left\{ psf(n) - wn \right\}.
\] (27)

The first order condition implies that in the optimum \( n^* \) solves

\[
psf_n(n^*) = w.
\] (28)

Let us denote the solution to this problem as the function \( n^*(s, p) \). Given the above assumptions, \( n^* \) is an increasing function of both \( s \) (i.e. more productive firms have more workers) and \( p \) (i.e. the higher the output price, the more workers will hire).

Suppose now there is a mass of firms in the industry, each associated with a productivity parameter \( s \in S \subset \mathbb{R}_+ \), where \( S := [s, \bar{s}] \). Let \( S \) denote a \( \sigma \)-algebra on \( S \) (a Borel \( \sigma \)-algebra, for instance). Let \( x \) be a probability measure defined over the space \((S, S)\), which describes the cross-sectional distribution of productivity among firms. Then, for any \( B \subset S \) with \( B \in S \), \( x(B) \) is the mass of firms having productivities in \( S \).

\[\text{As we declared in advance, this is a partial equilibrium analysis. Hence, we ignore the dependence of the solution on } w \text{ to focus on the determination of } p.\]
We will use $x$ to define statistics of the industry. For example, at this point, it is convenient to define the aggregate supply of the industry. Since individual supply is just $sf(n^*(s,p))$, then the aggregate supply can be written as

$$Y^S(p) = \int_s sf(n^*(s,p))x(ds).$$

(29)

Observe that $Y^S$ is a function of the price $p$ only. For any price $p$, $Y^S(p)$ gives us the supply in this economy.

**Exercise 30** Search Wikipedia for an index of concentration in an industry and adopt it for our economy.

Suppose now that the demand of the market is described by some function $Y^D(p)$. Then the industry’s equilibrium price $p^*$ is determined by the market clearing condition

$$Y^D(p^*) = Y^S(p^*).$$

(30)

So far, everything is too simple to be interesting. The ultimate goal here is to understand how the object $x$ is determined by the fundamentals of the industry. Hence, we will be adding tweaks to this basic environment in order to obtain a theory of firms’ distribution in a competitive environment. Let’s start by allowing firms to die.

### 10.2 A Simple Dynamic Environment

Consider now a dynamic environment, in which firms face the problem above every period. Firms discount profits at rate $r_t$, which is exogenously given. In addition, assume that a single firm faces a probability $1 - \delta$ of disappearing in each period. In what follows, we will focus on stationary equilibria; i.e. equilibria in which the price of the final output $p$, the rate of return, $r$, and the productivity of

$^{12}$ $S$ in $Y^S$ stands for supply.
firm, \( s \), stay constant through time.

Notice first that the firm’s decision problem is still a static problem. We can easily write the value of an incumbent firm with productivity \( s \) as

\[
V(s;p) = \sum_{t=0}^{\infty} \left( \frac{\delta}{1+r} \right)^t \pi(s,p)
= \left( \frac{1+r}{1+r-\delta} \right) \pi(s,p)
\]

Note that we are considering that \( p \) is fixed (that is why we use a semicolon and therefore we can omit it from the expressions above). Note also that every period there is positive mass of firms that die.

Then, how can this economy be in a stationary equilibrium? To achieve that, we have to assume that there is a constant flow of firms entering the economy in each period as well, so that the mass of firms that disappear is exactly replaced by new entering firms.

As before, let \( x \) be the measure describing the distribution of firms within the industry. The mass of firms that die is given by \((1-\delta)x(S)\). We will allow these firms to be replaced by new entrants. These entrants draw a productivity parameter \( s \) from a probability measure \( \gamma \) over \((S,S)\).

One might ask what keeps these firms out of the market in the first place? If \( \pi(s;p) = psf(n^*(s;p)) - wn^*(s;p) > 0 \), which is the case for the firms operating in the market (since \( n^* > 0 \)), then all the (potential entering) firms with productivities in \( S \) would want to enter the market.

We can fix this flaw by assuming that there is a fixed entry cost that each firm must pay in order to operate in the market, denoted by \( c^E \). Moreover, we will assume that the entrant has to pay this cost before learning \( s \). Hence the value of a new entrant is given by the following function

\[
V^E(p) = \int_S V(s;p) \gamma(ds) - c^E.
\]

Entrants will continue to enter if \( V^E \) is greater than 0 and decide not to enter if this value is less than zero (since the option value from staying out of the market is 0). As a result, stationarity occurs when
\(V^E\) is exactly equal to zero (this is the free-entry condition)\(^{13}\)

Let’s analyze how this environment shapes the distribution of firms in the market. Let \(x_t\) be the cross-sectional distribution of firms in any given period \(t\). For any \(B \subset S\), a fraction \(1 - \delta\) of firms with productivity \(s \in B\) will die and newcomers will enter the market (the mass of which is \(m\)). Hence, next period’s measure of firms on set \(B\) will be given by

\[
x_{t+1}(B) = \delta x_t(B) + m \gamma(B),
\]

(32)

That is, the mass \(m\) of firms would enter the market in \(t + 1\), but only fraction \(\gamma(B)\) of them will have productivities in the set \(B\). As you might suspect, this relationship must hold for every \(B \in S\). Moreover, since we are interested in stationary equilibria, the previous expression tells us that the cross-sectional distribution of firms will be completely determined by \(\gamma\).

If we let mapping \(T\) be defined as

\[
Tx(B) = \delta x(B) + m \gamma(B), \quad \forall B \in S,
\]

(33)

a stationary distribution of productivity is the fixed point of the mapping \(T\), i.e. \(x^*\) such that \(Tx^* = x^*\), which implies the following

\[
x^*(B; m) = \frac{m}{1 - \delta} \gamma(B), \quad \forall B \in S.
\]

(34)

Now, note that the demand and supply condition in equation \(^{30}\) takes the form

\[
Y^D(p^*(m)) = \int_S s f(n^*(s;p)) dx^*(s;m),
\]

(35)

whose solution \(p^*(m)\) is a continuous function under regularity conditions stated in Stockey, Lucas, and Prescott (1989).

\(^{13}\) We are assuming that there is an infinite number (mass) of prospective firms willing to enter the industry.
We have two equations, (31) and (35), and two unknowns, \( p \) and \( m \). Thus, we can defined the equilibrium as follows

**Definition 21** A stationary distribution for this environment consists of functions \( V, \pi^*, n^*, p^*, x^* \), and \( m^* \), that satisfy:

1. Given prices, \( V, \pi^*, \) and \( n^* \) solve the incumbent firm’s problem;
2. \( Y^D(p^*(m)) = \int_S sf(n^*(s;p))dx^*(s;m) \);
3. \( \int_S V(s;p)\gamma(ds) - c^E = 0 \); and,
4. \( x^*(B) = \delta x^*(B) + m^*\gamma(B) \), \( \forall B \in S \).

### 10.3 Introducing Exit Decisions

We want to introduce more (economic) content by making the exit of firms endogenous (i.e. a decision of the firm). One way to do so is to assume that the productivity of firms follows a Markov process governed by the transition function \( \Gamma \). This would change the mapping \( T \) in Equation (33) as

\[
Tx(B) = \delta \int_S \Gamma(s, B) x(ds) + m\gamma(B), \quad \forall B \in S.
\]

But, this wouldn’t add much economic content to our environment; firms still do not make any (interesting) decision. To change this, let’s introduce operating costs in the model. Suppose firms have to pay \( c^o \) each period in order to stay in the market. In this case, when \( s \) is low, the firm’s profit might not cover its operating cost. The firm might therefore decide to leave the market. Note, however, that the firm has already paid (the sunk cost of) \( c^E \) from entering the market and since \( s \) follows a first-order Markov process, the prospects of future profits might deter the firm from exiting the market. Therefore, having negative profits in one period does not imply that the firm’s optimal choice is to leave the market.
By adding such a minor change, the solution will have a reservation productivity property under some conditions (to be discussed in the comment below). In words, there will be a minimum productivity, \( s^* \in S \), above which it is profitable for the firm to stay in the market (and below which the firm decides to exit).

To see this, note that the value of a firm currently operating in the market with productivity \( s \in S \) is given by

\[
V(s; p) = \max \left\{ 0, \pi(s; p) + \frac{1}{(1 + r)} \int_S V(s'; p) \Gamma(s, ds') - c^0 \right\}.
\]  

(37)

**Exercise 31** Show that the firm's decision takes the form of a reservation productivity strategy, in which, for some \( s^* \in S \), \( s < s^* \) implies that the firm would leave the market.

In this case, the law of motion of the distribution of productivities on \( S \) is given by

\[
x'(B) = \int_{s^*}^{\hat{s}} \Gamma(s, B \cap [s^*, \hat{s}]) x(ds) + m\gamma(B \cap [s^*, \hat{s}]), \quad \forall B \in S.
\]  

(38)

A stationary distribution of the firms in this economy, \( x^* \), is the fixed point of this equation.

**Example 3** How productive does a firm have to be, to be in the top 10% largest firms in this economy (in the stationary equilibrium)? The answer to this question is the solution to the following equation

\[
\frac{\int_{s^*}^{\hat{s}} x^*(ds)}{\int_{s^*}^{\hat{s}} x^*(ds)} = 0.1,
\]

where \( \hat{s} \) is the productivity level above which a firm is in the top 10% largest firm. Then, the fraction of the labor force in the top 10% largest firms in this economy, is

\[
\frac{\int_{s^*}^{\hat{s}} n^*(s, p) x^*(ds)}{\int_{s^*}^{\hat{s}} n^*(s, p) x^*(ds)}.
\]

**Exercise 32** Compute the average growth rate of the smallest one third of the firms. What would be the fraction of firms in the top 10% largest firms in the economy that remain in the top 10% in next
period? What is the fraction of firms younger than five years?

**Comment 2** To see that the firm’s decision is determined by a reservation productivity, we need to start by showing that the profit function (before the variable cost) $\pi(s; p)$ is increasing in $s$. Hence the productivity threshold is given by the $s^*$ that satisfies the following condition:

$$\pi(s^*; p) = c_v$$

for an equilibrium price $p$. Now instead of considering $\gamma$ as the probability measure describing the distribution of productivities among entrants, we consider $\hat{\gamma}$ defined as follows

$$\hat{\gamma}(B) = \frac{\gamma(B \cap [s^*, \bar{s}])}{\gamma([s^*, \bar{s}])}$$

for any $B \in S$.

To make things more concrete and easier to compute, we will assume that $s$ follows a Markov process. To facilitate the exposition, let’s make $S$ finite and assume $s$ has the transition matrix $\Gamma$. Assume further that $\Gamma$ is regular enough so that it has a stationary distribution $\gamma^*$. For the moment we will not put any additional structure on $\Gamma$.

The operating cost $c_v$ is such that the exit decision is meaningful since firms can have negative profits in any given period and thus it is costly to keep doors open. Let’s analyze the problem from the perspective of the firm’s manager. He has now two things to decide. First, he asks himself the question “Should I stay or should I go?”. Second, conditional on staying, he has to decide how much labor to hire. Importantly, notice that this second decision is still a static decision since the manager chooses labor that maximizes the firm’s period profits. Later, we will introduce adjustment costs that will make this decision a dynamic one.

Let $\Phi(s; p)$ be the value of the firm before having decided whether to stay in the market or to go. Let
be the value of the firm that has already decided to stay. Assuming \( w = 1 \), \( V(s; p) \) satisfies

\[
V(s; p) = \max_n \left\{ sfp(n) - n - cv + \frac{1}{1 + r} \int_{s' \in S} \Phi(s'; p) \Gamma(s, ds') \right\}
\]

(39)

Each morning the firm chooses \( d \) in order to solve

\[
\Phi(s; p) = \max_{d \in \{0, 1\}} dV(s; p)
\]

(40)

Let \( d^*(s; p) \) be the optimal decision to this problem. Then \( d^*(s; p) = 1 \) means that the firm stays in the market. One can alternatively write:

\[
\Phi(s; p) = \max_{d \in \{0, 1\}} \left[ \pi(s; p) - cv + \frac{1}{1 + r} \int_{s' \in S} \Phi(s'; p) \Gamma(s, ds') \right]
\]

(41)

or else

\[
\Phi(s; p) = \max \left\{ \pi(s; p) - cv + \frac{1}{1 + r} \int_{s' \in S} \Phi(s'; p) \Gamma(s, ds'), 0 \right\}
\]

(42)

All these are valid. Additionally, one can easily add minor changes to make the exit decision more interesting. For example, things like scrap value or liquidation costs will affect the second argument of the max operator above, which so far was assumed to be zero.

What about \( d^*(s; p) \)? Given a price, this decision rule can take only finitely many values. Moreover, if we could ensure that this decision is of the form “stay only if the productivity is high enough and go otherwise” then the rule can be summarized by a unique number \( s^* \in S \). Without a doubt that would be very convenient, but we don’t have enough structure to ensure that such is the case. Although the ordering of \( s \) is such that \( s_1 < s_2 < ... < s_N \), we need some additional regularity conditions on the transition matrix to ensure that if a firm is in a good state today, it will land in a good state tomorrow with higher probability than a firm that departs today from a worse productivity level.

In order to get a cutoff rule for the exit decision, we need to add an assumption about the transition matrix \( \Gamma \). Let the notation \( \Gamma(\cdot|s) \) indicate the probability distribution over next period state conditional
on being on state \( s \) today. You can think of it as being just a row of the transition matrix (given by \( s \)). Take two different rows, \( s \) and \( \tilde{s} \). We will say that the matrix \( \Gamma \) displays first order stochastic dominance (FOSD) if \( s > \tilde{s} \) implies that \( \sum_{s' \leq b} \Gamma (s' \mid s) \geq \sum_{s' \leq b} \Gamma (s' \mid \tilde{s}) \) for any \( b \in \mathcal{S} \)[14]. It turns out that FOSD is a sufficient condition for having a cutoff rule. You can prove that by using the same kind of dynamic programming tricks that have been used in standard search problems for obtaining the reservation wage property. Try it as an exercise. Also note that this is just a sufficient condition.

Finally, we need to mention something about potential entrants. Since we will assume that they have to pay the cost \( c^E \) before learning their \( s \), they can leave the industry even before producing anything. That requires us to be careful when we describe industry dynamics.

Now the law of motion becomes

\[
x' (B) = m \gamma (B \cap [s^*, \tilde{s}]) + \int_{s^*}^{\tilde{s}} \Gamma (s, B \cap [s^*, \tilde{s}]) x (ds), \quad \forall B \in \mathcal{S}.
\]

### 10.4 Stationary Equilibrium

Now that we have all the ingredients in the table, let’s define the equilibrium formally.

**Definition 22** A stationary equilibrium for this environment consists of a list of functions \( \Phi, \pi^*, n^*, d^*, s^*, V^E \), a price \( p^* \), a measure \( x^* \), and mass \( m^* \) such that

1. Given \( p^* \), the functions \( \Phi, \pi^*, n^*, d^* \) solve the problem of the incumbent firm

2. The reservation productivity \( s^* \) satisfies

\[
d^* (s; p^*) = \begin{cases} 
1 & \text{if } s \geq s^* \\
0 & \text{otherwise}
\end{cases}
\]

[14] Recall that a distribution \( F \) FOSD \( G \) (continuous and defined over the support \([0, \infty)\)) iff \( F(x) \leq G(x) \) for all \( x \). Also, for any nondecreasing function \( u : \mathbb{R} \to \mathbb{R} \), iff \( F \) FOSD \( G \) we have that \( \int u(x) dF(x) \geq \int u(x) dG(x) \).
3. Free-entry condition:

\[ V^E(p^*) = 0 \]

4. For any \( B \in S \) (assuming we have a cut-off rule with \( s^* \) is cut-off in stationary distribution)\[^{15}\]

\[ x^*(B) = m^* \gamma(B \cap [s^*, \bar{s}]) + \int_{s^*}^{\bar{s}} \Gamma(s, B \cap [s^*, \bar{s}]) x^*(ds) \]

5. Market clearing:

\[ Y^d(p^*) = \int_{s^*}^{\bar{s}} s f(n^*(s; p^*)) x^*(ds) \]

You can think of condition (2) as a “no money left over the table” condition, which ensures additional entrants find it unprofitable to participate in the industry.

We can use this model to compute interesting statistics. For example the average output of the firm is given by

\[ \frac{Y}{N} = \frac{\int_{s^*}^{\bar{s}} s f(n^*(s)) x^*(ds)}{\int_{s^*}^{\bar{s}} x^*(ds)} \]

Next, suppose that we want to compute the share of output produced by the top 1% of firms. To do so, we first need to find \( \bar{s} \) such that

\[ \frac{\int_{s^*}^{\bar{s}} x^*(ds)}{N} = .01 \]

\[^{15}\] If we do not have such cut-off rule, we have to define

\[ x^*(B) = \int_S \sum_{s' \in S} \Gamma_{ss'} 1\{s' \in B\} 1\{d(s', p^*) = 1\} x^*(ds) + \mu^* \int_S 1\{s \in B\} 1\{d(s, p^*) = 1\} \gamma(ds) \]

where

\[ \mu^* = \int_S \sum_{s' \in S} \Gamma_{ss'} 1\{d(s', p^*) = 0\} x^*(ds) \]
where \( N \) is the total measure of firms defined above. Then the share of output produced by these firms is given by

\[
\frac{\int_{\tilde{s}}^{\bar{s}} s f(n^*(s)) x^*(ds)}{\int_{\tilde{s}}^{\bar{s}} s f(n^*(s)) x^*(ds)}
\]

Suppose now that we want to compute the fraction of firms in the top 1% two periods in a row. If \( s \) is a continuous variable, this is given by

\[
\int_{s \geq \tilde{s}} \int_{s' \geq \tilde{s}} \Gamma_{ss'} x^*(ds)
\]

or if \( s \) is discrete, then

\[
\sum_{s \geq \tilde{s}} \sum_{s' \geq \tilde{s}} \Gamma_{ss'} x^*(s)
\]

We can use this model to compute a variety of other interesting statistics, including for instance the Gini coefficient.

### 10.5 Adjustment Costs

To end with this section it is useful to think about environments in which firm’s productive decisions are no longer static. A simple way of introducing dynamics is by adding adjustment costs. We will consider labor adjustment costs\(^{16}\).

Consider a firm that enters period \( t \) with \( n_{t-1} \) units of labor, hired in the previous period. We consider three specifications for the adjustment costs \( c(n_t, n_{t-1}) \) due to hiring \( n_t \) units of labor in \( t \) as

- **Convex Adjustment Costs**: if the firm wants to vary the units of labor, it has to pay \( \alpha (n_t - n_{t-1})^2 \) units of the numeraire good. The cost here depends on the size of the adjustment.

---

\(^{16}\) These costs work pretty much like capital adjustment costs, as one might suspect.
• **Training Costs or Hiring Costs**: if the firm wants to increase labor, it has to pay \( \alpha [n_t - (1 - \delta) n_{t-1}]^2 \) units of the numeraire good only if \( n_t > n_{t-1} \). We can write this as

\[
1_{\{n_t > n_{t-1}\}} \alpha [n_t - (1 - \delta) n_{t-1}]^2,
\]

where \( 1 \) is the indicator function and \( \delta \) measures the exogenous attrition of workers in each period.

• **Firing Costs**: the firm has to pay if it wants to reduce the number of workers.

The recursive formulation of the firm’s problem would be:

\[
V(s, n_-, p) = \max \left\{ 0, \max_{n \geq 0} s f(n) - wn - c(n, n_-) + \frac{1}{(1 + r)} \int_{s' \in S} V(s', n, p) \Gamma(s, ds') \right\},
\]

where the function \( c(\cdot, \cdot) \) gives the specified cost of adjusting \( n_- \) to \( n \). Note that we are assuming limited liability for the firm since its exit value is 0 and not \(-c(0, n_-)\).

Now, a firm is characterized by both its current productivity \( s \) and labor in the previous period \( n_- \). Note that since the production function \( f \) has decreasing returns to scale, there exists an amount of labor \( \bar{N} \) such that none of the firms hire labor greater than \( \bar{N} \). So, \( n_- \in N := [0, \bar{N}] \). Let \( \mathcal{N} \) be a \( \sigma \)-algebra on \( N \). If the labor policy function is \( n = g(s, n_-, p) \), then the law of motion for the measure of firms becomes

\[
x'(B^S, B^N) = m \gamma \left( B^S \cap [s^*, \bar{s}] \right) 1_{\{0 \in B^N\}} + \int_{s^*}^{\bar{s}} \int_{0}^{\bar{N}} 1_{\{g(s, n_-; p) \in B^N\}} \Gamma(s, B^S \cap [s^*, \bar{s}]) x(ds, dn_-),
\]

\[\forall B^S \in S, \forall B^N \in \mathcal{N}.\]  

**Exercise 33** Write the first order conditions for the problem in (43). Define the recursive competitive equilibrium for this economy.

**Exercise 34** Another example of labor adjustment costs is when the firm has to post vacancies to
attract labor. As an example of such case, suppose the firm faces a firing cost according to the function $c$. The firm also pays a cost $\kappa$ to post vacancies and after posting vacancies, it takes one period for the workers to be hired. How can we write the problem of firms in this environment?

### 10.6 Non-stationary Equilibrium

Until now we focused on stationary industry equilibria in which individual firms enter and exit the industry, but the whole distribution of firms is invariant. A more interesting case is to look at non-stationary equilibria and examine how the distribution of firms shifts across time.

Let’s maintain our baseline model (with entry & exit, but no adjustment costs), and think about the economy starting with some (arbitrary) initial distribution of incumbent firms $x_0$. Without any shocks, the firm distribution would converge to the stationary equilibrium distribution $x^*$ defined in section 10.4 and on the transitional path towards the stationary equilibrium, firms would face a sequence of prices $\{p_t\}_{t=0}^\infty$. Industry prices $p_t$ are going to be pinned down by equating the endogenous aggregate supply and ad-hoc aggregate demand in each period. But we will now feed in a sequence of shocks $\{z_t\}_{t=0}^\infty$.

Denote the aggregate demand by $D(p_t, z_t)$, where $z_t$ is a demand side shock that shifts aggregate demand. We will maintain wages normalized to 1.

A few remarks regarding the shock. In general, $z_t$ can be deterministic or stochastic. Deterministic shocks are fully anticipated by agents in the economy, while stochastic shocks are random and agents only know the random process that governs them. Solving the model with deterministic shocks is as easy as solving the transitional path of the model without shocks. But models with stochastic shocks are much harder to solve. We will consider for now that the shock $z_t$ is deterministic and thus focus on the perfect foresight equilibrium.

We are now ready to define the firm’s problem. State variables are now the individual state $s$ (idiosyncratic productivity shock) and the aggregate states $z$ (aggregate demand shock) and $x$ (measure of
firms). We thus have

$$V(s, z_t, x_t) = \max \left\{ 0, \pi(s, z_t, x_t) + \frac{1}{1+r} \int_{s'} V(s', z_{t+1}, x_{t+1}) \Gamma(s, ds') \right\}$$  \hspace{1cm} (45)$$

s.t. \quad \pi(s, z_t, x_t) = \max_{n_t \geq 0} p_t(z_t, x_t) s f(n_t) - w n_t - c^e$$

Note that we can maintain the cutoff property of the decision rule given the regularity conditions assumed above. Let’s denote the exit cutoff productivity as $s^*_t$. Note that in order to solve this problem, the firm needs to know the measure of firms in the industry. So we need to compute the law of motion of the measure of firms. For each $B \in S$, we have

$$x_{t+1}(B) = m_{t+1} \gamma(B \cap [s^*_{t+1}, \bar{s}]) + \int_{s_t}^{s} \Gamma(s, B \cap [s^*_{t+1}, \bar{s}]) x_t(ds)$$  \hspace{1cm} (46)$$

where $m_{t+1}$ is the mass of firms that enter at the beginning of period $t + 1$, which is pinned down by the free-entry condition

$$\int V(s, z_t, x_t) \gamma(ds) \leq c^e$$  \hspace{1cm} (47)$$

with strict equality if $m_t > 0$. The distribution of productivity among entrants $\gamma$ and the entry cost $c^e$ are exogenously given. Finally, the market clearing condition will close the model by pinning down price $p_t$ from

$$D(p_t, z_t) = \int_{s_t}^{\bar{s}} p_t s f(n^*(s, z_t, x_t)) x_t(ds)$$  \hspace{1cm} (48)$$

We can now define the perfect foresight equilibrium as follows

**Definition 23** Given a path of shocks $\{z_t\}_{t=0}^{\infty}$ and a initial measure of firms $x_0$, a perfect foresight equilibrium (PFE) for this environment consists of sequences $\{p_t, x_t, m_t, V_t, s^*_t, d^*_t, n^*_t\}_{t=0}^{\infty}$ that satisfy:

1. **Optimality**: Given $\{p_t\}, \{V_t, s^*_t, d^*_t, n^*_t\}$ solve the firm’s problem (45) for each period $t$, where $d^*_t = d^*(s, z_t, x_t)$ and $n^*_t = n^*(s, z_t, x_t)$. 

68
2. **Free-entry**: \( \int V(s, z_t, x_t) \gamma(ds) \leq c^e \), with strict equality if \( m_t > 0 \).

3. **Law of motion**: \( x_{t+1}(B) = m_{t+1} \gamma(B \cap [s^*_t, \bar{s}]) + \int_{s^*_t}^{\bar{s}} \Gamma(s, B \cap [s^*_t, \bar{s}]) x_t(ds) \), \( \forall B \in \mathcal{S} \).

4. **Market clearing**: \( D(p_t, z_t) = \int_{s^*_t}^{\bar{s}} p_t s f(n^*(s, z_t, x_t)) x_t(ds) \).

Having figured out the equilibrium of the perfect foresight model, the natural next step is to solve the fully stochastic equilibrium. It is a much harder problem to solve. We will resort to some notion of linearization to achieve that, which we will revisit in the next subsection.

**Exercise 35** What happens if demand doubles? Sketch an algorithm to find the equilibrium prices.

### 10.7 Linear Approximation

To better understand linearization, we will first look at a basic growth model and approximate the solution linearly. Consider the social planner’s problem (with full depreciation)

\[
V(k_t) = \max_{c_t, k_{t+1}} \left[ u(c_t) + \beta V(k_{t+1}) \right]
\]

s.t. \( c_t + k_{t+1} \leq f(k_t), \ \forall \ t \geq 0 \)

\( c_t, k_{t+1} \geq 0, \ \forall \ t \geq 0 \)

\( k_0 > 0 \) given.

We can show that \( \{c_t, k_{t+1}\}_{t=0}^{\infty} \) is a solution to the above social planner’s problem if and only if

\[
u'(c_t) = \beta u'(c_{t+1}) f'(k_{t+1}), \ \forall \ t \geq 0
\]

\( c_t + k_{t+1} = f(k_t), \ \forall \ t \geq 0
\)

\[
\lim_{t \to \infty} \beta^t u'(c_t) k_{t+1} = 0
\]

**Exercise 36** Derive the above equilibrium conditions.
We will focus on cases where a steady state $k^*$ exists. Note that the above necessary and sufficient conditions give us a second order difference equation system (we can combine the above solution as $\psi(k_t, k_{t+1}, k_{t+2}) = 0$), with exactly two boundary conditions. So the model is perfectly solvable. The question is how to do it. One obvious option is to find the global solution. For instance, you can guess $a_{k_1}$, use $k_0$ and $\psi(k_t, k_{t+1}, k_{t+2}) = 0$ to get $k_2, k_3, \ldots$ forward up until some $k_T$, and adjust $k_1$ to make sure $k_T$ is close enough to the steady state $k^*$ (this is called forward shooting). Or you can guess a $k_{T-1}$ and do it backward (which is called backward shooting). Or you can guess and adjust the whole path (which is called the extended path method). All these methods will give you a numerical solution starting from the arbitrary $k_0$ (that’s why we call it a global solution).

As you may have done it in another course, the above process can be computationally time consuming. Linearization is a short cut that can yield a good approximation of the solution locally, that is, around the neighborhood of some point (usually, around the steady state). The idea is simple. We know the true solution is in the form of $k_{t+1} = g(k_t)$. Let’s use a linear function to approximate the true solution $g(\cdot)$. Let’s conjecture that our approximation is $k_{t+1} = \hat{g}(k_t) = a + bk_t$. Then we only need to figure out two numbers: $a$ and $b$. We thus need two conditions to pin them down. Since we know the steady state is $k^*$ and that solution must hold in the steady state, then we have that $a + bk^* = k^*$. So we got one condition for free (recall we are approximating around $k^*$). Where do we find the second condition?

We can find it in $\psi$ and our criteria is that we are going to choose $b$ such that the slope of $\hat{g}$ exactly matches the slope of true decision rule $g$ at the steady state $k^*$. So we take a first order Taylor expansion of $\psi[k, g(k), g(g(k))]$ around $k^*$ and obtain

$$\psi[k, g(k), g(g(k))] \approx \psi(k^*, k^*, k^*) + \psi_k(k^*, k^*, k^*)(k - k^*)$$

We know $\psi[k, g(k), g(g(k))] = 0$, and $k$ is in the neighborhood of $k^*$, so it must be

$$\psi_k(k^*, k^*, k^*) = \psi_1^* + \psi_2^* g'(k^*) + \psi_3^* g'(g(k^*)) g'(k^*) = 0$$

Solving this equation gives us $g'(k^*)$ which is exactly what we need (note $\psi_1$, $\psi_2$, and $\psi_3$ may also involve $g'(k^*)$). We can then let $b = g'(k^*)$ and use $\hat{g}(k_t) = a + bk_t$ to approximate the solution near
the steady state.

**Comment 3** In practice, it’s messy to do the total derivative as above. A cleaner way is to linearize the system directly with $k_t, k_{t+1}, k_{t+2}$ and then solve the linear system using whatever method you like. Usually, we cast the system in its state space representation and solve it using matrix algebra (here it helps to know some econometrics).

**Exercise 37** Suppose $f(k_t) = k_t^\alpha$, $u(c_t) = \ln c_t$. Verify that the solution to the social planner’s problem is $k_{t+1} = \alpha \beta k_t^\alpha$. Get the linearized solution around the steady state and compare it with the closed form solution. How precise is the linear approximation?

**Exercise 38** Extend the linearization to the case where we have stochastic productivity shocks $z_t$.

## 11 Incomplete Market Models

We now turn to models with incomplete asset markets and thus agents will not be able to fully insure in all possible states of the world.

### 11.1 A Farmer’s Problem

We start with a simple Robinson Crusoe economy with coconuts that can be stored. Consider the problem of a farmer given by

$$V(s, a) = \max_{c, a'} \ u(c) + \beta \sum_{s'} \Gamma_{ss'} V(s', a')$$

s.t. $c + qa' = a + s$

$c \geq 0$

$a' \geq 0$,  

(55)
where $a$ is his holding of coconuts, which can only take positive values, $c$ is his consumption, and $s$ is amount of coconuts that nature provides. The latter follows a Markov chain, taking values in a finite set $S$, and $q$ is the fraction of coconuts that can be stored to be consumed tomorrow. Note that the constraint on the holdings of coconuts tomorrow ($a'$) is a constraint imposed by nature. Nature allows the farmer to store coconuts at rate $1/q$, but it does not allow him to transfer coconuts from tomorrow to today (i.e. borrow).

We are going to consider this problem in the context of a partial equilibrium setup in which $q$ is given. What can be said about $q$?

**Remark 9** Assume there are no shocks in the economy, so that $s$ is a fixed number. Then, we could write the problem of the farmer as

$$V(a) = \max_{c, a' \geq 0} \left\{ u(a + s - qa') + \beta V(a') \right\}. \quad (56)$$

We can derive the first order condition as

$$qu_c \geq \beta u'_c. \quad (57)$$

If $u$ is assumed to be logarithmic, the FOC for this problem simplifies to

$$\frac{c'}{c} \geq \frac{\beta}{q}, \quad (58)$$

and with equality if $a' > 0$. Therefore, if $q > \beta$ (i.e. nature is more stingy, or the farmer is less patient than nature), then $c' < c$ and the farmer dis-saves (at least, as long as $a' > 0$). But, when $q < \beta$, consumption grows without bound. For that reason, we impose the assumption that $\beta/q < 1$ in what follows.

A crucial assumption to bound the asset space is that $\beta/q < 1$, which states that agents are sufficiently impatient so that they want to consume more today and thus decumulate their assets when they are richer and far away from the non-negativity constraint, $a' \geq 0$. However, this does not mean that when
faced with the possibility of very low consumption, agents would not save (even though the rate of return, \(1/q\), is smaller than the rate of impatience \(1/\beta\)).

The first order condition for farmer’s problem (55) with \(s\) stochastic is given by

\[
uc(c(s,a)) \geq \frac{\beta}{q} \sum_{s'} \Gamma_{ss'}uc(c(s',a'(s,a))),
\]

with equality when \(a'(s,a) > 0\), where \(c(\cdot)\) and \(a'(\cdot)\) are policy functions from the farmer’s problem. Notice that \(a'(s,a) = 0\) is possible for an appropriate stochastic process. Specifically, it depends on the value of \(s_{min} := \min_{s_i \in S} s_i\).

The solution to the problem of the farmer, for a given value of \(q\), implies a distribution of coconut holdings in each period. This distribution, together with the Markov chain describing the evolution of \(s\), can be summed together as a single probability measure for the distribution of shocks and assets (coconut holdings) over the product space \(E = S \times \mathbb{R}_+\), and its \(\sigma\)-algebra, \(\mathcal{B}\). We denote that measure by \(X\). The evolution of this probability measure is then given by

\[
X'(B) = \sum_s \int_0^\infty \sum_{s' \in B_s} \Gamma_{ss'} \mathbf{1}_{\{a'(s,a) \in B_a\}} X(s,da), \quad \forall B \in \mathcal{B},
\]

where \(B_s\) and \(B_a\) are the \(S\)-section and \(\mathbb{R}_+\)-section of \(B\) (projections of \(B\) on \(S\) and \(\mathbb{R}_+\)), respectively, and \(\mathbf{1}\) is an indicator function. Let \(\tilde{T}(\Gamma, a', \cdot)\) be the mapping associated with (60) (the adjoint operator), so that

\[
X'(B) = \tilde{T}(\Gamma, a', X)(B), \quad \forall B \in \mathcal{B}.
\]

Define \(\tilde{T}^n(\Gamma, a', \cdot)\) as

\[
\tilde{T}^n(\Gamma, a', X) = \tilde{T}(\Gamma, a', \tilde{T}^{n-1}(\Gamma, a', X)).
\]

Then, we can define the following theorem.
Theorem 3 Under some conditions on $\tilde{T}(\Gamma, a', \cdot)$ there is a unique probability measure $X^*$, so that:

$$X^*(B) = \lim_{n \to \infty} \tilde{T}^n(\Gamma, a', X_0)(B), \quad \forall B \in \mathcal{B},$$

for all initial probability measures $X_0$ on $(E, \mathcal{B})$.

A condition that makes things considerably easier for this theorem to hold is that $E$ is a compact set. Then, we can use Theorem (12.12) in Stokey, Lucas, and Prescott (1989) to show this result holds. Given that $S$ is finite, this is equivalent to a compact support for the distribution of asset holdings. We discuss this in further detail in Appendix A.

11.2 Huggett Economy

Now we modify the farmer’s problem in (55) a little bit, in line with Huggett (1993). Look carefully at the borrowing constraint in what follows

$$V(s, a) = \max_{c, a'} u(c) + \beta \sum_{s'} \Gamma_{ss'} V(s', a')$$

s.t. $c + qa' = a + s$

$c \geq 0$

$a' \geq \bar{a}$.

where $a < 0$. Now farmers can borrow and lend among each other, but up to a borrowing limit. We continue to make the same assumption on $q$; i.e. that $\beta/q < 1$. As before, solving this problem gives the policy function $a'(s, a)$. It is easy to extend the analysis in the last section to show that there is an upper bound on the asset space, which we denote by $\bar{a}$, so that for any $a \in A := [a, \bar{a}], a'(s, a) \in A$, for any $s \in S$.

17 As in the previous section, we need $\Gamma$ to be monotone, enough mixing in the distribution, and that $\tilde{T}$ maps the space of bounded continuous functions to itself.
Remark 10 One possibility for $a$ is what we call the natural borrowing limit. This limit ensures the agent can pay back his debt with certainty, no matter what the nature unveils (i.e. whatever sequence of idiosyncratic shocks is realized). This is given by

$$a^n := -\frac{s_{\min}}{\left(\frac{1}{q} - 1\right)}.$$  \hspace{1cm} (65)

If we impose this constraint on (64), the farmer can fully pay back his debt in the event of receiving an infinite sequence of bad shocks by setting his consumption equal to zero forever.

But, what makes this problem more interesting is to tighten this borrowing constraint more. The natural borrowing limit is very unlikely to be binding. One way to restrict borrowing further is to assume no borrowing at all, as in the previous section. Another case is to choose $0 > a > a^n$, which we will consider in this section.

Now suppose there is a (unit) mass of farmers with distribution function $X(\cdot)$, where $X(D, B)$ denotes the fraction of people with shock $s \in D$ and $a \in B$, where $D$ is an element of the power set of $S$, $P(S)$ (which, when $S$ is finite, is the natural $\sigma$-algebra over $S$), and $B$ is a Borel subset of $A$ ($B \in A$).

Then the distribution of farmers tomorrow is given by

$$X'(D', B') = \sum_{s \in S} \int_A 1_{\{a'(s, a) \in B'\}} \sum_{s' \in D'} \Gamma_{ss'} X(s, da),$$  \hspace{1cm} (66) for any $D' \in P(S)$ and $B' \in A$.

Implicitly this defines an operator $T$ such that $X' = T(X)$. If $T$ is sufficiently nice (as defined above and in the previous footnote), then there exits a unique $X^*$ such that $X^* = T(X^*)$ and $X^* = \lim_{n \to \infty} T^n(X_0)$ for any initial distribution over the product space $S \times A$, $X_0$. Note that the decision rule is obtained for a given price $q$. Hence, the resulting stationary distribution $X^*$ also depends on $q$. So, let us denote it by $X^*(q)$.

To determine the equilibrium value of $q$ in a general equilibrium setting consider the following variable
(as a function of $q$):

$$
\int_{A \times S} a \, dX^*(q).
$$

This expression gives us the average asset holdings, given the price $q$ (assuming $s$ is a continuous variable). What we want to do is to determine the endogenous $q$ that clears the asset market. Recall that we assumed that there is no storage technology so that the supply of assets is 0 in equilibrium. Hence, the price $q$ should be such that the asset demand equals asset supply, i.e.

$$
\int_{A \times S} a \, dX^*(q) = 0.
$$

In this sense, the equilibrium price $q$ is the price that generates the stationary distribution of asset holdings that clears the asset market.

We can now show that a solution exists by invoking the intermediate value theorem. We need to ensure that the following three conditions are satisfied (note that $q \in [\beta, \infty]$)

1. $\int_{A \times S} a \, dX^*(q)$ is a continuous function of $q$;

2. $\lim_{q \to \beta} \int_{A \times S} a \, dX^*(q) \to \infty$; (As $q \to \beta$, the interest rate $R = 1/q$ increases up to $1/\beta$, which is the steady state interest rate in the representative agent economy. Hence, agents would like to save more. Adding to this the precautionary savings motive, agents would want to accumulate an unbounded amount of assets in the stationary equilibrium); and,

3. $\lim_{q \to \infty} \int_{A \times S} a \, dX^*(q) < 0$. (This is also intuitive: as $q \to \infty$, the interest rate $R = 1/q$ converges to 0. Hence, everyone would rather borrow).

### 11.3 Aiyagari Economy

The Aiyagari (1994) economy is one of the workhorse models of modern macroeconomics. It features incomplete markets and an endogenous wealth distribution, which allows us to examine interactions
between heterogeneous agents and distributional effects of public polices. The setup will similar to the one above, but now physical capital is introduced. Then, the average asset holdings in the economy that we computed above must be equal to the average amount of (physical) capital $K$. Keeping the notation from the previous section (i.e. the stationary distribution of assets is $X^*$), then we have that

$$\int_{A \times S} a \, dX^*(q) = K,$$

(69)

where $A$ is the support of the distribution of wealth. (It is not difficult to see that this set is compact.)

We will now assume that the shocks affect labor income. We can think of these shocks as fluctuations in the employment status of individuals. Now the restriction for the existence of a stationary equilibrium is $\beta (1 + r) < 1$. Thus, the problem of an individual in this economy can be written as

$$V(s, a) = \max_{c, a'} u(c) + \beta \int_{s'} V(s', a') \Gamma(s, ds')$$

(70)

s.t. $c + a' = (1 + r) a + ws$

$c \geq 0$

$a' \geq a,$

where $r$ is the return on savings and $w$ is the wage rate. Then,

$$\int_{A \times S} s \, dX^*(q)$$

(71)

gives the average labor in this economy. If agents are endowed with one unit of time, we can think of the expression as determining the effective labor supply.

We also assume the standard constant returns to scale production technology for the firm as

$$F(K, L) = AK^{1-\alpha} L^\alpha,$$

(72)

where $A$ is TFP and $L$ is the average amount of labor in the economy. Let $\delta$ be the rate of depreciation.
of capital. Hence, solving for the firm’s FOC we have that factor prices satisfy

\[ r = F_k(K,L) - \delta \]
\[ = (1 - \alpha)A \left( \frac{K}{L} \right)^{-\alpha} - \delta \]
\[ =: r \left( \frac{K}{L} \right), \]

and

\[ w = F_l(K,L) \]
\[ = \alpha A \left( \frac{K}{L} \right)^{1-\alpha} \]
\[ =: w \left( \frac{K}{L} \right). \]

The prices faced by agents are functions of the capital-labor ratio. As a result, we may write the stationary distribution of assets as a function of the capital-labor ratio as well and thus \( X^* \left( \frac{K}{L} \right) \). The equilibrium condition now becomes

\[ \frac{K}{L} = \frac{\int_{A \times S} a \, dX^* \left( \frac{K}{L} \right)}{\int_{A \times S} s \, dX^* \left( \frac{K}{L} \right)}. \]  \( \text{(73)} \)

Using this condition, one can solve for the equilibrium capital-labor ratio and study the distribution of wealth in this economy.

**Remark 11** Note that relative to Huggett (1993), the price of assets \( q \) is now given by

\[ q = \frac{1}{1 + r} = \frac{1}{1 + F_k(K,L) - \delta}. \]  \( \text{(74)} \)

**Exercise 39** Show that aggregate capital is higher in the stationary equilibrium of the Aiyagari economy than it is the standard representative agent economy.
11.3.1 Policy Changes and Welfare

Let the model parameters in an In Aiyagari or Huggett economy be summarized by \( \theta = \{u, \beta, s, \Gamma, F\} \). The value function \( V(s, a; \theta) \) as well as \( X^*(\theta) \) can be obtained in the stationary equilibrium as functions of the model parameters, where \( X^*(\theta) \) is a mapping from the model parameters to the stationary distribution of agent’s asset holding and shocks. Suppose now there is a policy change that shifts \( \theta \) to \( \hat{\theta} = \{u, \beta, s, \hat{\Gamma}, F\} \). Associated with this new environment there is a new value function \( V(s, a; \hat{\theta}) \) and a new distribution \( X^*(\hat{\theta}) \). Now define \( \eta(s, a) \) to be the solution of

\[
V(s, a + \eta(s, a); \hat{\theta}) = V(s, a; \theta), \tag{75}
\]

which corresponds to the transfer necessary to make the agent indifferent between living in the old environment and living in the new one (say from an initial steady state to a final steady state). Hence, the total transfer needed to compensate the agent for this policy change is given by

\[
\int_{A \times S} \eta(s, a) \, dX^*(\theta). \tag{76}
\]

**Remark 12** Notice that the changes do not take place when the government is trying to compensate the households and that is why we use the original stationary distribution associated with \( \theta \) to aggregate the households \( (X^*(\theta)) \).

If \( \int_{A \times S} V(s, a) \, dX^*(\hat{\theta}) > \int_{A \times S} V(s, a) \, dX^*(\theta) \), does this necessarily mean that households are willing to accept this policy change? Not necessarily! Recall that comparing welfare requires us to compute the transition from one world to the other. Then, during the transition to the new steady state, the welfare losses may be very large despite agents being better off in the final steady state.
11.4 Business Cycles in an Aiyagari Economy

11.4.1 Aggregate Shocks

In this section, we consider an economy that is subject to both aggregate and idiosyncratic shocks. Consider the Aiyagari economy again, but with a production function that is subject to an aggregate shock $z$ so that we have $zF(K, \bar{N})$.

Then the current aggregate capital stock is given by

$$K = \int a \, dX(s,a). \tag{77}$$

and next period aggregate capital is

$$K' = G(z, K) \tag{78}$$

The question is what are the sufficient statistics to predict the aggregate capital stock and, consequently, prices tomorrow? Are $z$ and $K$ sufficient to determine capital tomorrow? The answer to these questions is no, in general. It is only true if, and only if, the decision rules are linear. Therefore, $X$, the distribution of agents in the economy becomes a state variable (even in the stationary equilibrium).\(^\text{18}\)

\(^{18}\) Note that with $X$ we can compute aggregate capital.
Then, the problem of an individual becomes

\[ V(z, X, s, a) = \max_{c, a'} u(c) + \beta \sum_{z', s'} \Pi_{zz'} \Gamma_{ss'} V(z', X', s', a') \quad (79) \]

s.t. \[ c + a' = az f_k(K, \bar{N}) + sz f_n(K, \bar{N}) \]

\[ K = \int adX(s, a) \]

\[ X' = G(z, X) \]

\[ c, a' \geq 0, \]

where we replaced factor prices with marginal productivities. Computationally, this problem is a beast! So, how can we solve it? To fix ideas, we will first consider an economy with dumb agents!

Consider an economy in which people are stupid. By stupid, we mean that people believe tomorrow’s capital depends only on \( K \) and not on \( X \). This, obviously, is not an economy with rational expectations. The agent’s problem in such a setting is

\[ \tilde{V}(z, X, s, a) = \max_{c, a'} u(c) + \beta \sum_{z', s'} \Pi_{zz'} \Gamma_{ss'} \tilde{V}(z', X', s', a') \quad (80) \]

s.t. \[ c + a' = az f_k(K, \bar{N}) + sz f_n(K, \bar{N}) \]

\[ K = \int adX(s, a) \]

\[ X' = \tilde{G}(z, K) \]

\[ c, a' \geq 0. \]

The next step is to allow people to become slightly smarter, by letting them use extra information, such as the mean and variance of \( X \), to predict \( X' \). Does this economy work better than our dumb benchmark? Computationally no! This answer, as stupid as it may sound, has an important message: agents’ decision rules are approximately linear. It turns out that the approximations are quite reliable.
11.4.2 Linear Approximation Revisited

Let’s now revisit our discussion of linear approximation in the context of the Aiyagari economy. As we can see in section 11.4.1, solving the heterogeneous agent model with aggregate shocks is computationally hard. We need to guess a reduced form rule to approximate the distribution for agents to forecast future prices, and when the model has frictions on several dimensions, there is little we can say on how to choose such a rule.

We can, however, use a linear approximation to obtain the model’s solution around the steady state. The idea is as follows: starting from the steady state, we obtain the impulse responses of the perfect foresight economy given a sequence of small deterministic shocks. Then, we use these responses to approximate the behavior of the main aggregates in the economy with heterogeneous agents by adding small stochastic shocks around the steady state. This method was recently proposed by Boppart, Krusell, and Mitman (2018).

To fix ideas, let’s consider the above Aiyagari economy with a TFP shock \( z \). Let \( \log(z_t) \) follow an AR(1) process with \( \rho \) as the autocorrelation parameter as \( \log(z_t) = \rho \log(z_{t-1}) + \epsilon_t \). First, compute the path of the (log of the) shock by letting \( \epsilon \) will go up by, say, one unit in period 0. Rewriting the process in its MA form, we have the full sequence of values \((1, \rho, \rho^2, \rho^3, \ldots)\) to pin down the TFP path. Then, we can compute the transition path in the deterministic economy, with the agent taking as given the sequence of prices. Thus, solving the deterministic path is straightforward: we guess a path for price (or else we could also guess the path for an aggregate variable), solve the household’s problem backwards from the final steady state back to initial steady state, and then derive the aggregate implications of the households’ behavior and update our guess for the price path. This iterative procedure is also standard and fully nonlinear.

After solving the PFE, we have a sequence of aggregates we care about. We choose one of those, 19 The description of the method below is from that paper with minor modifications.
call it $x$, and we thus have a sequence $\{x_0, x_1, x_2, \ldots\}$. Now consider the same economy subject to recurring aggregate shocks to $z$. Now we want to approximate the object of interest in that economy, call it $\hat{x}$. The key assumption behind this procedure is that we regard the $\hat{x}$ as well approximated by a linear system of the sequence of $x$ computed as a response to the one-time shock. A linear system means that the effects of shocks are linearly scalable and additive so that the level of $\hat{x}$ at some future time $T$, after a sequence of random shocks to $z$ is given by

$$\hat{x}_T \approx x_0 \epsilon_T + x_1 \epsilon_{T-1} + x_2 \epsilon_{T-2} + \ldots$$

or in deviation from steady state

$$(\hat{x}_T - x_{ss}) \approx (x_0 - x_{ss}) \epsilon_T + (x_1 - x_{ss}) \epsilon_{T-1} + (x_2 - x_{ss}) \epsilon_{T-2} + \ldots$$

where $\epsilon_t$ is the innovation to log($z_t$) at period $t$. Thus, the model with aggregate shocks can be obtained by mere simulation based on the one deterministic path. It corresponds to the superposition of non-linear impulse response functions derived from the PFE.

### 11.5 Aiyagari Economy with Job Search

In the Aiyagari model we have seen, the labor market is assumed to be competitive and everybody is employed at the wage rate $w$. Now, we want to add the possibility of agents being in one of two labor market status: $\varepsilon = \{0, 1\}$, where 0 stands for unemployment and 1 for the case in which the agent is employed.

Agents can now exert effort $h$ while searching for a job. Although exerting search effort provides some disutility, it also increases the probability of finding a job. Call that probability $\phi(h)$, with $\phi' > 0$. An employed worker, on the other hand, does not need to search for a new job and so $h = 0$, but his job can be destroyed with some exogenous probability $\delta$. Let $s$ be an employed worker’s stochastic labor productivity, which is a first order Markov process with transition probabilities given by $\Gamma$. 
The unemployed worker’s problem is given by

\[ V(s, 0, a) = \max_{c, a', h} u(c, h) + \beta \sum_{s'} \Gamma_{ss'} \left[ \phi(h)V(s', 1, a') + (1 - \phi(h))V(s', 0, a') \right] \] 

subject to

\[ c + a' = h + (1 + r)a \]

\[ a' \geq 0. \]

Similarly, the employed worker’s problem is as follows

\[ V(s, 1, a) = \max_{c, a'} u(c) + \beta \sum_{s'} \Gamma_{ss'} \left[ \delta V(s', 0, a') + (1 - \delta) V(s', 1, a') \right] \]

subject to

\[ c + a' = sw + (1 + r)a \]

\[ a' \geq 0. \]

**Exercise 40** Solve for the FOC and define the stationary equilibrium for this economy.

**11.6 Aiyagari Economy with Entrepreneurs**

Next, we will introduce entrepreneurs into the Aiyagari world. Suppose every period agents choose an occupation: to be either an entrepreneur or a worker. Entrepreneurs run their own business, by managing a project that combines her entrepreneurial ability \( \epsilon \), capital \( k \), and labor \( n \); while workers supply labor in the market.

Let’s denote \( V^w(s, \epsilon, a) \) the value of a worker labor productivity \( s \), and entrepreneurial ability \( \epsilon \), and wealth \( a \). Similarly, denote \( V^e(s, \epsilon, a) \) the value of an entrepreneur. The worker’s problem is to choose tomorrow’s occupation and wealth level as well as today’s consumption for a given wage rate \( w \) and...
interest rate $r$. 

$$V^w(s, \epsilon, a) = \max_{c, a', d \in \{0, 1\}} u(c) + \beta \sum_{s', \epsilon'} \Gamma_{ss'} \epsilon' \Gamma_{\epsilon\epsilon'} [dV^w(s', \epsilon', a') + (1 - d)V^e(s', \epsilon', a')]$$  \hspace{1cm} (83)

s.t.  \hspace{0.5cm} c + a' = ws + (1 + r)a

$$a' \geq 0$$

Similarly, the entrepreneur’s problem can be formulated as follows

$$V^e(s, \epsilon, a) = \max_{c, a', d \in \{0, 1\}} u(c) + \beta \sum_{s', \epsilon'} \Gamma_{ss'} \epsilon' \Gamma_{\epsilon\epsilon'} [dV^w(s', \epsilon', a') + (1 - d)V^e(s', \epsilon', a')]$$  \hspace{1cm} (84)

s.t.  \hspace{0.5cm} c + a' = \pi(s, \epsilon, a)

$$a' \geq 0$$

Note the entrepreneur’s income is from profits $\pi(a, s, \epsilon)$ rather than wage. We assume entrepreneurs have access to a DRS technology $f$ that produces output using as inputs $(k, n)$. After paying factors and loans needed to operate the business, the entrepreneurs’ profits are given by

$$\pi(s, \epsilon, a) = \max_{k, n} \epsilon f(k, n) + (1 - \delta)k - (1 + r)(k - a) - w \max\{n - s, 0\}$$  \hspace{1cm} (85)

s.t.  \hspace{0.5cm} k - a \leq \phi a

The constraint here reflects the fact that entrepreneurs can only make loans up to a fraction $\phi$ of his total wealth. A limit of this model is that entrepreneurs never make an operating loss within a period, as they can always choose $k = n = 0$ and earn the risk free rate on saving. In this model, agents with high entrepreneurial ability have access to an investment technology $f$ that provides higher returns than workers with high labor productivity and therefore the entrepreneurs accumulate wealth faster.

So, who is going to be an entrepreneur in this economy? In a world without financial constraints, wealth will play no role. There would be a threshold $\epsilon^*$ above which an agent would decide to become
an entrepreneur. With financial constraints, this changes and wealth now plays an important role. Wealthy individuals with high entrepreneurial ability will certainly be entrepreneurs, while the poor with low entrepreneurial ability will become workers. For the other cases, it depends. If the entrepreneurial ability is persistent, poor individuals with high entrepreneurial ability will save to one day become entrepreneurs, while rich agents with low entrepreneurial ability will lend their assets and become workers.

**Exercise 41** Solve for the FOC and define the RCE for this economy.

### 11.7 Other Extensions

There are many more interesting applications. One of these is the economy with unsecured credit and default decisions. The price of lending will now incorporate the possibility of default. For simplicity, assume that if the agent decides to default, she live in autarky forever after. In that case, she is excluded from the financial market and has to consume as much as her labor earnings allow. Let the individual’s budget constraint in the case of no default be given by

\[
c + q(a')a' = a + ws,
\]

where \(s\) is labor productivity with transition probabilities given by \(\Gamma_{ss'}\). The problem of an agent is thus given by

\[
V(s, a) = \max \left\{ u(ws) + \beta \sum_{s'} \Gamma_{ss'} \bar{V}(s'), u(ws + a - q(a')a') + \beta \sum_{s'} \Gamma_{ss'} V(s', a') \right\}
\]

s.t. \(a' \geq 0\),

where \(\bar{V}(s') = \frac{1}{1-\beta} u(ws')\) is the value of autarky.
12 Monopolistic Competition

12.1 Benchmark Monopolistic Competition

The two most important macroeconomic variables are perhaps output and inflation (movement in the aggregate price). In this section we take a first step in building a theory of aggregate price. To achieve this, we need a framework in which firms can choose their own prices and yet the aggregate price is well defined and easy to handle. The setup of Dixit and Stiglitz (1977) with monopolistic competition is such a framework.

In an economy with monopolistic competition, firms are sufficiently “different” so that they face a downward sloping demand curve and thus price discriminate, but also sufficiently small so that they ignore any strategic interactions with their competitors. We thus assume there are infinitely many measure 0 firms, each producing one variety of goods. Varieties span on the \([0, n]\) interval and are imperfect substitutes. Consumers have a “taste for variety” in that they prefer to consume a diversified bundle of goods (this gives firms some market power as we want). The consumer’s utility function will have the constant elasticity of substitution (CES) form

\[
u\left(\{c(i)\}_{i\in[0,n]}\right) = \left( \int_0^n c(i)^{\frac{\sigma-1}{\sigma}} di \right)^{\frac{\sigma}{\sigma-1}}
\]

where \(\sigma\) is the elasticity of substitution, which is a constant (as the name CES suggests), and \(c(i)\) is the quantity consumed of variety \(i\). For simplicity, we will rename \(c(i) = c_i\). For now, we will assume the agent receives the exogenous nominal income \(I\) and is endowed with one unit of time.

We can now solve the household problem

\[
\max_{\{c_i\}_{i\in[0,n]}} \left( \int_0^n c_i^{\frac{\sigma-1}{\sigma}} di \right)^{\frac{\sigma}{\sigma-1}}
\]

s.t. \(\int_0^n p_i c_i di \leq I\)
and derive the FOC, which relates the demand for any varieties $i$ and $j$ as

$$c_i = c_j \left( \frac{p_i}{p_j} \right)^{-\sigma}$$

Multiplying both sides by $p_i$ and integrating over $i$, we get the downward sloping demand curve faced by an individual firm producing variety $i$ as

$$c_i^* = \frac{I}{\int_0^n p_j^{1-\sigma} dj} p_i^{-\sigma}$$

We can see that the demand for variety $i$ depends both on the price of variety $i$ and some measure of “aggregate price”. It is actually convenient to define the aggregate price index $P$ as follows

$$P = \left( \int_0^n p_j^{1-\sigma} dj \right)^{\frac{1}{1-\sigma}}$$

and thus the demand faced by the firm producing variety $i$ can be reformulated as

$$c_i^* = \frac{I}{P} \left( \frac{p_i}{P} \right)^{-\sigma}$$

where the first term is real income and the second is a measure of relative price of variety $i$.

**Exercise 42** Show the following within the monopolistic competition framework above:

1. $\sigma$ is the elasticity of substitution between varieties.
2. Price index $P$ is the expenditure to purchase a unit-level utility for consumers.
3. Consumer utility is increasing in the number of varieties $n$.

We are now ready to characterize the firm’s problem. Let’s assume that the production technology is linear in its inputs and so one unit of output is produced with one unit of labor linearly, i.e., $f(n_j) = n_j$. Let the nominal wage rate be given by $W$. Also, recall that the quantity of variety $j$ demanded by the representative agent is such that $f(n_j) = c_j^*$. Then, the firm producing variety $j$ solves the following
Recall that we assume firms are sufficiently small so they would ignore the effect of their own pricing strategies on aggregate price index $P$, which greatly simplify the algebra. By solving for the FOC, we get the straightforward pricing rule

$$p^*_j = \frac{\sigma}{\sigma - 1} W \quad \forall j$$

where $\frac{\sigma}{\sigma - 1}$ is a constant mark-up over the marginal cost, which reflects the elasticity of substitution of consumers. When varieties are very close substitutes ($\sigma \to \infty$), price just converge to the factor price $W$. Not that all firms follow the same pricing strategy, which is independent of the variety $j$.

We can now define an equilibrium for this simple economy.

**Definition 24** A general equilibrium for this environment consists of prices $\{p^*_i\}_{i \in [0,n]}$, the aggregate price index $P$, household’s consumption $\{c^*_i\}_{i \in [0,n]}$ and nominal income $I$, firm’s labor demand $\{n^*_i\}_{i \in [0,n]}$ and profits $\{\pi^*_i\}_{i \in [0,n]}$, such that

1. Given prices, $\{c^*_i\}_{i \in [0,n]}$ solves the household’s problem
2. Given the aggregate price and the input price, $\{\pi^*_i\}_{i \in [0,n]}$ and $\{p^*_i\}_{i \in [0,n]}$ solve the firm’s problem
3. From the firm’s pricing strategy, we have the representative firm condition

$$P = n^{1-\sigma} p^*_i \quad \forall i$$
4. Markets clear

\[ \int c_i^* di = \int n_i^* di = 1 \]

\[ I = W + \int \pi_i^* di \]

Note that in equilibrium we have \( c_i^* = \bar{c}, \ p_i^* = \bar{p}, \ n_i^* = \bar{n}, \ \pi_i^* = \bar{\pi} \) for all \( i \).

12.2 Price Rigidity

We now have a simple theory of aggregate price \( P \), which is ultimately shaped by the consumer’s elasticity of substitution across varieties. However, we are still silent on inflation. To study inflation, and to have meaningful interactions between output and inflation, we need i) a dynamic model and ii) some source of nominal frictions.

Nominal frictions mean that nominal variables (things measured in dollars, say, quantity of money) can affect real variables. The most popular friction used is called price rigidity. With price rigidity, firms cannot adjust their prices freely. Two commonly used specifications to achieve this in the model are Rotemberg pricing (menu costs) and Calvo pricing (fairy blessing).

In Rotemberg pricing, firms face adjustment cost \( \phi(p_j, \bar{p}_j) \) when changing their prices \( p_j \) each period. Using the static model of the previous section (and assuming an exogenous process for the agent’s nominal endowment \( I_t \)), we can specify the firm’s per period profit under Rotemberg pricing in a dynamic setup as follows:

\[ \pi_{jt} = p_{jt} c_{jt}^* - W_t c_{jt}^* - \phi(p_{jt}, p_{jt-1}) I_t \]

where \( c_{jt}^* = \left( \frac{p_{jt}}{P_t} \right)^{-\sigma} \frac{I_t}{P_t} \)

Then each period, firms choose the price that maximizes the expected present discounted value of the flow profit. Rotemberg is easy in terms of algebra when we assume a quadratic price adjustment cost.
However, it generates some fiscal effects that are not so realistic.

A more popular version of price rigidity is the Calvo pricing. It says that instead of facing some adjustment costs, firms cannot adjust their prices each period with some probability. It’s a bit more complicated in terms of algebra. We will sketch the problem but leave most of the rest as an exercise.

Each period with probability $\theta$ a firm can change its price and with probability $1 - \theta$ the firm is not allowed to do so. When setting the price, the firm now needs to incorporate the possibility of not being allowed to adjust its price. Assuming the firm discounts the future at rate $1 + r$, its problem at period $t$ is given by

$$
\max_{p_{j,t}} \sum_{k=0}^{\infty} \left( \frac{1 - \theta}{1 + r} \right)^k \left[ p_{j,t}c_{j,t+k}^* - W_{t+k}c_{j,t+k}^* \right]
$$

s.t. 
$$
c_{j,t}^* = \left( \frac{p_{j,t}}{P_t} \right)^{-\sigma} \frac{I_t}{P_t}
$$

**Exercise 43** Derive the following for the dynamic model with Calvo pricing

1. Solve the firm’s problem and write the firm’s equilibrium pricing $p_{j,t}$ as a function of present and future aggregate prices, wages, and endowments: $\{P_t, W_t, I_t\}_t^{\infty}$.

2. Show that under flexible pricing ($\theta = 1$), the firm’s pricing strategy is identical to the static model.

3. Show that with price rigidity ($\theta < 1$), the firm’s pricing strategy is identical to the static model in the steady state with zero inflation.
A Farmer’s Problem: Revisited

Consider the following problem of a farmer that we studied in class:

\[ V(s, a) = \max_{c, a'} \left\{ u(c) + \beta \sum_{s'} \Gamma_{ss'} V(s', a') \right\} \]
\[ \text{s.t. } c + qa' = a + s \]
\[ c \geq 0 \]
\[ a' \geq 0. \]

As we discussed, we are in particular interested in the case where \( \beta/q < 1 \). In what follows, we are going to show that, under monotonicity assumption on the Markov chain governing \( s \), the optimal policy associated with (87) implies a finite support for the distribution of asset holding of the farmer, \( a \).

Before we start the formal proof, suppose \( s_{\text{min}} = 0 \), and \( \Gamma_{ss_{\text{min}}} > 0 \), for all \( s \in S \). Then, the agent will optimally always choose \( a' > 0 \). Otherwise, there is a strictly positive probability that the agent enters tomorrow into state \( s_{\text{min}} \), where he has no cash in hand \( (a' + s_{\text{min}} = 0) \) and is forced to consume 0, which is extremely painful to him (e.g. when Inada conditions hold for the instantaneous utility). Hence he will raise his asset holding \( a' \) to insure himself against such risk.

If \( s_{\text{min}} > 0 \), then the above argument no longer holds, and it is indeed possible for the farmer to choose zero assets for tomorrow.

Notice that the borrowing constraint \( a' \geq 0 \) is affecting agent’s asset accumulation decisions, even if he is away from the zero bound, because he has an incentive to ensure against the risk of getting a series of bad shocks to \( s \) and is forced to 0 asset holdings. This is what we call precautionary savings motive.

\(^{20}\) This section was prepared by Keyvan Eslami, at the University of Minnesota. This section is essentially a slight variation on the proofs found in 7. However, he accepts the responsibility for the errors.
Next, we are going to prove that the policy function associated with (87), which we denote by \( a'(\cdot) \), is similar to that in Figure 1. We are going to do so, under the following assumption.

**Assumption 1** The Markov chain governing the state \( s \) is monotone; i.e. for any \( s_1, s_2 \in S, s_2 > s_1 \) implies \( E(s|s_2) \geq E(s|s_1) \).

It is straightforward to show that, the value function for Problem (87) is concave in \( a \), and bounded.

Now, we can state our intended result as the following theorem.

**Theorem 4** Under Assumption 1, when \( \beta/q < 1 \), there exists some \( \hat{a} \geq 0 \) so that, for any \( a \in [0, \hat{a}] \), \( a'(s,a) \in [0, \hat{a}] \), for any realization of \( s \).

To prove this theorem, we proceed in the following steps. In all the following lemmas, we will assume that the hypotheses of Theorem 4 hold.
Lemma 1 The policy function for consumption is increasing in $a$ and $s$;

$$c_a(a, s) \geq 0 \text{ and } c_s(a, s) \geq 0.$$ 

Proof 1 By the first order condition, we have:

$$u'(c(s, a)) \geq \frac{\beta}{q} \sum_{s'} \Gamma_{ss'} V_a\left(s', \frac{a + s - c(s, a)}{q}\right),$$

with equality, when $a + s - c(s, a) > 0$.

For the first part of the lemma, suppose $a$ increases, while $c(s, a)$ decreases. Then, by concavity of $u$, the left hand side of the above equation increases. By concavity of the value function, $V$, the right hand side of this equation decreases, which is a contradiction.

For the the second part, we claim that $V_a(s, a)$ is a decreasing function of $s$. To show this is the case, first consider the mapping $T$ as follows:

$$Tv(s, a) = \max_{c, a'} \left\{ u(c) + \beta \sum_{s'} \Gamma_{ss'} v\left(s', a\right) \right\}$$

s.t. $c + qa' = a + s$

$$c \geq 0$$

$$a' \geq 0.$$ 

Suppose $v^n_a(s, a)$ is decreasing in its first argument; i.e. $v^n_a(s_2, a) < v^n_a(s_1, a)$, for all $s_2 > s_1$ and $s_1, s_2 \in S$. We claim that, $v^{n+1} = Tv^n$ inherits the same property. To see why, note that for $a^{n+1}(s, a) = a'$ (where $a^{n+1}$ is the policy function associated with $n$'th iteration) we must have:

$$u'(a + s - qa') \geq \frac{\beta}{q} \sum_{s'} \Gamma_{ss'} v^n_a\left(s', a'\right),$$

with strict equality when $a' > 0$. For a fixed value of $a'$, an increase in $s$ leads to a decrease in both sides of this equality, due to the monotonicity assumption of $\Gamma$, and the assumption on $v^n_a$. As a result,
we must have

\[ u' \left( a + s_2 - qa^{n+1}(s_2, a) \right) \leq u' \left( a + s_1 - qa^{n+1}(s_1, a) \right) , \]

for all \( s_2 > s_1 \). By Envelope theorem, then:

\[ v^{n+1}_a(s, a) \leq v^{n+1}_a(s_1, a) . \]

It is straightforward to show that \( v^n \) converges to the value function \( V \) point-wise. Therefore,

\[ V_a(s_2, a) \leq V_a(s_1, a) , \]

for all \( s_2 > s_1 \).

Now, note that, by envelope theorem:

\[ V_a(s, a) = u'(c(s, a)) . \]

As \( s \) increases, \( V_a(s, a) \) decreases. This implies \( c(s, a) \) must increase.

**Lemma 2** There exists some \( \hat{a} \in \mathbb{R}_+ \), such that \( \forall a \in [0, \hat{a}], a'(a, s_{\min}) = 0 \).

**Proof 2** It is easy to see that, for \( a = 0 \), \( a'(a, s_{\min}) = 0 \). First of all, note the first order condition:

\[ u_c(c(s, a)) \geq \frac{\beta}{q} \sum_{s'} \Gamma_{ss'} u_c(c(s', a'(s, a))) , \]
with equality when \( a' (s, a) > 0 \). Under the assumption that \( \beta / q < 1 \), we have:

\[
uc(c(smin, 0)) = \frac{\beta}{q} \sum_{s'} \Gamma_{smin,s'} uc(c(s', a'(smin, 0))) < \sum_{s'} \Gamma_{ss'} uc(c(s', a'(smin, 0))) .
\]

By Lemma 1, if \( a' = a'(0, smin) > a = 0 \), then \( c(s', a') > c(smin, 0) \) for all \( s' \in S \), which leads to a contradiction.

**Lemma 3** \( a'(smin, a) < a, \) for all \( a > 0 \).

**Proof 3** Suppose not; then \( a'(smin, a) \geq a > 0 \) and as we showed in Lemma 2

\[
uc(c(smin, a)) < \sum_{s'} \Gamma_{ss'} uc(c(s', a'(smin, a))) .
\]

Contradiction, since \( a'(smin, a) \geq a, \) and \( s' \geq smin \), and the policy function in monotone.

**Lemma 4** There exits an upper bound for the agent’s asset holding.

**Proof 4** Suppose not; we have already shown that \( a'(smin, a) \) lies below the 45 degree line. Suppose this is not true for \( a'(smax, a) \); i.e. for all \( a \geq 0 \), \( a'(smax, a) > a \). Consider two cases.

In the first case, suppose the policy functions for \( a'(smax, a) \) and \( a'(smin, a) \) diverge as \( a \to \infty \), so that, for all \( A \in \mathbb{R}_+ \), there exist some \( a \in \mathbb{R}_+ \), such that:

\[
a'(smax, a) - a'(smin, a) \geq A .
\]

Since \( S \) is finite, this implies, for all \( C \in \mathbb{R}_+ \), there exist some \( a \in \mathbb{R}_+ \), so that

\[
c(smin, a) - c(smax, a) \geq C ,
\]

which is a contradiction, since \( c \) is monotone in \( s \).
Next, assume \( a'(s_{\text{max}}, a) \) and \( a'(s_{\text{min}}, a) \) do not diverge as \( a \to \infty \). We claim that, as \( a \to \infty \), \( c \) must grow without bound. This is quite easy to see; note that, by envelope condition:

\[
V_a(s, a) = u'(c(s, a)).
\]

The fact that \( V \) is bounded, then, implies that \( V_a \) must converge to zero as \( a \to \infty \), implying that \( c(s, a) \) must diverge to infinity for all values of \( s \), as \( a \to \infty \). But, this implies, if \( a'(s_{\text{max}}, a) > a \),

\[
u_c(c(s_{\text{max}}, a'(s_{\text{max}}, a))) \to \sum_{s'} \Gamma_{s_{\text{max}}s'} u_c(c(s', a'(s_{\text{max}}, a))).
\]

As a result, for large enough values of \( a \), we may write:

\[
u_c(c(s_{\text{max}}, a)) = \frac{\beta}{q} \sum_{s'} \Gamma_{s_{\text{max}}s'} u_c(c(s', a'(s_{\text{max}}, a)))
\]

\[
< \sum_{s'} \Gamma_{s_{\text{max}}s'} u_c(c(s', a'(s_{\text{max}}, a)))
\]

\[
\approx u_c(c(s_{\text{max}}, a'(s_{\text{max}}, a))).
\]

But, this implies:

\[
c(s_{\text{max}}, a) > c(s_{\text{max}}, a'(s_{\text{max}}, a)),
\]

which, by monotonicity of policy function, means \( a > a'(s_{\text{max}}, a) \), and this is a contradiction.